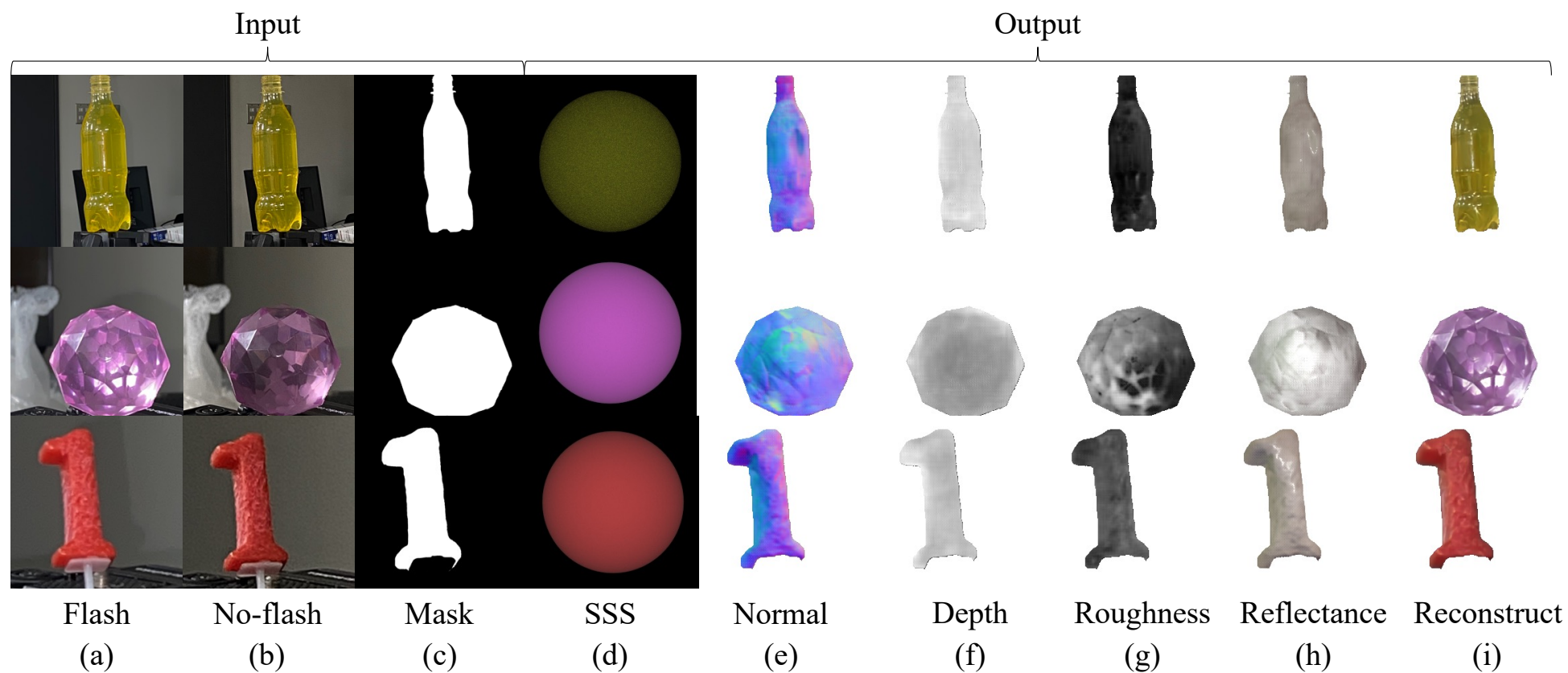




Inverse Rendering of Translucent Objects using Physical and Neural Renderers

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Quick Preview



Translucent objects

Surface



Volume



Surface or Volume?

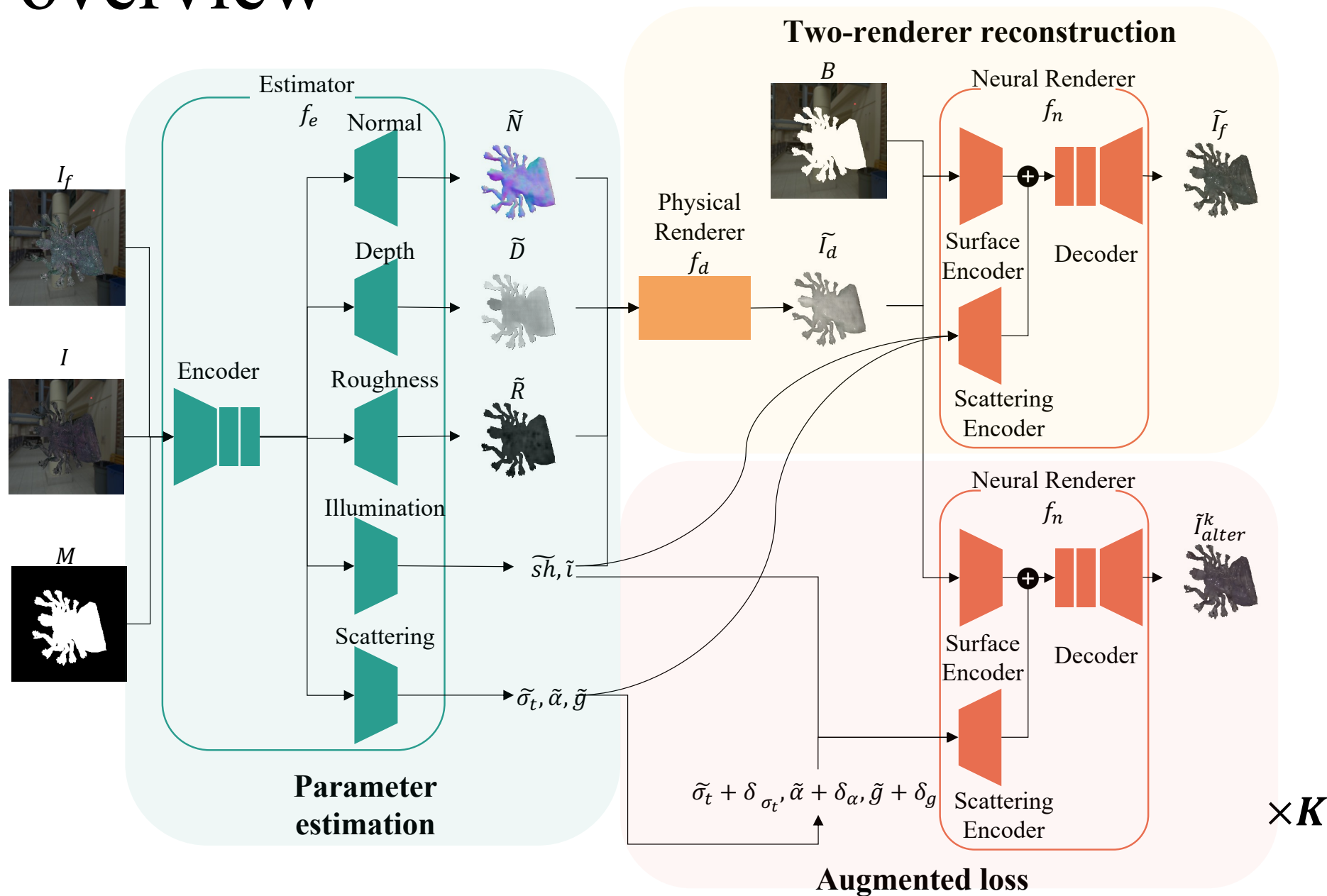


Existing inverse rendering works.

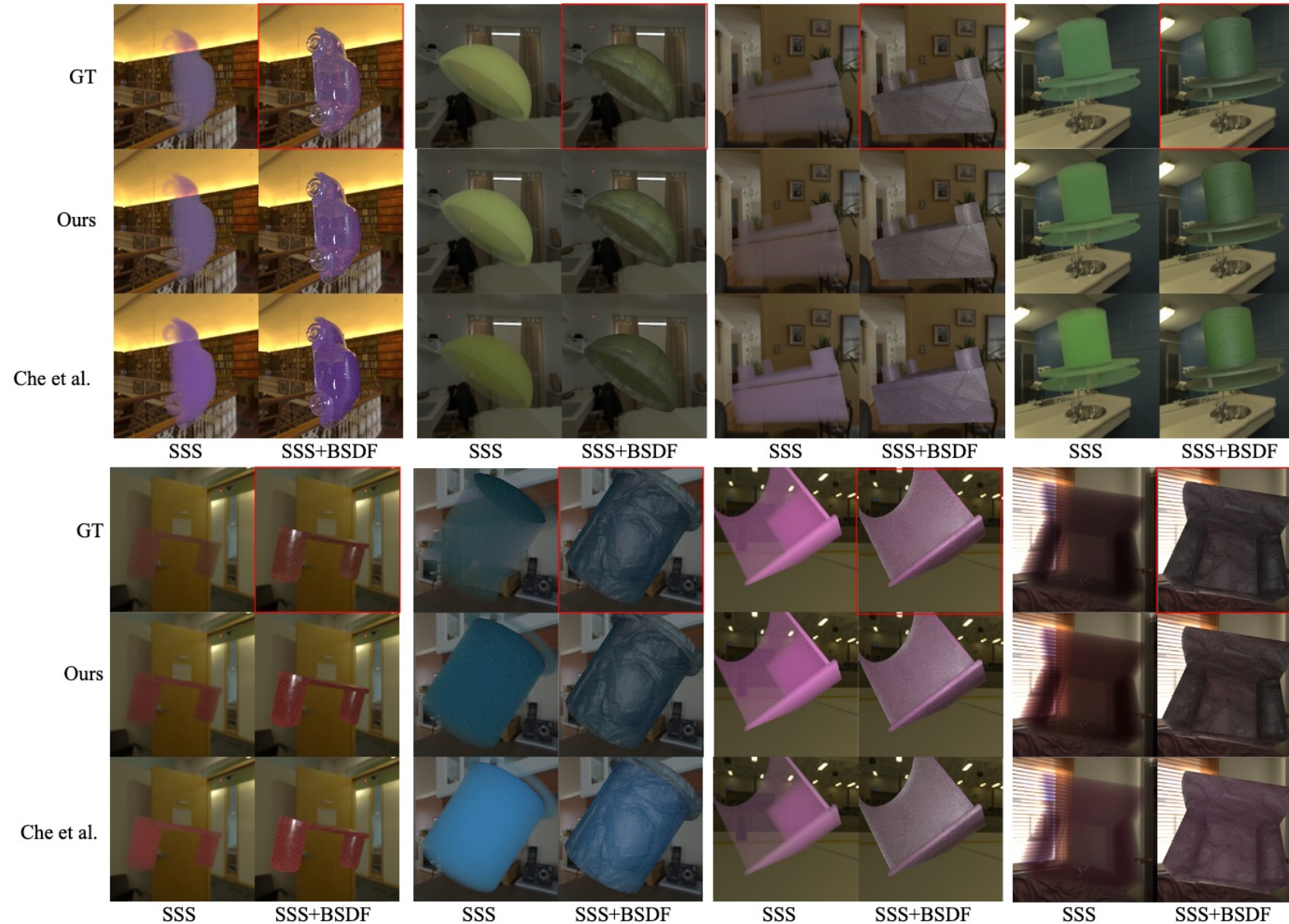
Our target objects



Model overview



Qualitative results



Re-rendered images using estimated SSS parameters.



Quantitative results

Table 1. MAE results on 17140 test scenes. For each element we report mean(std) value. The scale of mean is 1×10^0 , and std is 1×10^{-3} .

	Geometry		BSDF	Illumination			SSS	
	N	D	R	sh	i	σ_t	α	g
Baseline	.0918(.4395)	.0705(.4443)	.0811(.5303)	.1083(.6571)	.0912(1.042)	.1670(.7904)	.1061(.5792)	.1762(.8811)
2R	.0916(.3009)	.0697(.3617)	.0811(.4903)	.1064(.8984)	.0908(.7697)	.1675(1.072)	.1057(.4191)	.1777(2.562)
2R-AUG	.0913(.1768)	.0699(1.271)	.0807(.2714)	.1105(8.926)	.0893(1.151)	.1619(.9635)	.1040(.1578)	.1703(.8856)
Che <i>et al.</i> [11]	-	-	-	-	-	.1828	.1115	.2123
Full model	.0894 (.1532)	.0646 (.3283)	.0769 (.2659)	.0989 (1.017)	.0804 (1.736)	.1590 (.2286)	.1002 (.5185)	.1655 (.3932)

Baseline: Re-renderer the image only using a neural network

2R: Use a physically-based renderer and a neural renderer

2R-AUG: Use two renderers and Augment loss

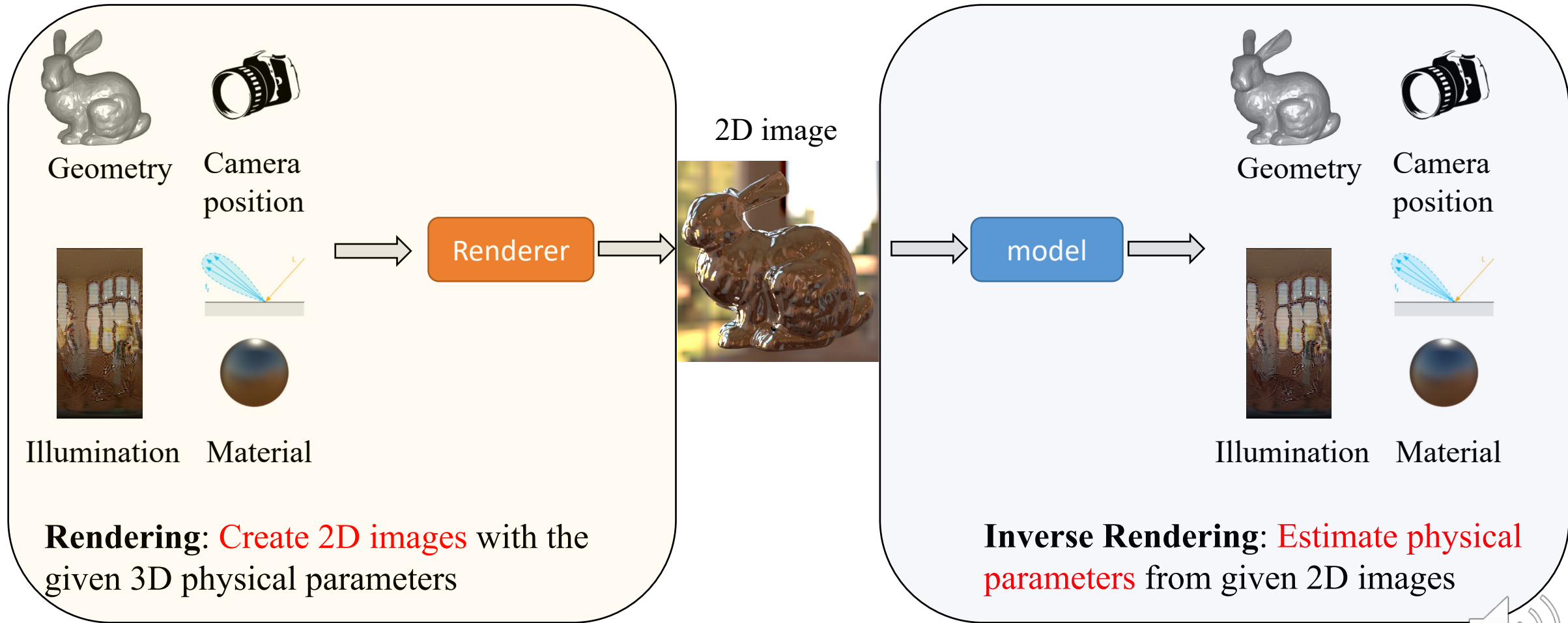
Full model: add two-shot to 2R-AUG



Details



Rendering & Inverse Rendering

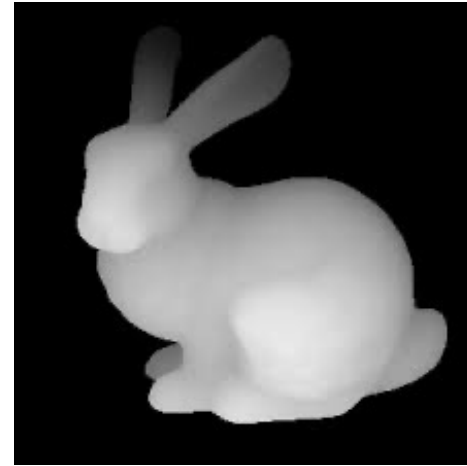


Geometry

Fine



Coarse



Surface normal

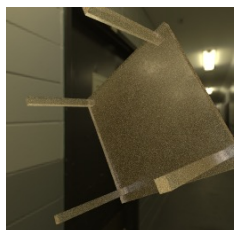
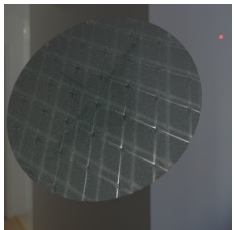
Depth

This work

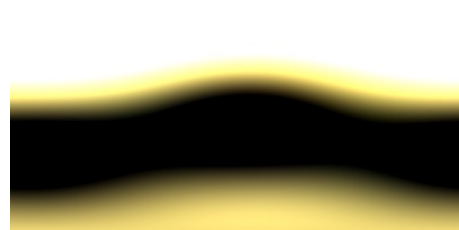
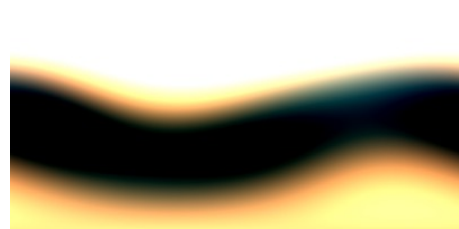
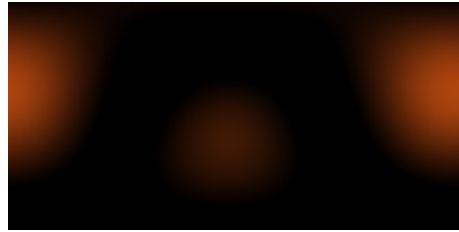


Illumination

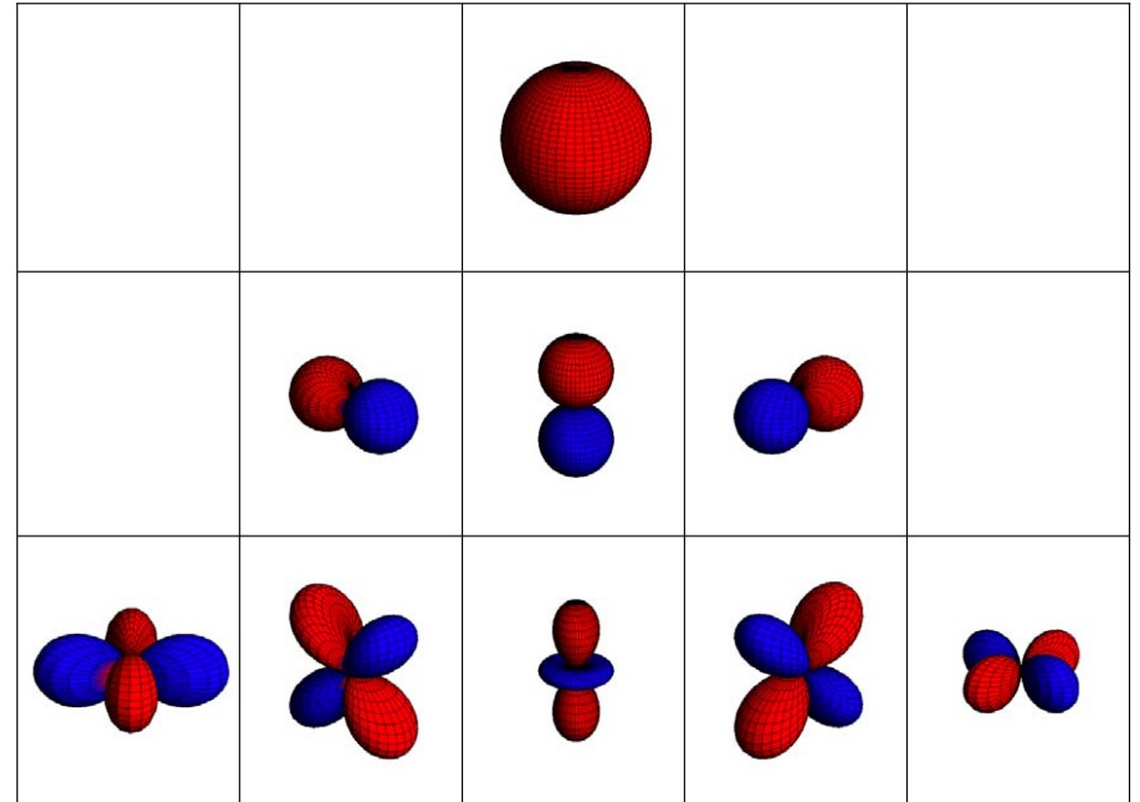
Scene



Spherical harmonics illumination



Spherical harmonics basis



• <http://www.ppsloan.org/publications/StupidSH36.pdf>

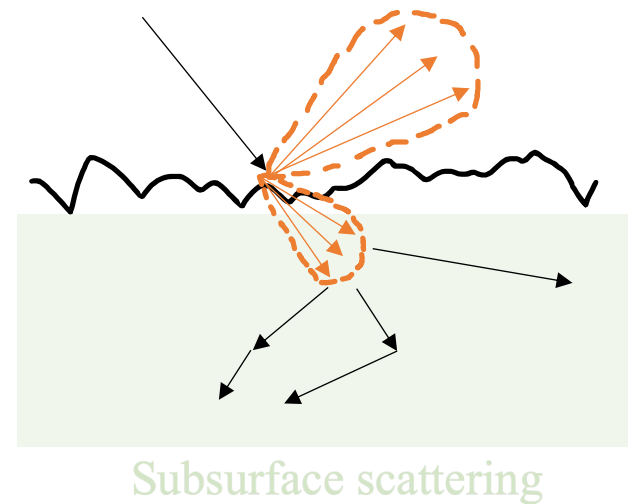


Material

Translucent objects



Our material model



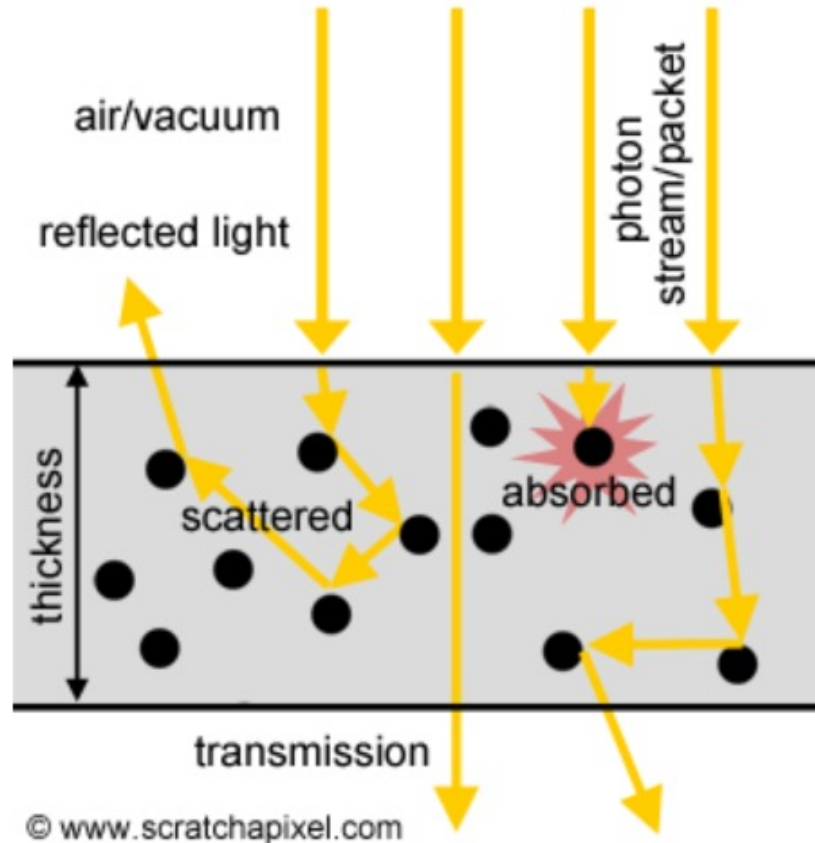
Spatially-varying
dielectric BSDF

Homogeneous
Subsurface scattering
(RTE)

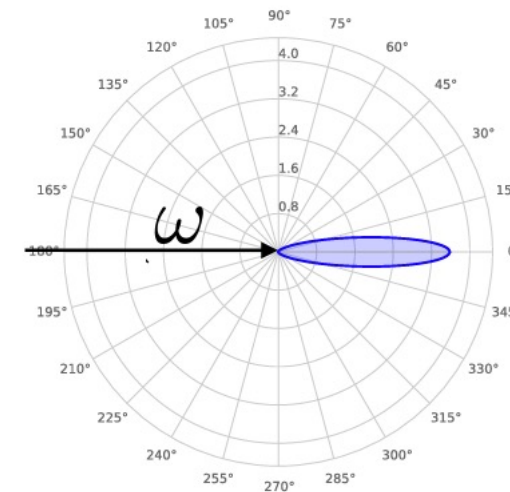


Subsurface scattering

An important physical phenomenon that occurs inside translucent objects



σ_t : extinction coefficient
 α : volumetric albedo





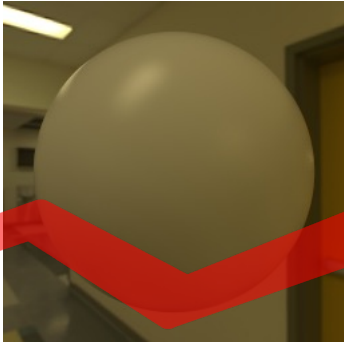
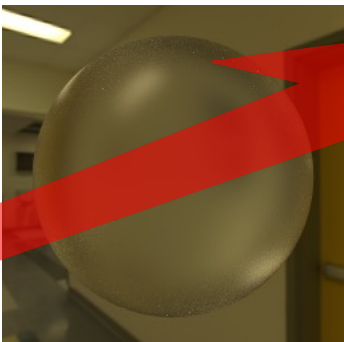
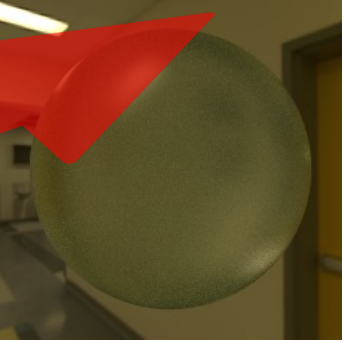
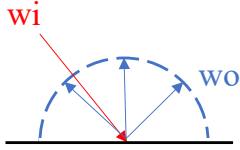
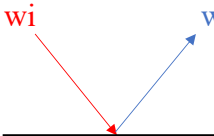
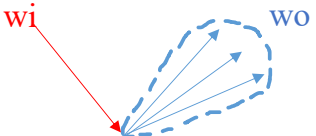
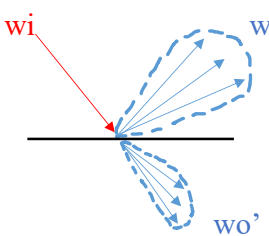
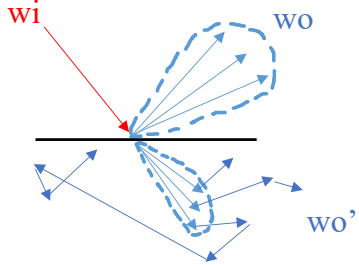
Henyey-Greenstein

<https://jannovak.info/publications/VolumeCourse/index.html>

g : phase function parameter



Challenges: complex material introduce more ambiguity

Diffuse	Specular	Glossy	Glossy & Transparent	Our material model
				
				

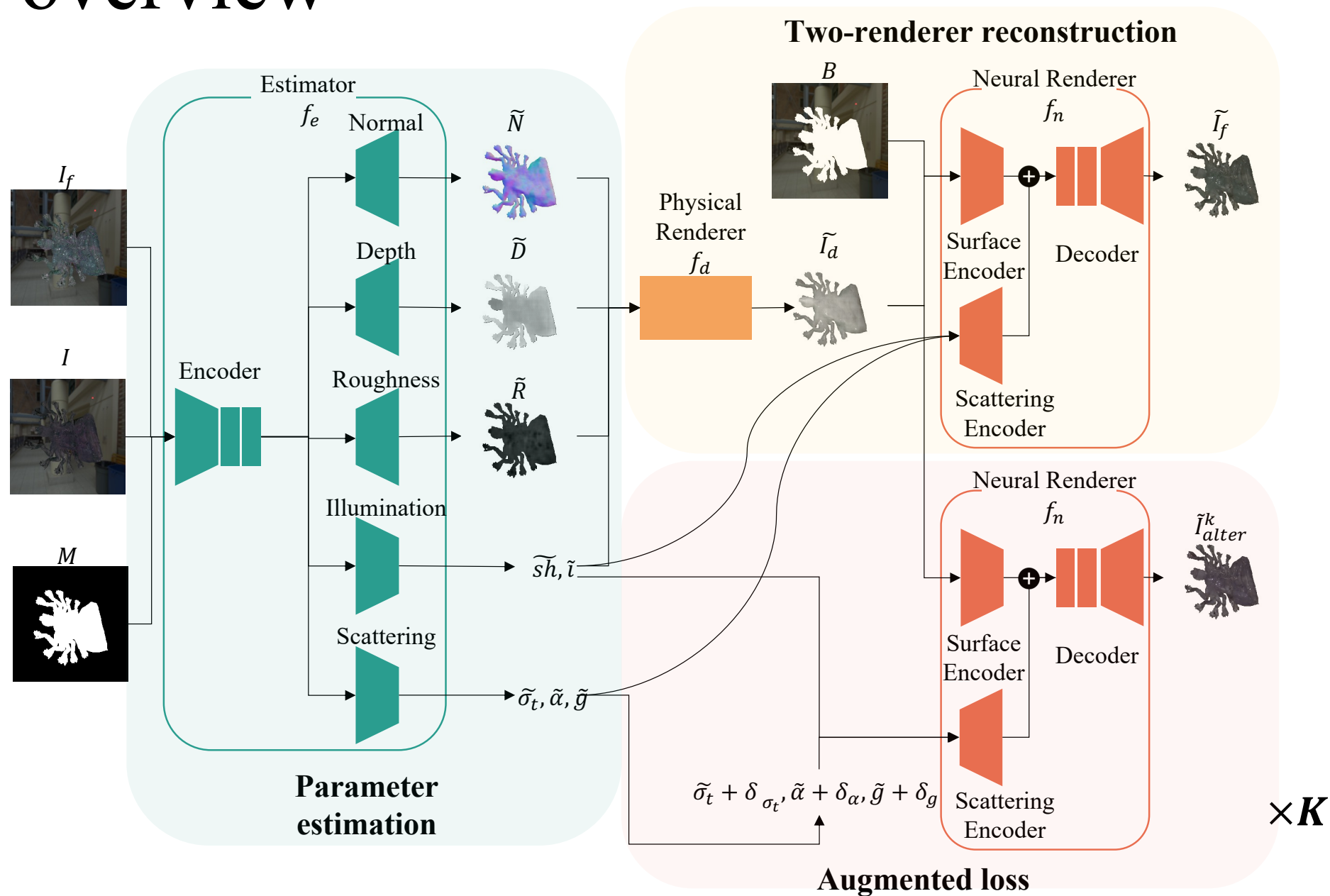
A red arrow points from the 'Diffuse' column to the 'Our material model' column, indicating an increase in ambiguity.

Translucent objects exhibit surface reflection and subsurface scattering at the same time!

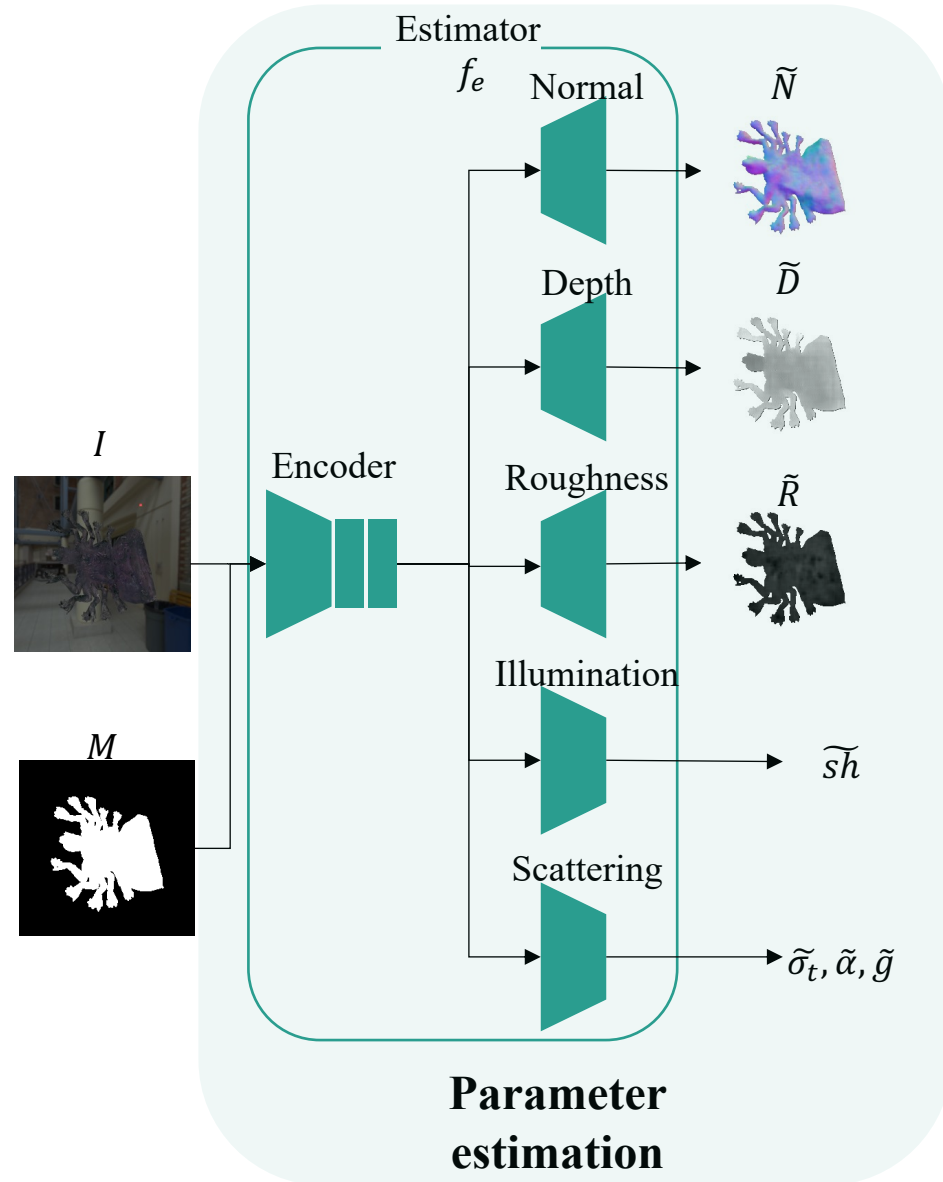
Multi-path,
Multi-bounce scattering



Model overview



Estimator



Input:

- Image I
- Mask M

Out put:

- Surface normal \tilde{N}
- Depth \tilde{D}
- Roughness \tilde{R}
- Illumination $\tilde{s}h$
- Subsurface scattering parameter $\tilde{\sigma}_t, \tilde{\alpha}, \tilde{g}$

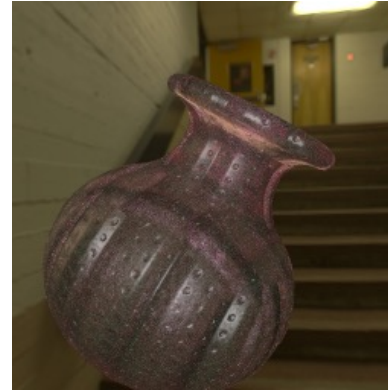


Improvement: flash and no-flash inputs

w/o flashlight



w/ flashlight

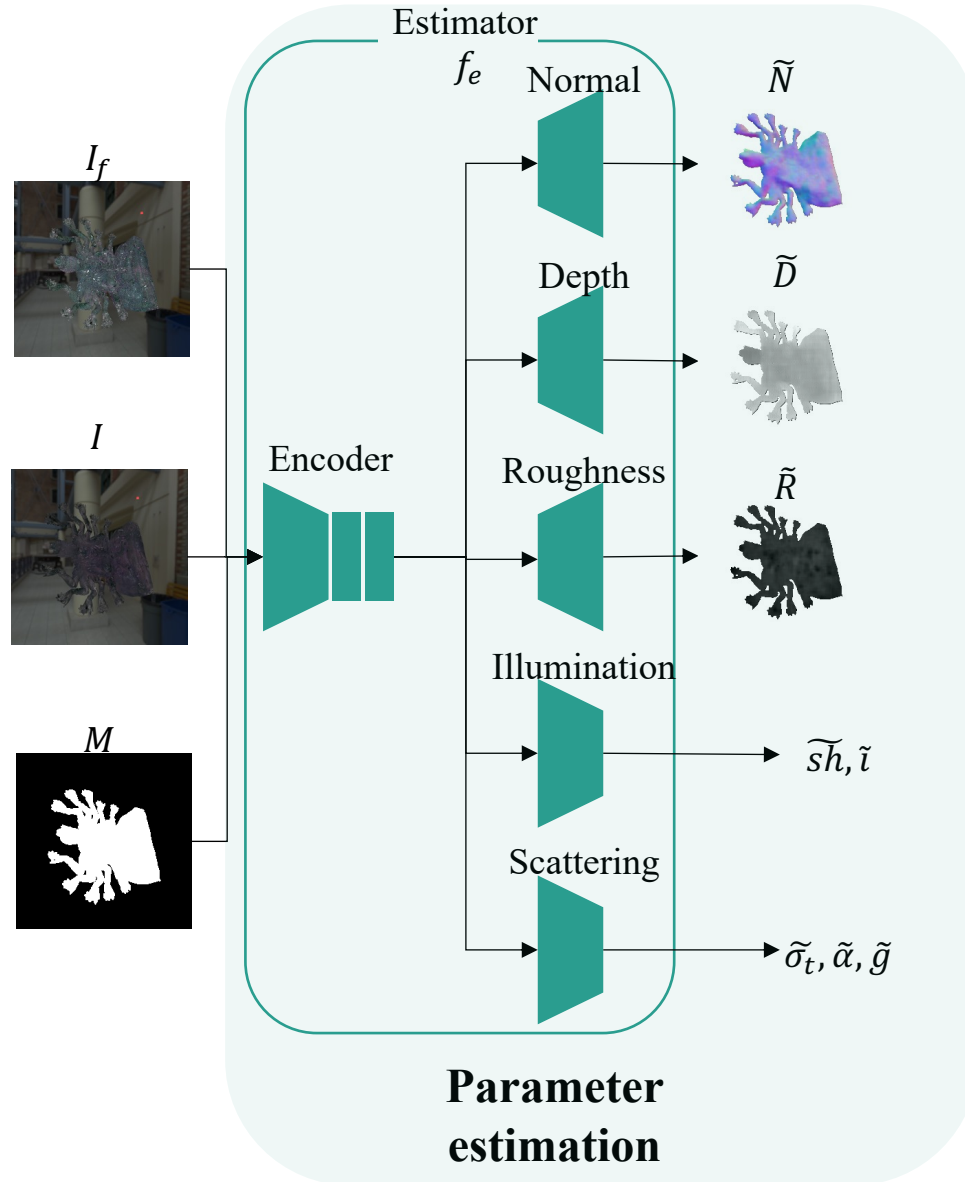


Motivation of using flash and no-flash images:

- the appearance of translucent object is significantly affected by the illumination



Two-shot inputs

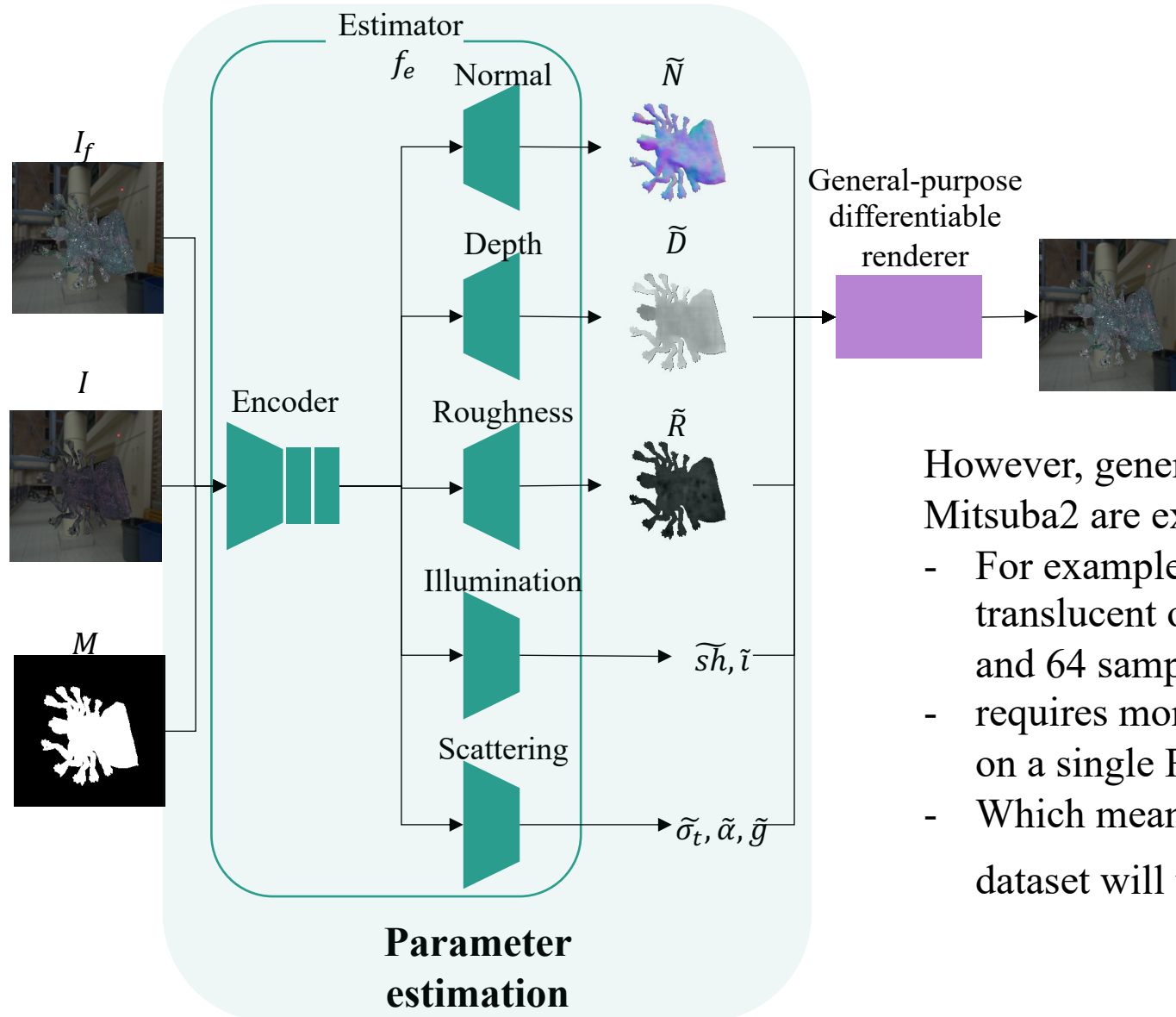


Improvements:

- Adding a flash image I_f as input
- Also estimate a flashlight intensity \tilde{i}



Using a general-purpose renderer for reconstruction loss?

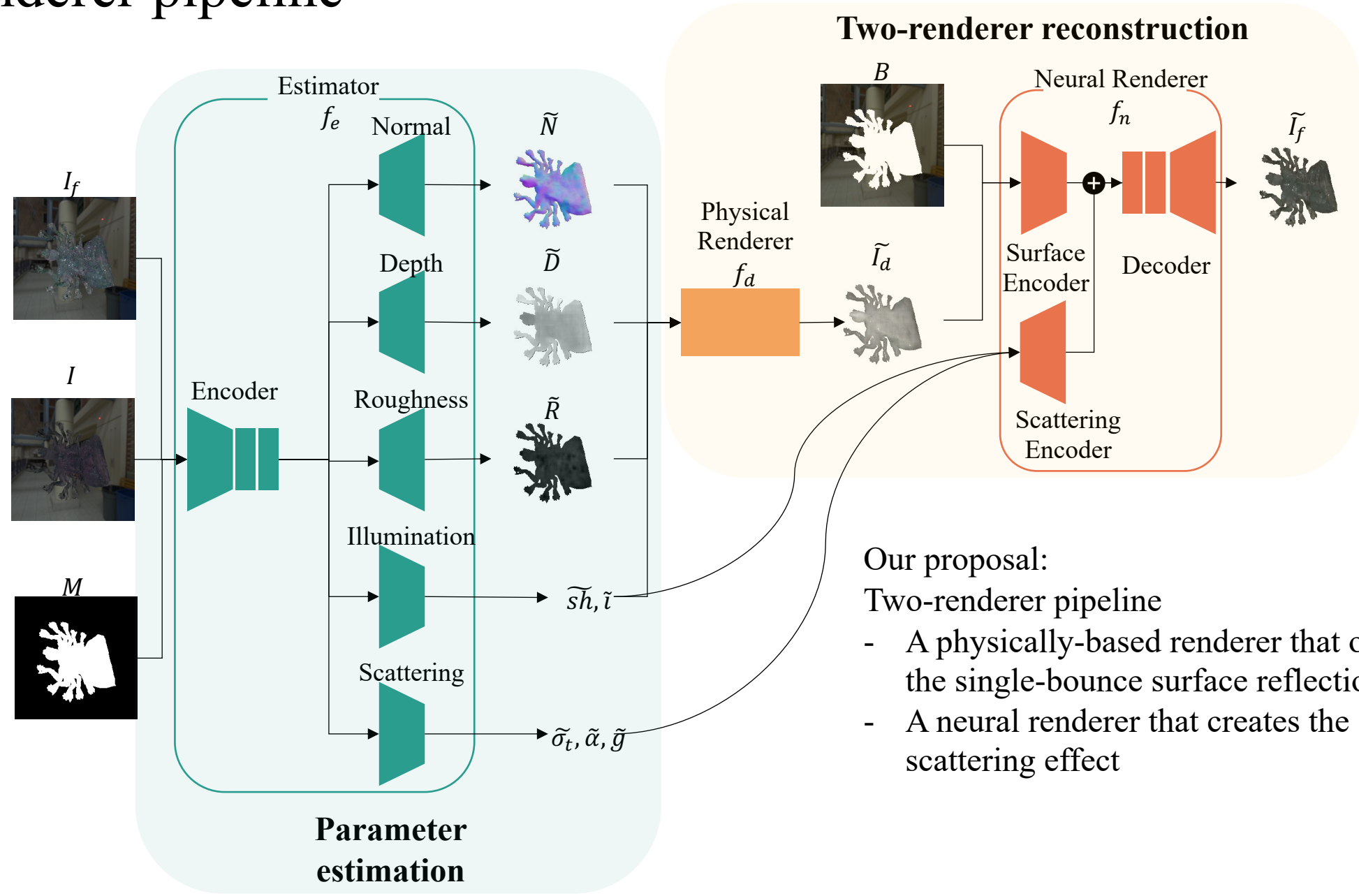


However, general-purpose differentiable renderers like Mitsuba2 are expensive:

- For example, differentiable rendering of a single translucent object image with 256x256 resolution and 64 samples per pixel (spp)
- requires more than 5 seconds and 20 GB memory on a single RTX3090 GPU.
- Which means the training of 20 epochs on our 117K dataset will take **115 DAYS!!**



Two-renderer pipeline

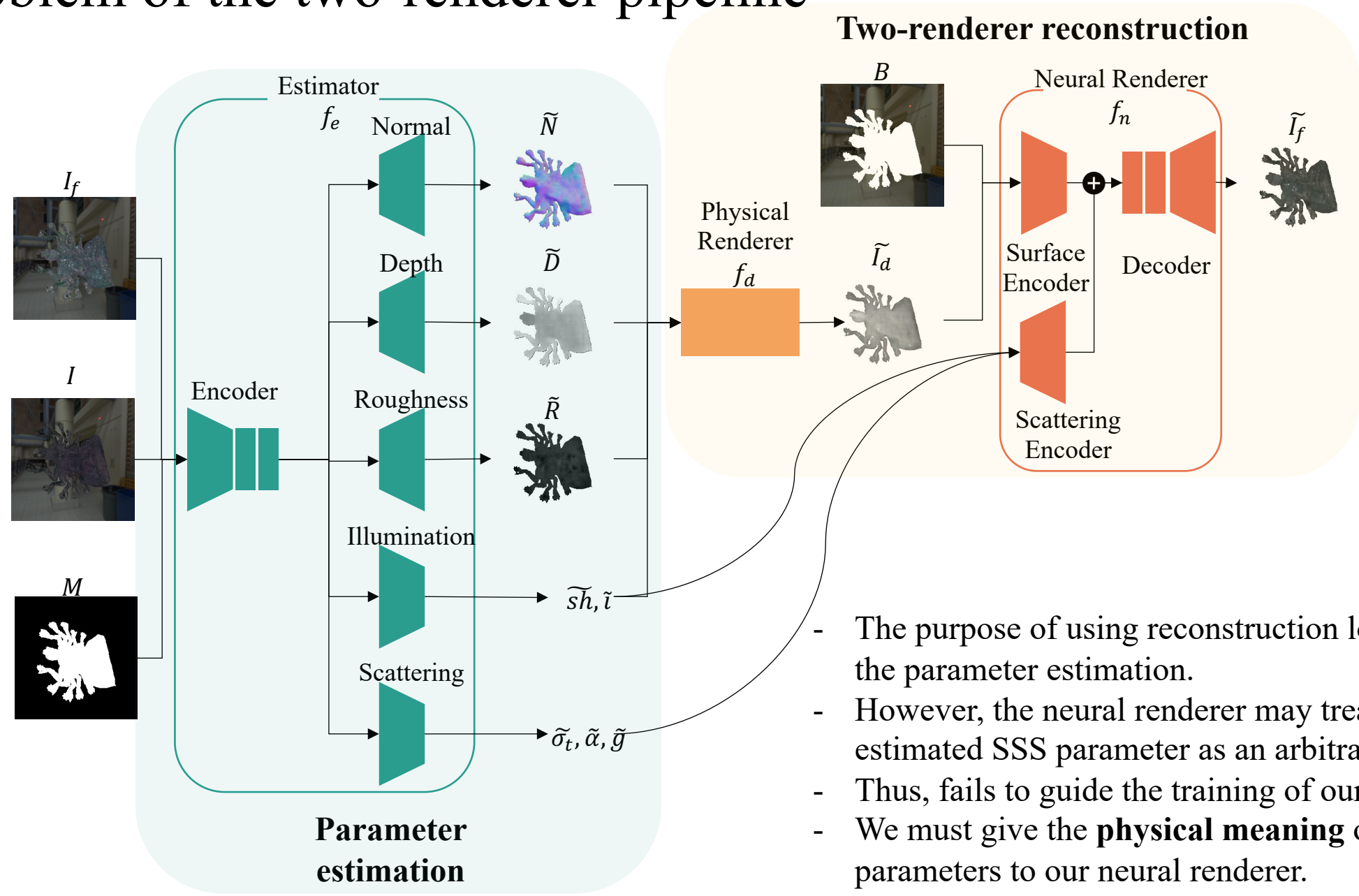


Our proposal:

Two-renderer pipeline

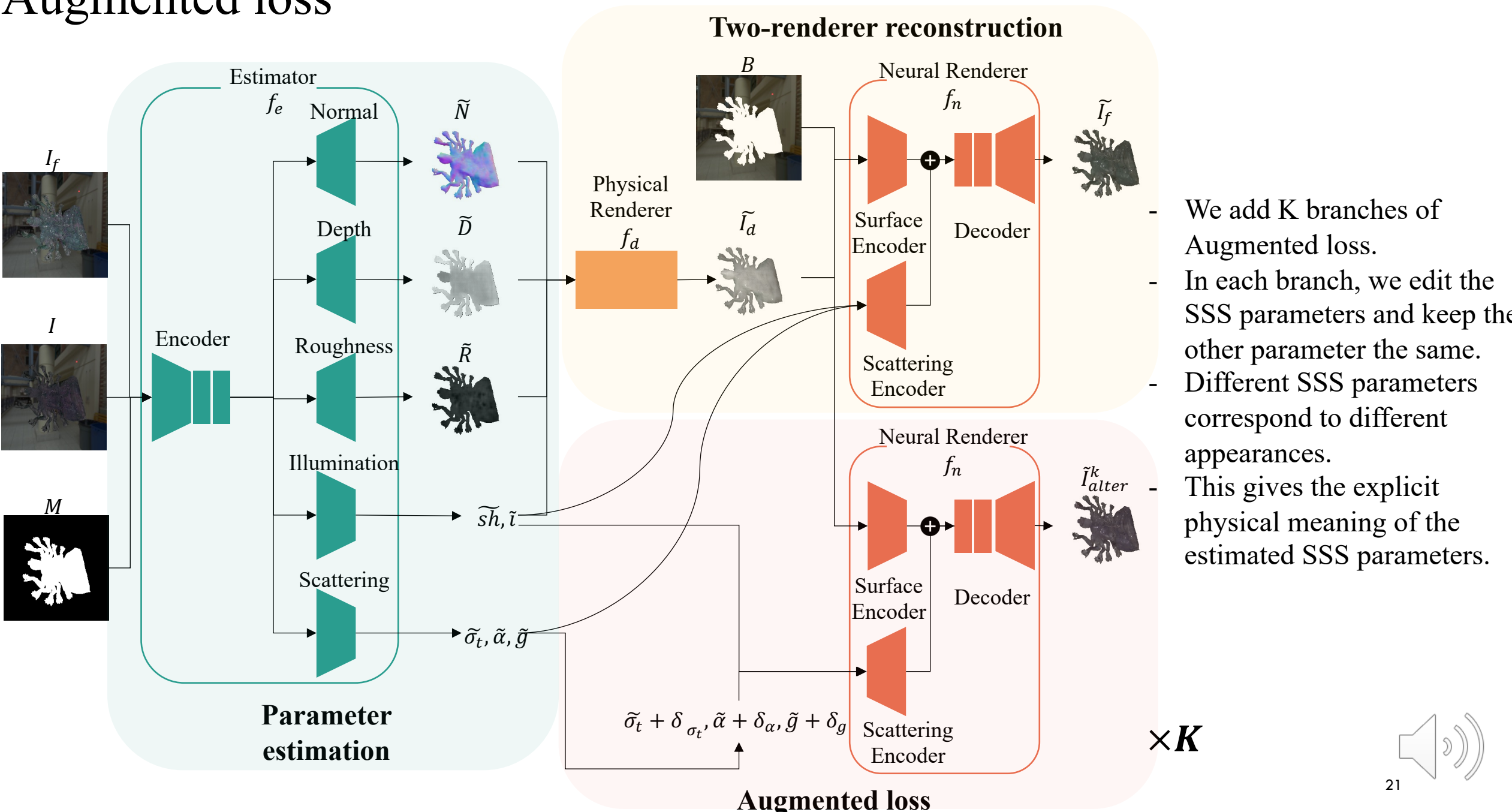
- A physically-based renderer that only render the single-bounce surface reflection
- A neural renderer that creates the subsurface scattering effect

One problem of the two-renderer pipeline



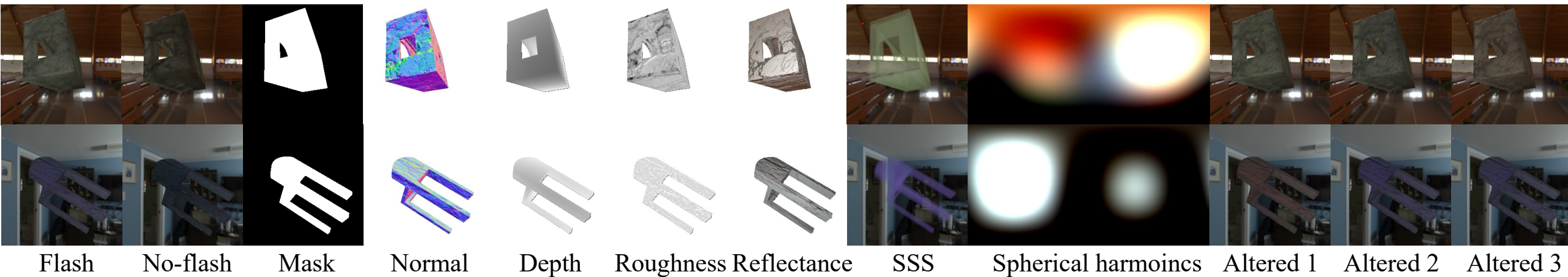
- The purpose of using reconstruction loss is to assist the parameter estimation.
- However, the neural renderer may treat the estimated SSS parameter as an arbitrary latent code.
- Thus, fails to guide the training of our Estimator.
- We must give the **physical meaning** of SSS parameters to our neural renderer.

Augmented loss



- We add K branches of Augmented loss.
- In each branch, we edit the SSS parameters and keep the other parameter the same.
- Different SSS parameters correspond to different appearances.
- This gives the explicit physical meaning of the estimated SSS parameters.

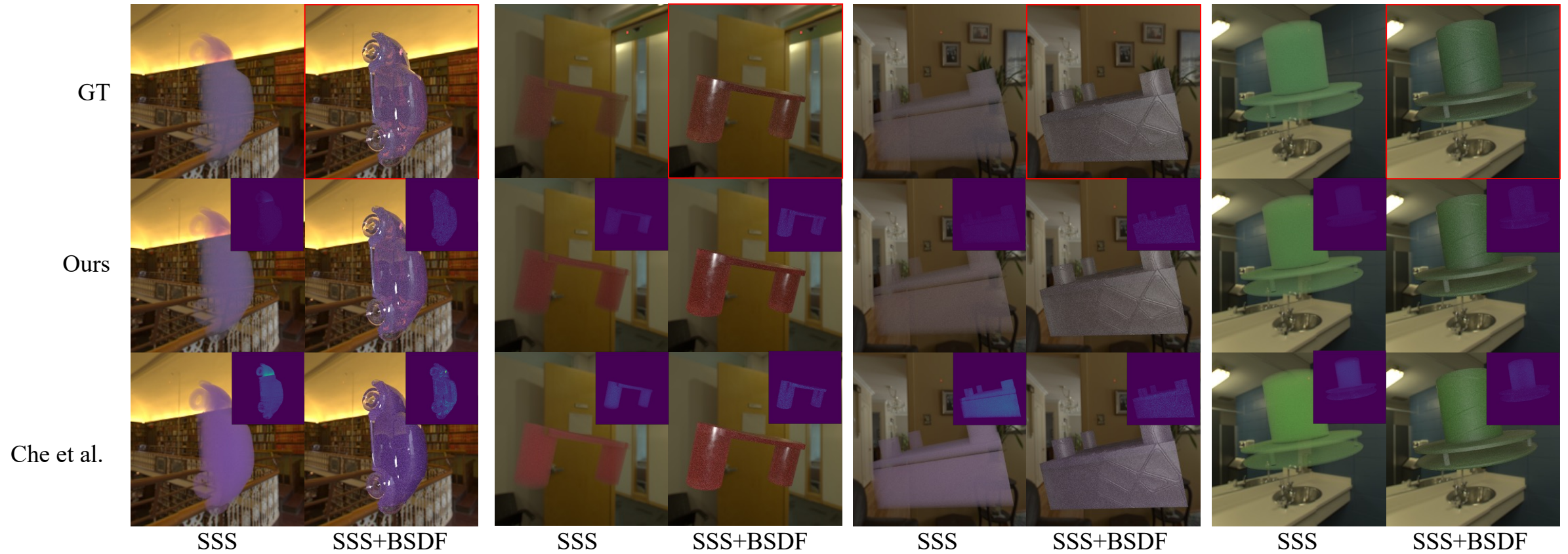
Our translucent objects dataset



- We construct a large-scale synthetic dataset consisting of more than 117K translucent scenes.
- Each scene contains
 - a human-created 3D model
 - and is rendered with a spatially-varying microfacet BSDF,
 - homogeneous SSS,
 - under an environment illumination.



Visual comparison with an existing inverse scattering work



Re-rendered images using estimated SSS parameters.



Ablation study

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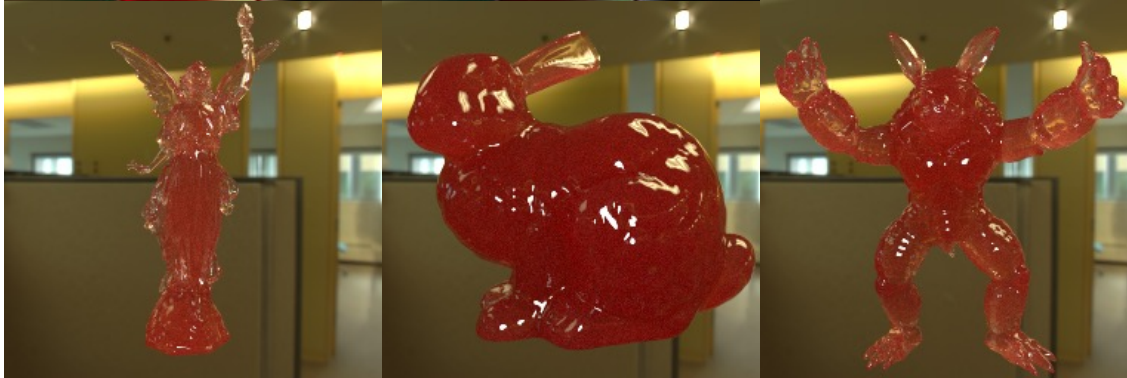


Application: Material acquisition

Input



Illumination 1



Illumination 2



Application: Material editing



Thank you!

