Improving Zero-shot Generalization and Robustness of Multi-modal Models



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Motivation: Multi-modal Models (Vision-Language Models)

1. CLIP_[1] has high zero-shot accuracy and more robustness to distribution shifts.



[1] Radford, Alec, et al. "Learning transferable visual models from natural language supervision." International conference on machine learning. PMLR, 2021.



Finding 1: Multi-modal Models are sensitive to prompts

| Caltech101 | Prompt | Accuracy | Flowers102 | Prompt | Accuracy |
|---------------------------|--|-------------------------|------------|--|--------------------------------|
| | a [CLASS]. | 82.68 | | a photo of a [CLASS]. | 60.86 |
| | a photo of [CLASS]. | 80.81 | | a flower photo of a [CLASS]. | 65.81 |
| | a photo of a [CLASS]. | 86.29 | | a photo of a [CLASS], a type of flower. | 66.14 |
| | $[V]_1[V]_2 \dots [V]_M$ [CLASS]. | 91.83 | | [V] ₁ [V] ₂ [V] _M [CLASS]. | 94.51 |
| (a) | | | | (b) | |
| Describable Textures (DTI | D) Prompt | Accuracy | EuroSAT | Prompt | Accuracy |
| 0,000 | a photo of a [CLASS]. | 39.83 | Self-S | a photo of a [CLASS]. | 24.17 |
| | | 40.05 | | | |
| 0 | a photo of a [CLASS] texture. | 40.25 | | a satellite photo of [CLASS]. | 37.46 |
| | a photo of a [CLASS] texture. [CLASS] texture. | 40.25 | | a satellite photo of [CLASS]. a centered satellite photo of [CLASS]. | 37.46 37.56 |
| | a photo of a [CLASS] texture. [CLASS] texture. [V] ₁ [V] ₂ [V] _M [CLASS]. | 40.25 42.32 63.58 | 2 | a satellite photo of [CLASS]. a centered satellite photo of [CLASS]. [V] ₁ [V] ₂ [V] _M [CLASS]. | 37.46 37.56 83.53 |

Zhou, Kaiyang, Jingkang Yang, Chen Change Loy, and Ziwei Liu. "Learning to prompt for vision-language models." *International Journal of Computer Vision* 130, no. 9 (2022): 2337-2348.

However, they are sensitive to prompts. Different prompts lead to different performances.

Step 1: Uncertainty Estimation



Our first goal is to estimate the model's uncertainty, which allows the model to say "I do not know", when it has low confidence. Our intuition is: a high-confidence prediction should be agnostic to different prompts.

Step 1: Uncertainty Estimation



In other words, we estimate model uncertainty by measuring the self-consistency when applying different class-agnostic text prompts.

Failure mode 1: Class name does not specify super-class name



Ground Truth: Tusker Misclassified as: Asian elephant Parent: Elephant

96% of images with ground truth label "tusker" are wrongly classified as other elephant classes such as "Asian elephant". Concatenating the parent class name "elephant" fixes such errors. Failure mode 2: Class name does not specify sub-class name



Ground Truth: Balloon Misclassified as: Airship Child: Hot-air Balloon

Words like "balloon" are too broad and include different subtypes. Hot-air balloon images belonging to the "balloon" class are misclassified as "airship". Using child class name "hot-air balloon" fixes such errors.

Failure mode 3: Inconsistent naming between class names



Ground Truth: Screw Misclassified as: Metal Nail Child: Allen Screw

91% images from "screw" class are misclassified as "metal nail". "Metal nail" has the word "metal" in description, but "screw" does not. Using child class names for "screw" (e.g. "Allen screw") fixes such errors.

We also conduct failure case analysis. Most of the errors are due to the class name lacks information from WordNet

Step 2: Top-down and bottom-up label augmentation using WordNet hierarchy



So we augment the original class name to borrow the WordNet hierarchy knowledge during decision. Our method hyperparameter-free, requires no additional model training and can be easily scaled to other models.

Background: Multi-modal Models (Vision-Language Models)

Training with large scale (easy to access) image-text pairs



Shared Vision and language embedding

Some background of CLIP: it is trained using large-scale image-text pairs with contrastive loss. The images go through the image end ler, and the text goes through the text encoder. If they are from the same pair, their distance should be small; otherwise, they should have a large distance. CLIP created a shared vision and language embedding.

Background: Multi-modal Models

Create dataset classifier from label text plane car a photo of Text dog Encoder a {obiect}. bird Use for zero-shot prediction T_1 T_2 T_3 T_N Image $I_1 \cdot T_1 \quad I_1 \cdot T_2 \quad I_1 \cdot T_3$ $I_1 \cdot T_N$ Encoder a photo of a dog. logit = cos(zimg, ztext)

F00D101

guacamole (90.1%) Ranked 1 out of 101 labels



During zero-shot inference, given a test image and candidate class names, they will compare the cosine similarity of the image email and all candidate class embedding in the shared latent space, and select the class name with the largest cosine similarity as prediction. On some dataset, they perform well, while in some dataset that requires domain expert knowledge, like medical image, they may make mistakes.

Step 1: Uncertainty Estimation



To estimate uncertainty, given a test image, we made multiple times decisions by applying different class-agnostic nots to the candidate classes. For instance, "a good image of, a bad image of...". We calculate the decision consistency as the confidence score. The intuition is, if the decision is not influenced by different prompts, it has high confidence.

Result 1: Our proposed confidence score is better suited for selective prediction than baselines

Goal:

high confidence \rightarrow correct low confidence \rightarrow wrong

Baseline:

Max Logits: set threshold of the max logit

max_{K classes} logit_k

| F00D101 | | |
|--------------------------|---|--|
| guacamole (90.1%) Rank | xed 1 out of 101 labels | |
| | ✓ a photo of guacamole, a type of food. | |
| | × a photo of ceviche , a type of food. | |
| | × a photo of edamame , a type of food. | |
| | × a photo of tuna tartare , a type of food. | |
| | × a photo of hummus , a type of food. | |
| YOUTUBE-BB | | |
| airplane, person (89.0%) | Ranked I out of 23 | |
| | ✓ a photo of a airplane. | |
| | × a photo of a bird . | |
| | × a photo of a bear . | |
| - Je - | × a photo of a giraffe . | |
| | × a photo of a car . | |
| PATCHCAMELYON (PCAM) | | |
| healthy lymph node tissu | ue (22.8%) Ranked 2 out of 2 | |
| Serie / | × this is a photo of lymph node tumor tissue | |
| A | ✓ this is a photo of healthy lymph node tissue | |
| Call . | | |
| 1 1 | | |
| | | |

For evaluation, a good confidence score is a signal of the correctness of model prediction: the prediction with high confidence score is correct, and the prediction with a low confidence score is wrong. One baseline is Max Logits, which uses a fixed threshold to estimate confidence.

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Goal:

high confidence \rightarrow correct low confidence \rightarrow wrong

Baseline:

Max Logits: set threshold of the max logit max_{K classes} logit_k



We can compute the AUC score, where we use the confidence score to predict the correctness of the model prediction. Our self-consistency confidence score (orange curve) is better suited for vision-language models.

Result 1: Our proposed confidence score is better suited for selective prediction than baselines

Goal: High accuracy on the high confidence set.



We also evaluate Selective prediction, where we give the model a rejection budget to say "I do not know" on the low confident decision, and we only calculate the accuracy of the high confidence set. Ours performs better on both CLIP and LiT models.

Step 1: Uncertainty Estimation



With uncertainty estimation, we allow the model to say "I do not know" on low confidence set. What if we still want the model to make a decision even though the confidence is low? How to improve the performance on the low confidence set?

Failure mode 1: Class name does not specify super-class name



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91% images from "screw" class are misclassified as "metal nail". "Metal nail" has the word "metal" in description, but "screw" does not. Using child class names for "screw" (e.g. "Allen screw") fixes such errors.

While the top-5 zero-shot accuracies of these models are very high, the top-1 accuracies are much lower (over a 25% pir) some cases). We conduct failure case analysis. For instance, we find most of the tuskers are wrongly classified as Asian elephants by CLIP. But if we explicitly concatenate the parent class name "elephant" to "tusker" as a prompt, the error is fixed.

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Most of the balloon are wrongly classified as "airship". But if we check the image, we find actually they are hot-air bar, n. class names like "balloon" are too broad and include different subtypes. Using the child class name "hot-air balloon" fixes such errors.

Failure mode 1: Class name does not specify super-class name



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96% of images with ground truth label "tusker" are wrongly classified as other elephant classes such as "Asian elephant". Concatenating the parent class name "elephant" fixes such errors. Failure mode 2: Class name does not specify sub-class name



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Most of the errors are due to the class name itself may not align well with the image meaning. In other words, class name itself may not align well with the image meaning. In other words, class name itself may not align well with the image meaning.

Step 2: Top-down and bottom-up label augmentation using WordNet hierarchy



To improve accuracy on low confident set. We re-rank the top-5, and augment the original class name with top-down of bottom-up label augmentation to borrow the wordnet hierarchy knowledge during zero-shot inference.

Step 2: Top-down and bottom-up label augmentation using WordNet hierarchy



Given top-5 prediction, we first use top-down WordNet hierarchy to concatenate the ancestor names to prompts: for i tance: "husky, dog" "tusker elephant", which provide context information. Then we use a bottom-up hierarchy to add the crmeen's classes to the candidate class. In the decision, we re-rank the top-5 class based on the highest cosine similarity in each class group after augmentation.

Result 2: Using hierarchy to help improve zero-shot accuracy on low confidence subset

Table 1. CLIP (ViT-B/16) and LiT (ViT-B/32) zero-shot top-1 accuracy comparison between baseline and ours (w/ hierarchy).

| | | CLIP | (Ours) Hierarchy-CLIP | LiT | (Ours) Hierarchy-LiT |
|----------------------|---------------|--------|-----------------------|--------|----------------------|
| ImageNet | Low conf. set | 21.58% | 38.71% | 31.18% | 37.25% |
| | Full set | 64.18% | 67.78% | 68.26% | 69.41% |
| ImageNet-v2 | Low conf. set | 17.77% | 32.50 % | 27.08% | 31.45% |
| | Full set | 58.06% | 61.07 % | 60.11% | 61.11% |
| ImageNet-R | Low conf. set | 16.79% | 27.91% | 21.82% | 22.93% |
| | Full set | 56.88% | 59.46% | 66.54% | 66.75% |
| ImageNet-Adversarial | Low conf. set | 10.13% | 18.44% | 7.19% | 8.95% |
| | Full set | 26.12% | 29.23% | 13.93% | 14.56% |
| ImageNet-Sketch | Low conf set | 13.74% | 23.18% | 21.51% | 24.42 <i>%</i> |
| | Full set | 44.71% | 47.28% | 52.47% | 53.17 <i>%</i> |

We conduct zero-shot classification on ImageNet and its variant with both CLIP and LiT models. We find our methom significantly improves the accuracy on the low confidence set (over 17 percent point improvement), and overall also improves the whole ImageNet performance (3.6 percent point improvement).

Result 2: Using hierarchy to help improve zero-shot accuracy on low confidence subset

Table 2. Generalizability to non-ImageNet datasets (CLIP (ViT-B/16) zero-shot top-1 accuracy).

| Dataset | orig (low) | ours (low) | orig (full) | ours (full) |
|------------------|------------|----------------|-------------|---------------|
| Caltech-101 [15] | 10.6 % | 27.2% (+16.6%) | 74.1% | 77.1% (+3.0%) |
| Flower102 [17] | 20.0% | 29.4% (+9.4%) | 63.7% | 65.3% (+1.6%) |
| Food-101 [2] | 28.2% | 49.0% (+20.8%) | 84.7% | 86.8% (+2.1%) |
| Cifar-100 [13] | 9.4% | 17.5% (+8.1%) | 31.8% | 35.2% (+3.4%) |

Results 3: Our hierarchy-based label augmentation is complementary to prompt ensembling

Table 2. CLIP (ViT-B-16) zero-shot top-1 accuracy comparison with prompt ensemble.

| | | Ensemble only | Hierarchy and Ensemble |
|----------------------|---------------|----------------|------------------------|
| ImageNet | Low conf. set | 41.05% | 42.09% |
| | Full set | 68.48% | 68.86% |
| ImageNet-v2 | Low conf. set | 36.39 <i>%</i> | 36.34% |
| | Full set | 62.02 <i>%</i> | 62.00% |
| ImageNet-R | Low conf. set | 35.13% | 36.12% |
| | Full set | 60.21% | 60.62% |
| ImageNet-Adversarial | Low conf. set | 21.13% | 22.00% |
| | Full set | 30.59% | 31.07% |
| ImageNet-Sketch | Low conf. set | 27.13 <i>%</i> | 26.56% |
| | Full set | 48.52 <i>%</i> | 48.26% |

Our hierarchy-based label augmentation is complementary to prompt ensembling.



Results 4: Ablation Study

Generalizability to other

backbones

Table 3. Generalizability to different backbones with CLIP.

backbone ResNet-50 ResNet-101 ViT-B/32 ViT-B/16 ViT-1/14 ACC (low) +14.25% +12.97% +15.12% + 17.13% +18.89% +3.73%+3.71%+3.60%+3.23%ACC (full) +3.65%

Table 5. Effect of threshold of confidence score on zero-shot accuracy.

Effect of threshold of confidence score on zero-shot accuracy.

| Threshold | Low conf. set size | Acc on low conf. set | Acc on full set |
|-----------|--------------------|----------------------|-----------------|
| 0.47 | 10000 | 19.40% | 68.72% |
| 0.52 | 11000 | 20.82% | 68.78% |
| 0.57 | 12000 | 22.06% | 68.82% |
| 0.62 | 13000 | 23.58% | 68.85% |
| 0.66 | 14000 | 25.01% | 68.88% |
| 0.70 | 15000 | 26.51% | 68.86% |

We also show the generalization to other backbones and ablation studies.

Conclusion



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- [Confidence Estimation] We propose a simple yet efficient zero-shot confidence score that is better suited for multi-modal models, based on predictions' self-consistency under different text prompts and image perturbations.
- [Failure Case Analysis] We identified several failure modes for zero-shot ImageNet classification using multi-modal models.
- [Improve Top-1 accuracy with Hierarchy] We develop a label augmentation technique that uses both ancestor and children labels from WordNet. By applying the label augmentation to the previously identified low confidence subset of images, we significantly improve their prediction accuracy
- Our method is hyperparameter-free, requires no additional model training and can be easily scaled to other models.