

JUNE 18-22, 2023

CVPR



VANCOUVER, CANADA

Temporal Interpolation Is All You Need for Dynamic Neural Radiance Field

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TUE-PM-008

Problem

Neural Radiance Field (NeRF) of Dynamic Scenes



Input Sequence



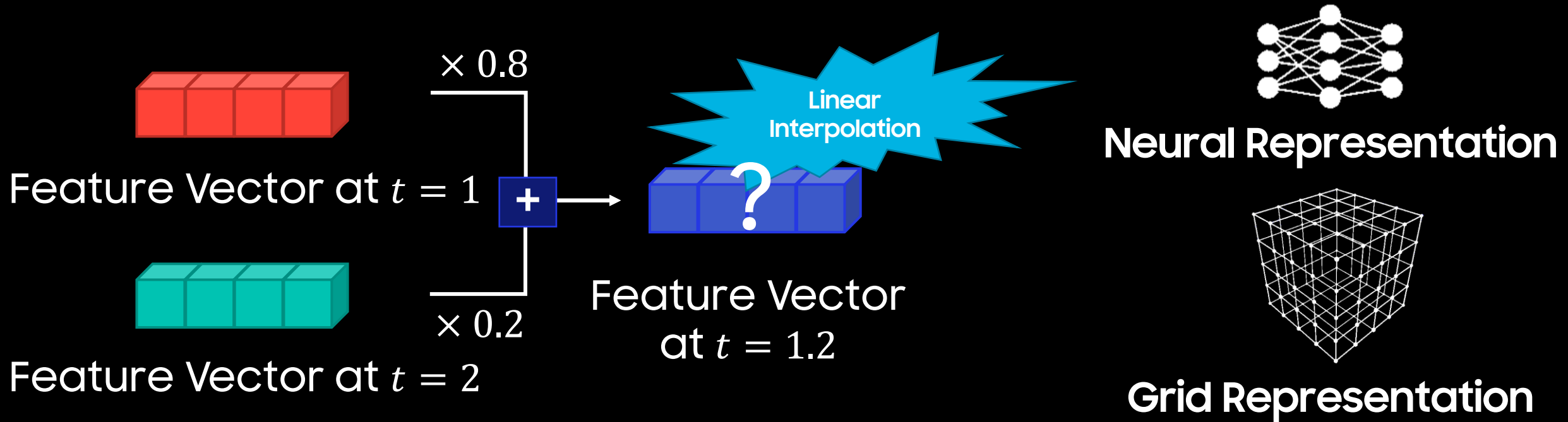
Dynamic
NeRF



Space-Time
View Synthesis

Key Idea

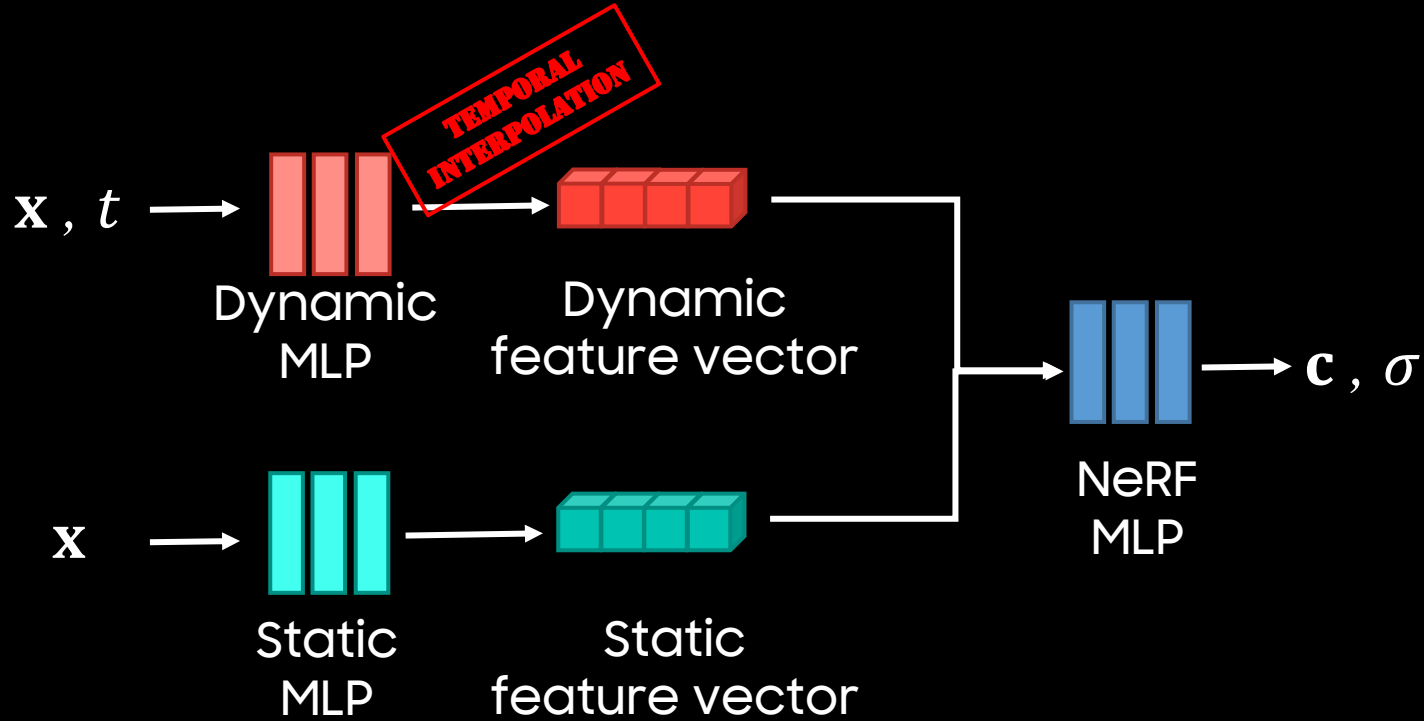
Temporal Interpolation



01 | Overview

Neural Representation

Extract static and dynamic features via neural nets

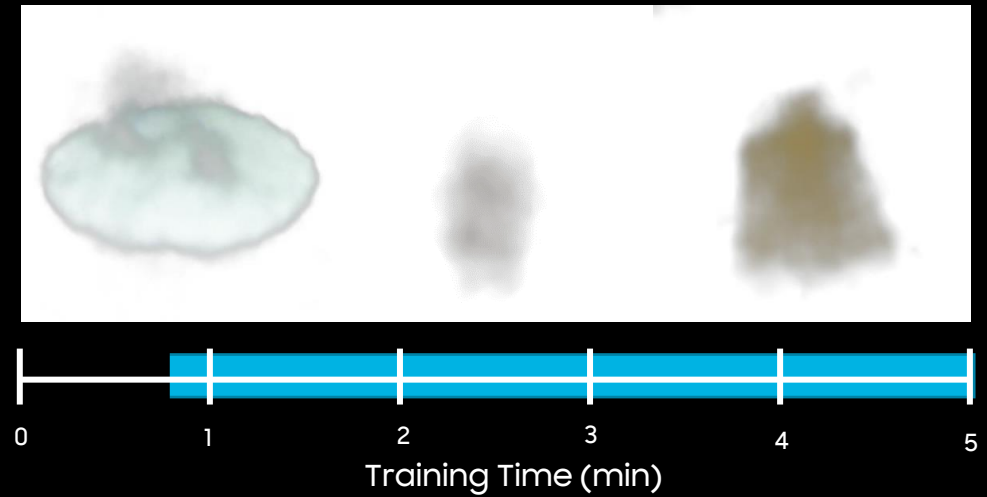
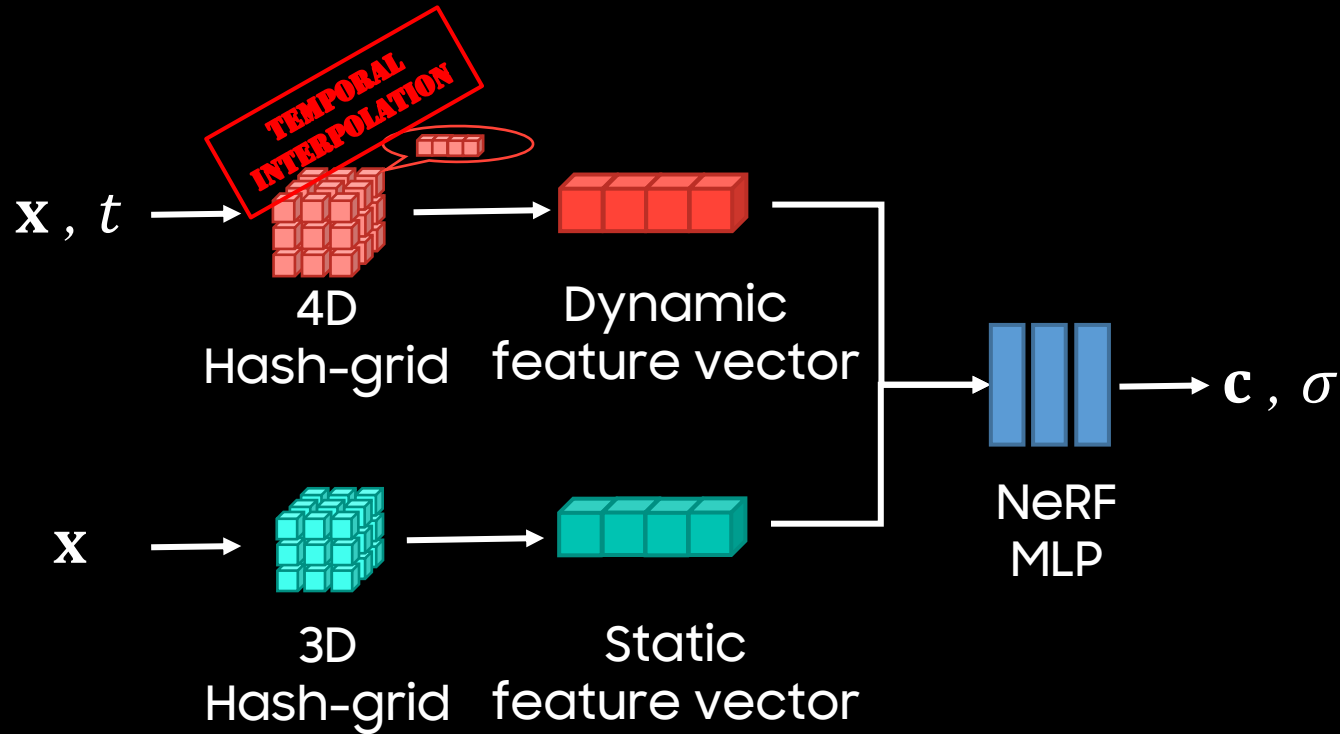


High-quality dynamic NeRF

01 | Overview

Grid Representation

Extract static and dynamic features via **hash grids** from InstantNGP



Fast-trained dynamic NeRF

Project Page

<https://sungheonpark.github.io/tempinterpnerf>



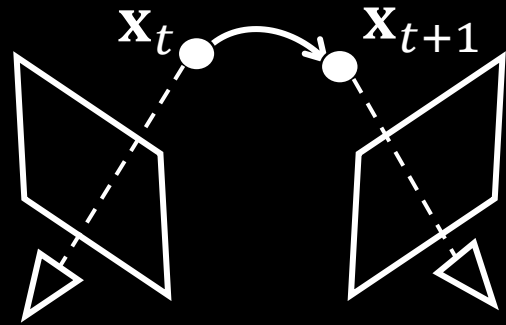
Poster session (JUN 20)
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02 | Previous Works

Dynamic NeRF

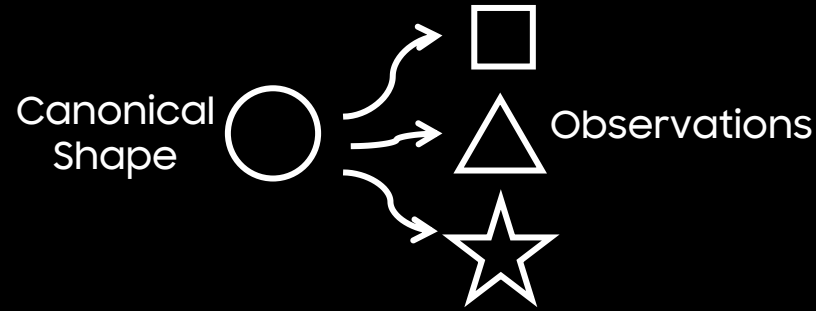
How to relate 3D points across frames?

3D Scene Flow



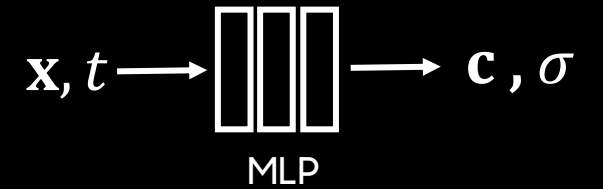
Neural Scene Flow Fields (CVPR 2021)

3D Warping



D-NeRF (CVPR 2021)
Nerfies (ICCV 2021)
HyperNeRF (SIGA 2021)
Non-rigid NeRF (ICCV 2021)

Direct Estimation



Neural 3D Video Synthesis from Multi-view Video
CVPR 2022

Tianye Li^{1,3,*}, Mira Slavcheva^{1,*}, Michael Zollhoefer¹,
Simon Green¹, Christoph Lassner¹, Changil Kim², Tanner Schmidt¹,
Steven Lovegrove¹, Michael Goesele¹, Richard Newcombe¹, Zhaoyang Lv¹

* equal contributions

¹ REALITY LABS RESEARCH ² Meta ³ THE UNIVERSITY OF SOUTHERN CALIFORNIA

(with audio)

DyNeRF (CVPR 2022)

Dynamic NeRF

Keep it SIMPLE!

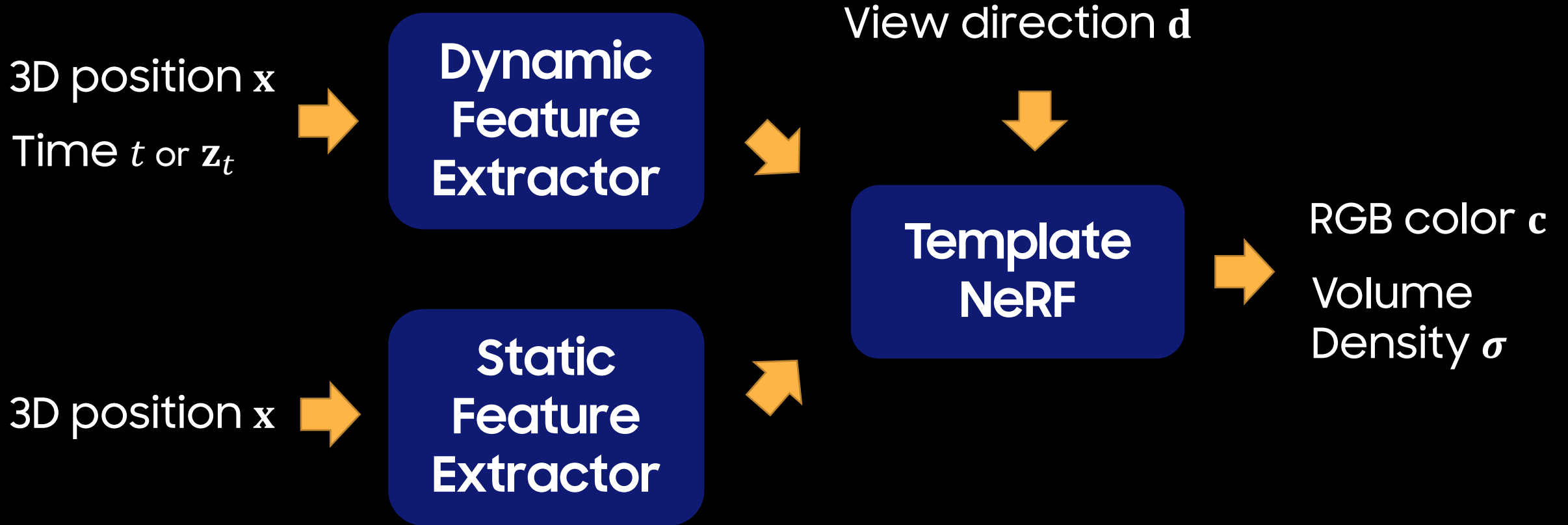
No Scene Flow estimation module

No warping estimation module

Let the neural networks (or feature grids) learn meaningful representations



Temporal Interpolation + Smoothness Term



04 | Method

Neural representation

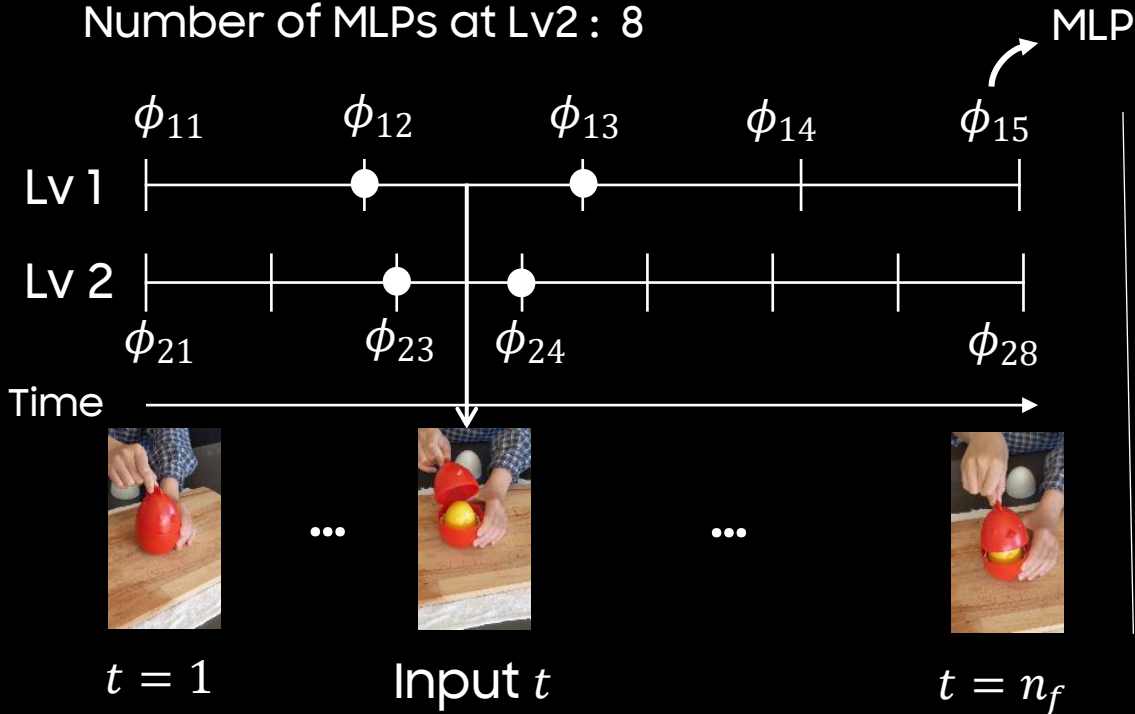
Extract static and dynamic features via neural nets

Structure of feature extractor

Levels : 2


Number of MLPs at Lv1 : 5

Number of MLPs at Lv2 : 8

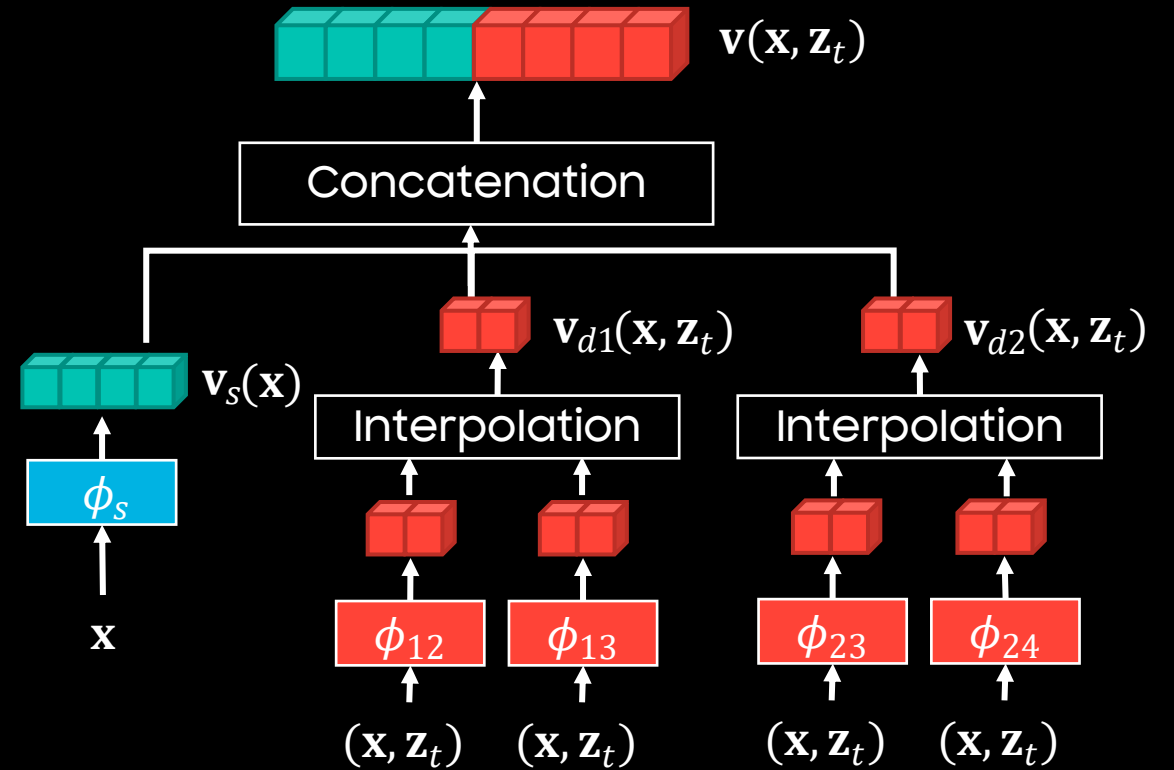


Grid representation

 : Static feature vector

 : Dynamic feature vector

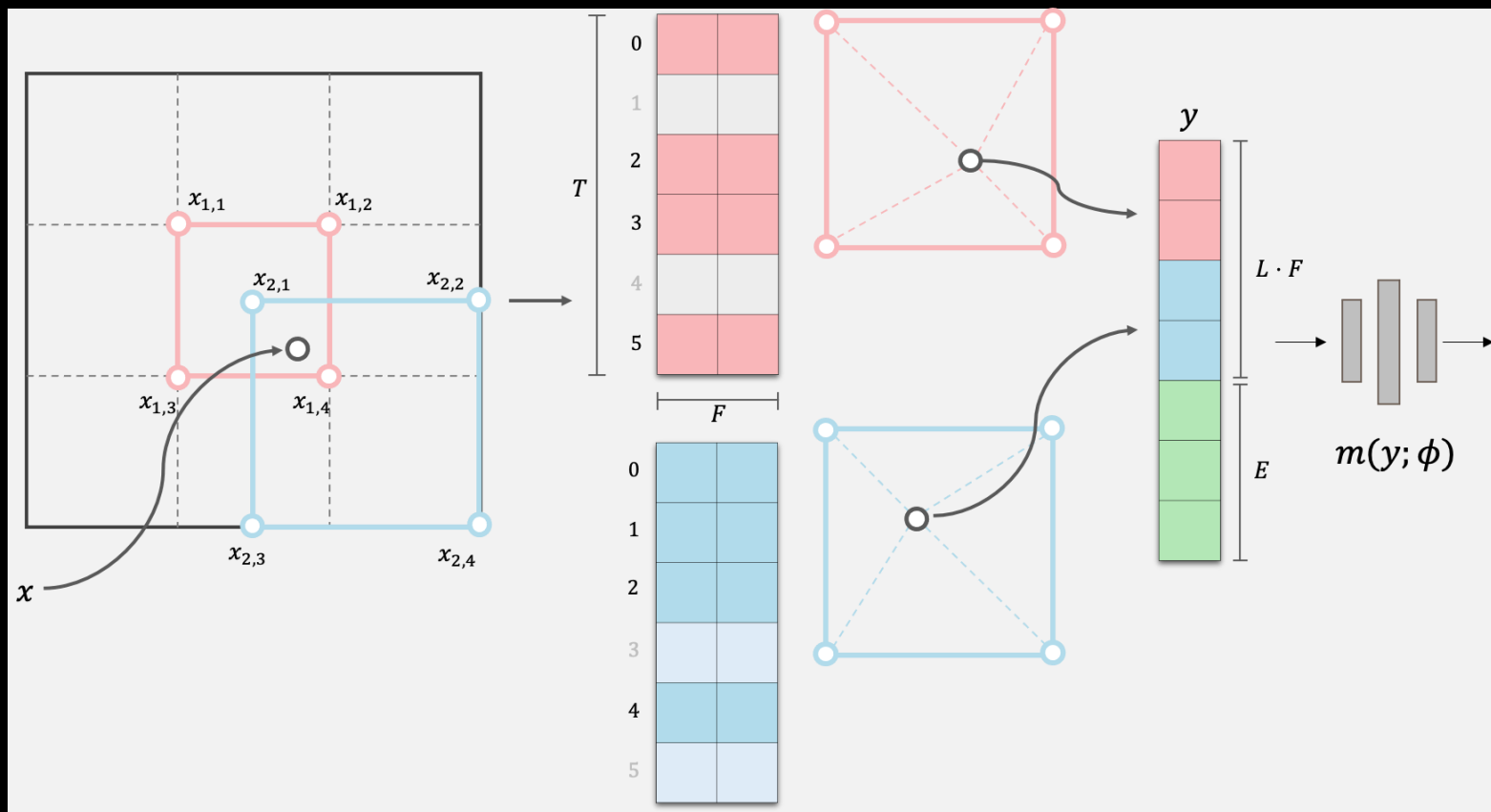
Feature extraction



Neural representation

Grid representation


Use static and dynamic features via Hashgrids

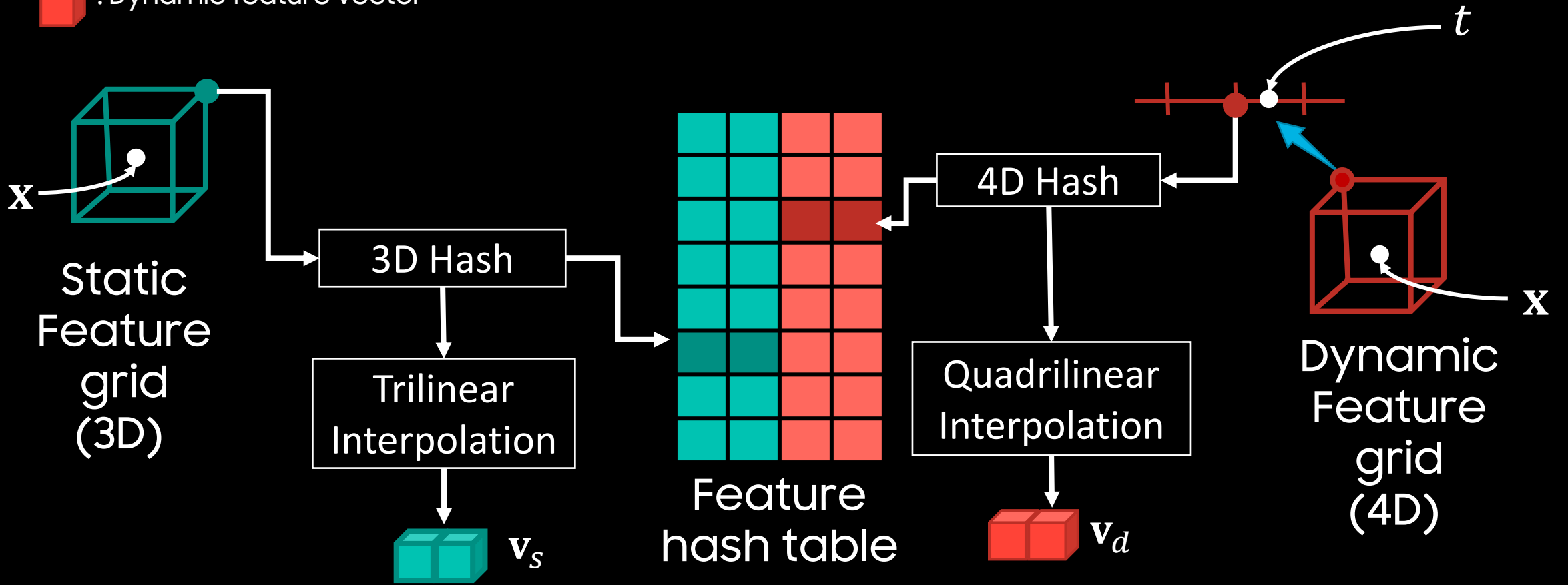


Multi-resolution Hash Grid from InstantNGP (SIGGRAPH 2022)

04 | Method

 : Static feature vector

 : Dynamic feature vector



Grid representation

Use static and dynamic features via Hashgrids

04 | Method

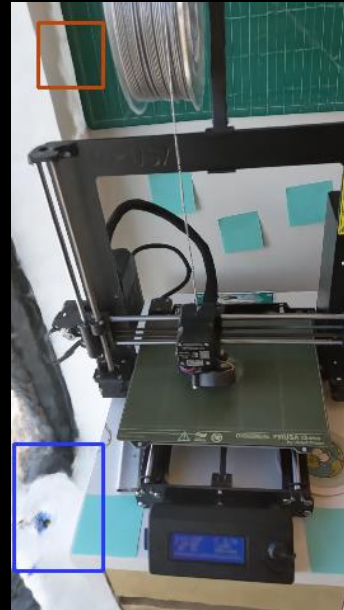
Smoothness Term

Simple assumption for partially observable points

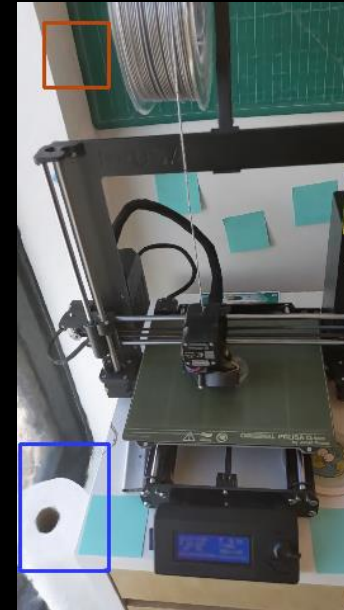
- Regularization between two adjacent time frames
- Unobserved regions remain static

$$\|v_d(\mathbf{x}, \mathbf{z}_t) - v_d(\mathbf{x}, \mathbf{z}_{t+1})\|_2$$

Smoothness on the
FEATURE SPACE!



w/o Smooth



w/ Smooth

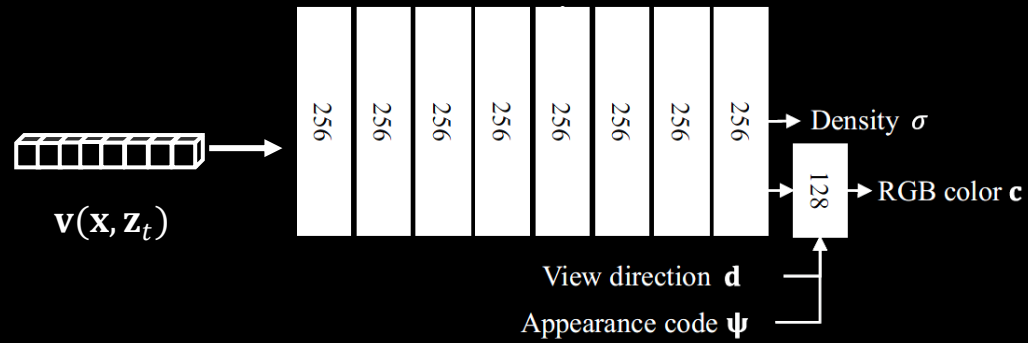


GT

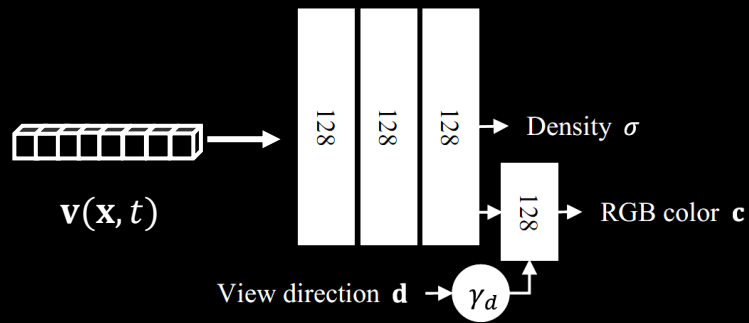
04 | Method

Template NeRF

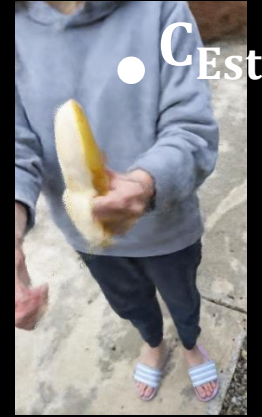
Neural Representation: Based on HyperNeRF



Grid Representation: Based on InstantNGP



Loss function



Rendered Image

GT

$$L_{rgb} = \|\mathbf{C}_{Est} - \mathbf{C}_{GT}\|^2$$

$$L_{smooth} = \|v_d(\mathbf{x}, z_t) - v_d(\mathbf{x}, z_{t+1})\|_2$$

$$L = L_{rgb} + \lambda L_{smooth}$$

Experimental Results

05 | Results

Neural Representation

D-NeRF Dataset

Method	PSNR \uparrow	SSIM \uparrow	LPIPS \downarrow	AVG \downarrow
D-NeRF	30.43	0.95	0.07	0.02
TiNeuVox-B	<u>32.67</u>	<u>0.971</u>	0.041	<u>0.016</u>
Ours-NN (w/o smooth)	30.18	0.963	<u>0.038</u>	0.019
Ours-NN (w/ smooth)	32.73	0.974	0.033	0.014



05 | Results

Neural Representation

HyperNeRF Dataset

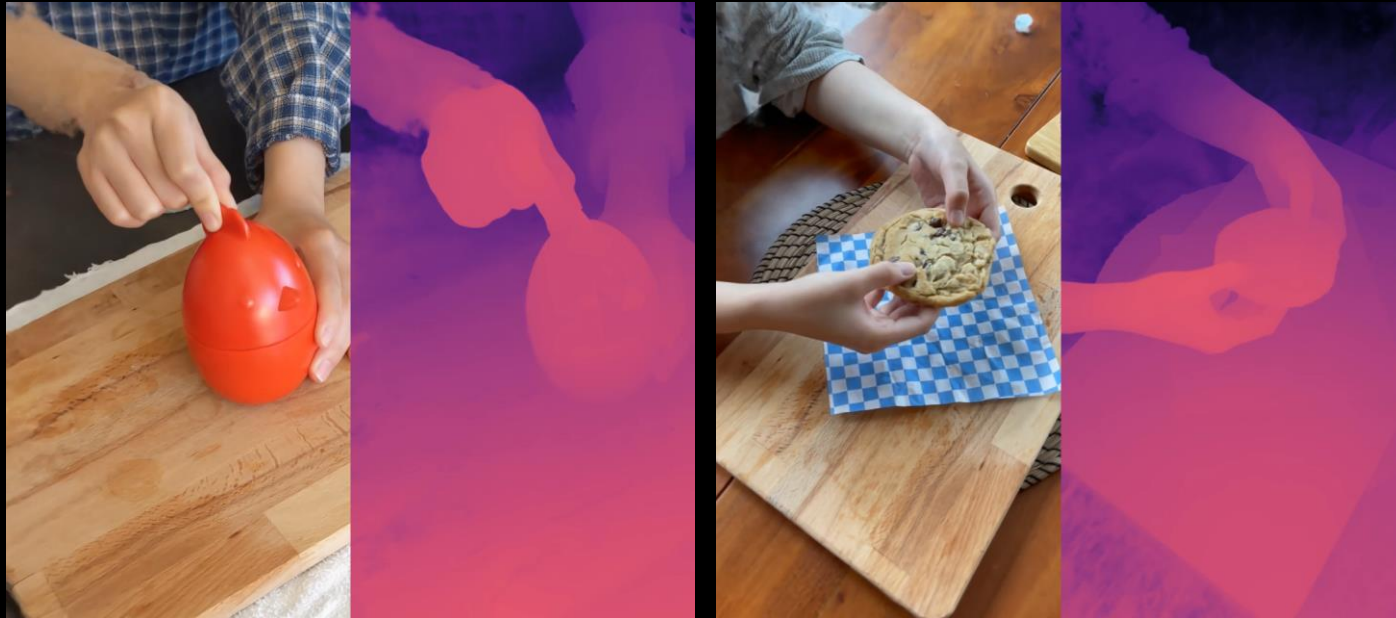
DyNeRF Dataset

Method	vrig		interp	
	PSNR ↑	MS-SSIM ↑	PSNR ↑	MS-SSIM ↑
NSFF	26.33	0.916	25.80	0.883
Nerfies	22.23	0.803	28.47	0.939
HyperNeRF	22.38	0.814	29.00	0.945
Ours-NN	<u>24.35</u>	<u>0.867</u>	<u>28.67</u>	<u>0.940</u>

Method	PSNR ↑
NV	22.8
LLFF	23.24
DyNeRF	<u>29.58</u>
Ours-NN	29.88

05 | Results

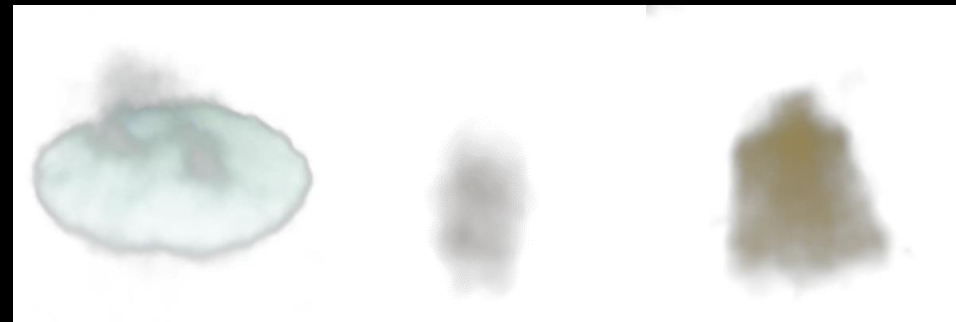
Neural Representation



Grid Representation

D-NeRF Dataset

Method	Train time	PSNR \uparrow	SSIM \uparrow	LPIPS \downarrow	AVG \downarrow
NDVG-half	23min	27.15	0.857	0.048	0.033
TiNeuVox-S	8min	30.75	0.956	0.067	0.023
Ours-grid	1min	26.77	0.933	0.107	0.039
Ours-grid	5min	29.73	<u>0.961</u>	0.063	0.024
Ours-grid	8min	<u>29.84</u>	0.962	<u>0.062</u>	0.023



05 | Results

Grid Representation

D-NeRF Dataset

TinueVox-S

Ours-grid



Conclusion

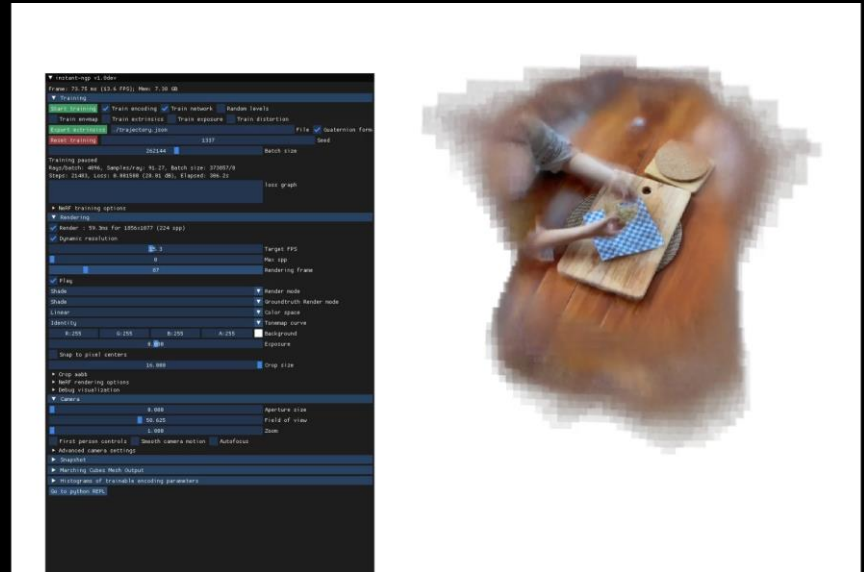
✓ A simple yet powerful feature representation for dynamic NeRF

Neural representation



- Good quality
- Small-sized models
- Hours of training

Grid representation



- Fast training
- Real-time applications

Thank you

Join us at the Poster session!

Project Page

<https://sungheonpark.github.io/tempinterpnerf>



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