# Learning Instance-Level Representation for LargeScale Multi-Modal Pretraining in E-commerce 

Yang Jin, Yongzhi Li, Zehuan Yuan, Yadong Mu

Peking University, ByteDance Inc.
Poster: Wed-PM-269


## Our Foundation Model : ECLIP



## Introduction

Given an image-text pair, existing Vision-Language foundation models aims to learn the image-level representations.


## Introduction

We explore the ways to enable vision-language foundation model to obtain instance-level representation in E-commerce.

## General Domain

Foreground: horse, people, church


A group of people on horseback next to a church

## E-commerce Domain

Foreground: frying pan, coffee machine


Stainless steel frying pan


Italian semi-automatic home coffee maker

The difference of natural image and product image in E-commerce.

## Motivation

A product usually has multiple image samples from different sources (e.g., merchant, customer comments, attached advertisement videos, etc.)


PROYA ruby face cream for ladies
The property of product images in E-commerce.

## Instance Decoder



## Input:

Instance Query

$$
\boldsymbol{Q}=\left\{q_{t} \in \mathcal{R}^{D}\right\}_{t=1}^{T}, q_{t}=q_{t}^{\mathrm{prompt}}+q_{t}^{\mathrm{pos}}+q_{t}^{\text {type }} .
$$

One positive query, T-1 negative ones


Positive
Image Patch Representation

$$
\boldsymbol{Z}=\left\{z_{i} \in \mathcal{R}^{D}\right\}_{i=1}^{N} .
$$

Instance Representations

$$
\boldsymbol{H}=\left\{h_{t}\right\}_{t=1}^{T} \quad \boldsymbol{H}^{0} \text { are zero-initialized, }
$$

## Slot-Attention Layer



## Step 1:

Calculate the similarity matrix

$$
\begin{aligned}
& \qquad M=\frac{1}{\sqrt{D}}\left(Z W_{z}\right) \cdot\left(\left(Q+H^{l-1}\right) W_{q}\right)^{\top} \\
& \qquad M_{i j}=\frac{\exp \left(M_{i j}\right)}{\sum_{t=1}^{T} \exp \left(M_{i t}\right)} \cdot M \in \mathcal{R}^{N \times T}, \\
& \begin{array}{l}
\text { Image } \\
\text { Patches }
\end{array} \\
& \begin{array}{l}
\text { Instance } \\
\text { Queries }
\end{array}
\end{aligned}
$$

## Slot-Attention Layer



## Step 2:

Perform the soft assignment and Update the instance representation

$$
\begin{gathered}
\Delta h_{t}^{l-1}=\frac{1}{\sum_{i=1}^{N} M_{i t}} \sum_{i=1}^{N} M_{i t}\left(W_{v} z_{i}\right) . \\
h_{t}^{l}=h_{t}^{l-1}+W_{o} \Delta h_{t}^{l-1} .
\end{gathered}
$$



## Pretraining Proxy Tasks

## Image-Text Contrastive Learning :



$$
s\left(x^{I}, x^{T}\right)=g_{I}\left(v_{c l s}\right)^{\top} g_{T}\left(w_{c l s}\right)
$$

$$
\mathcal{L}_{i 2 t}=-\sum_{i=1}^{B} \log \frac{\exp \left(s\left(x_{i}^{I}, x_{i}^{T}\right) / \tau\right)}{\sum_{j=1}^{B} \exp \left(s\left(x_{i}^{I}, x_{j}^{T}\right) / \tau\right)}
$$

$$
\mathcal{L}_{t 2 i}=-\sum_{i=1}^{B} \log \frac{\exp \left(s\left(x_{i}^{T}, x_{i}^{I}\right) / \tau\right)}{\sum_{j=1}^{B} \exp \left(s\left(x_{i}^{T}, x_{j}^{I}\right) / \tau\right)}
$$



## Pretraining Proxy Tasks

## Inter-Product Multi-modal Learning



We use the similarity between $g_{I}\left(v_{c l s}\right)$ and $g_{T}\left(w_{c l s}\right)$ to sample the hard negative samples.

$$
\mathcal{L}_{\text {inter }}=-\sum_{i=1}^{B} \log \frac{\exp \left(h_{\theta}^{i}{ }^{\top} h_{\xi}^{j} / \tau\right)}{\exp \left(h_{\theta}^{i}{ }^{\top} h_{\xi}^{j} / \tau\right)+\sum_{k \in \mathcal{N}^{-}} \exp \left(h_{\theta}^{i}{ }^{\top} h_{\xi}^{k} / \tau\right)},
$$

## Pretraining Proxy Tasks

## Intra-Product Multi-modal Learning



To regularize the Similarity Matrix M

$$
\begin{aligned}
& \mathcal{L}_{\mathcal{R}}=\begin{array}{|l}
\sum_{i=1}^{N} M_{i, r} \log \left(\frac{1}{M_{i, r}}\right)+ \\
\\
\sum_{j=1, j \neq r}^{T}\left(\log N-\sum_{i=1}^{N} M_{i, j} \log \left(\frac{1}{M_{i, j}}\right)\right)
\end{array} \longrightarrow \text { For Positive Query } \\
&
\end{aligned}
$$

## Pretraining On 100M E-commerce Data

100M various image-text pairs, from 15M different products
(a) Product Detail Page

(b) Customer Comment

(c) Advertisement Video


Living room oil painting style tissue box

| Method | Classification |  |  | Image-to-Text |  |  | Text-to-Image |  |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Acc@1 |  | R@1 | R@5 |  | R@ | R@5 |  |
| CLIP [21] | 37.2 |  | 52.6 | 74.1 |  | 58.7 | 84.0 |  |
| FILIP [32] | 37.1 |  | 52.3 | 73.8 | 58.0 | 83.5 |  |  |
| DeCLIP [15] | 37.8 |  | 53.1 | 75.8 | 58.8 | 83.9 |  |  |
| ALBEF [13] | 38.5 |  | 52.9 | 74.4 | 58.2 | 83.3 |  |  |
| BLIP [12] | 39.3 |  | 53.3 | 75.6 | 59.1 | 84.4 |  |  |
| Ours $_{\text {ViT-B/16 }}$ | 43.8 |  | 53.8 | 76.0 | 59.9 | 84.6 |  |  |
| Ours $_{\text {viT-L/16 }}$ | $\mathbf{4 4 . 8}$ |  | $\mathbf{5 8 . 2}$ | $\mathbf{7 9 . 6}$ | $\mathbf{6 3 . 8}$ | $\mathbf{8 7 . 4}$ |  |  |

Zero-shot transfer to classification and image-text retrieval

## Experimental Results

| Method | Pretraining Dataset | Coarse Product Retrieval |  |  | Fine-grained Product Retrieval |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | mAP@1 | mAP@5 | mAP@10 | R@1 | R@5 | R@10 | mAP@1 | mAP@5 | mAP@10 |
| ViLBERT [17] |  | 58.6 | 61.7 | 60.1 | - | - | - | - | - | - |
| UNITER [2] | M5Product | 58.9 | 62.8 | 60.9 | - | - | - | - | - | - |
| SCALE [4] |  | 59.8 | 64.1 | 62.2 | - | - | - | - | - | - |
| CLIP [20] |  | 68.2 | 73.2 | 70.7 | 34.8 | 54.2 | 62.9 | 34.8 | 40.2 | 39.9 |
| FILIP [31] |  | 67.8 | 73.0 | 70.3 | 34.6 | 53.9 | 62.2 | 34.6 | 40.1 | 39.7 |
| DeCLIP [14] |  | 68.5 | 73.4 | 70.8 | 35.3 | 56.4 | 65.5 | 35.3 | 41.2 | 40.8 |
| ALBEF [12] | ECLIP 100M | 68.7 | 73.6 | 71.2 | 35.1 | 56.1 | 65.2 | 35.1 | 40.7 | 40.4 |
| BLIP [11] |  | 69.1 | 74.1 | 71.6 | 35.6 | 56.8 | 66.0 | 35.6 | 41.6 | 41.3 |
| Ours vit-B/16 $^{\text {a }}$ |  | 69.6 | 74.9 | 72.5 | 44.3 | 63.4 | 71.1 | 43.8 | 48.6 | 48.2 |
| Ours vith/l/ |  | 70.2 | 75.3 | 72.9 | 45.0 | 64.2 | 72.1 | 45.0 | 50.0 | 49.5 |

Zero-shot transfer to Product Retrieval

| Method | Visual Grounding |  |
| :--- | :---: | :---: |
|  | Acc@0.5 | Acc@0.7 |
| CLIP [20] | 80.9 | 75.2 |
| FILIP [31] | 81.3 | 75.6 |
| DeCLIP [14] | 81.0 | 75.3 |
| ALBEF [12] | 80.9 | 74.7 |
| BLIP [11] | 81.1 | 75.1 |
| Ours $_{\text {viT-B/16 }}$ | $\mathbf{9 1 . 2}$ | $\mathbf{8 9 . 6}$ |

## Visualization Results



ECLIP on Zero-Shot Grounding


The T-SNE visualization of learned representation

## Thanks!

