



# SCoDA: Domain Adaptive Shape Completion for Real Scans

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Yushuang Wu<sup>1,2,3</sup> Zizheng Yan<sup>1,2,3</sup> Ce Chen<sup>1,2</sup> Lai Wei<sup>4</sup> Xiao Li<sup>5</sup> Guanbin Li<sup>6,7</sup> Yihao Li<sup>1,2</sup> Shuguang Cui<sup>2,1</sup> Xiaoguang Han<sup>2,1#</sup>

<sup>1</sup>FNii, CUHKSZ <sup>2</sup>SSE, CUHKSZ <sup>3</sup>SRIBD <sup>4</sup>SDS, CUHKSZ <sup>5</sup>Microsoft Research Asia <sup>6</sup>Sun Yat-sen University <sup>7</sup>Research Institute, Sun Yat-sen University, Shenzhen







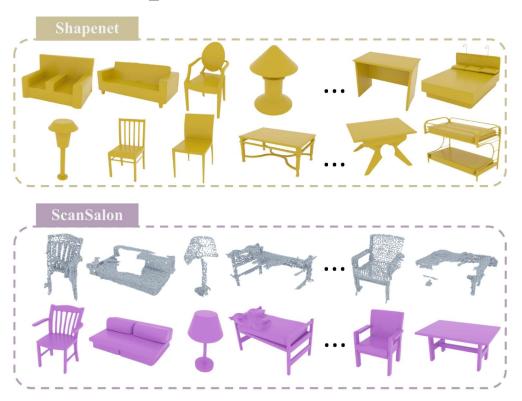








# Domain Gap



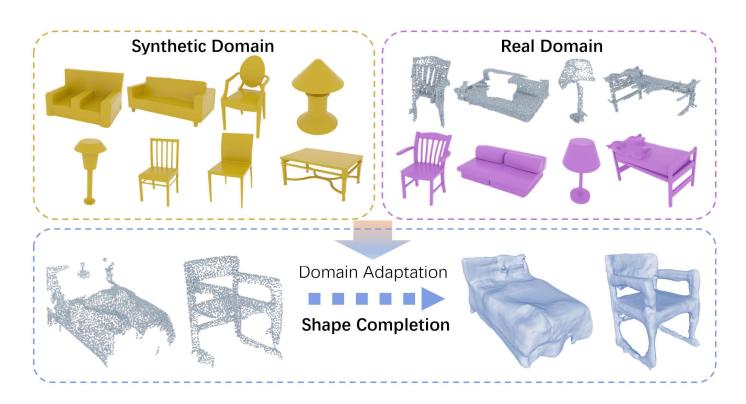
### Synthetic v.s. Real

- Noise
- Incompleteness
- Sparsity





## Task: Domain Adaptive Shape Completion







### Dataset: ScanSalon



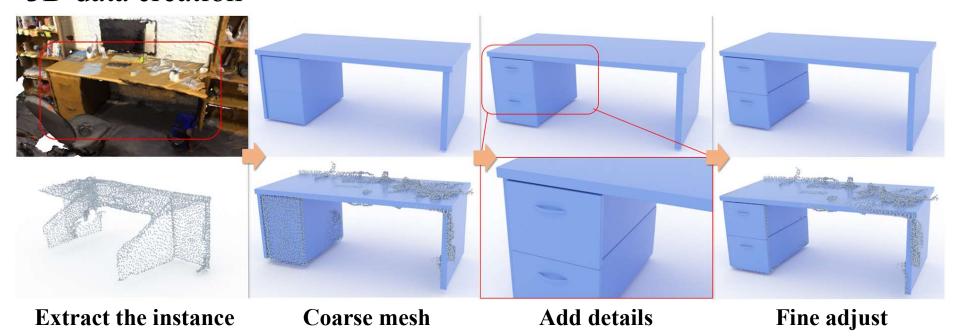
	Syn.	Real	Mesh
Chair	6,579	4,651	497
Desk	8,071	1,630	161
Sofa	3,091	428	43
Bed	233	365	36
Lamp	2,318	133	20
Car	3,514	437	43
Total	23,806	7,644	800





#### Dataset: ScanSalon

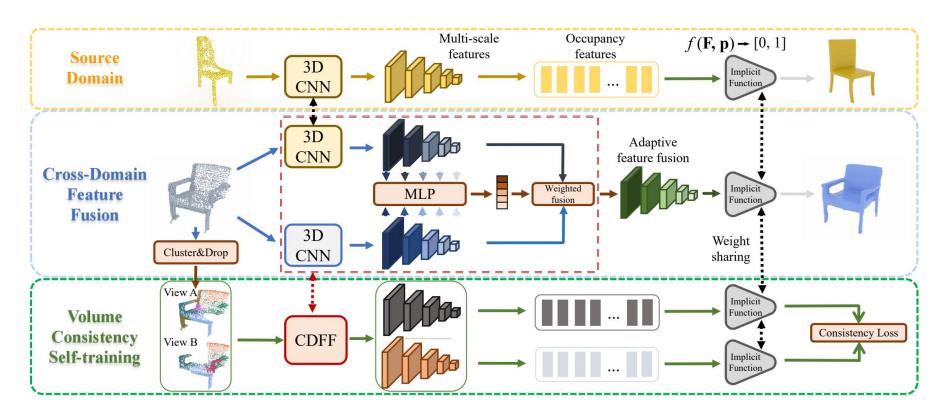
• 3D data creation







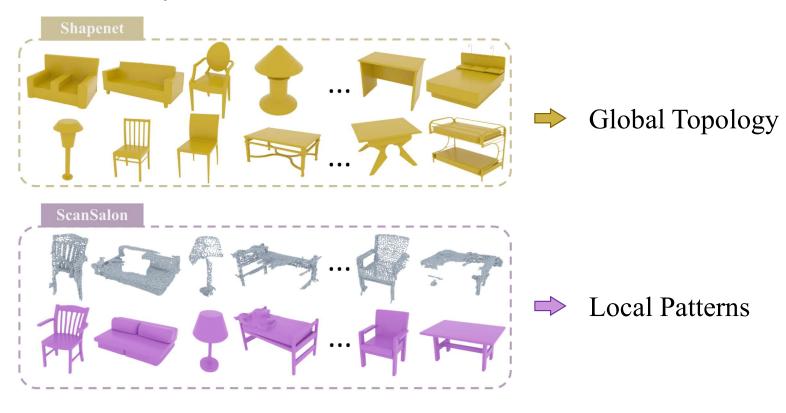
### Methods







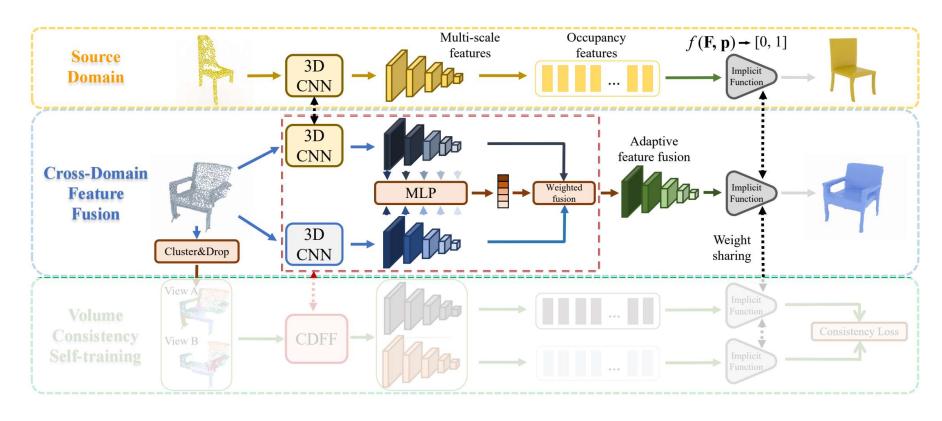
# Method: Key Observation







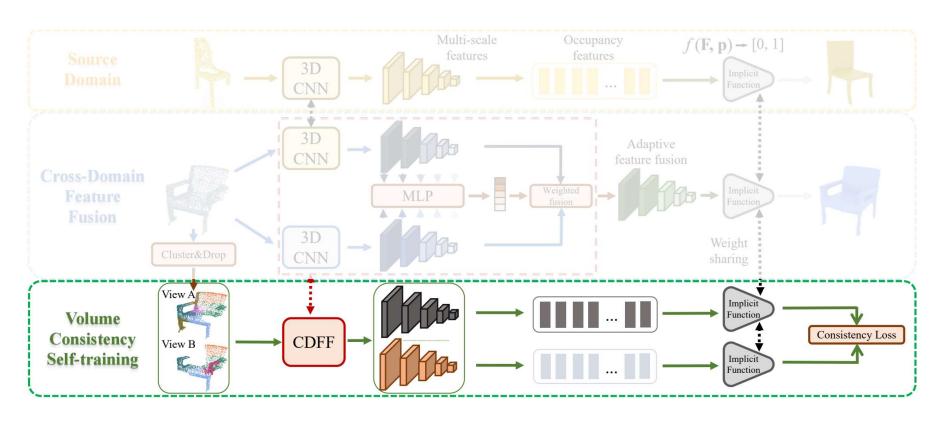
### Methods: CDFF

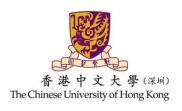






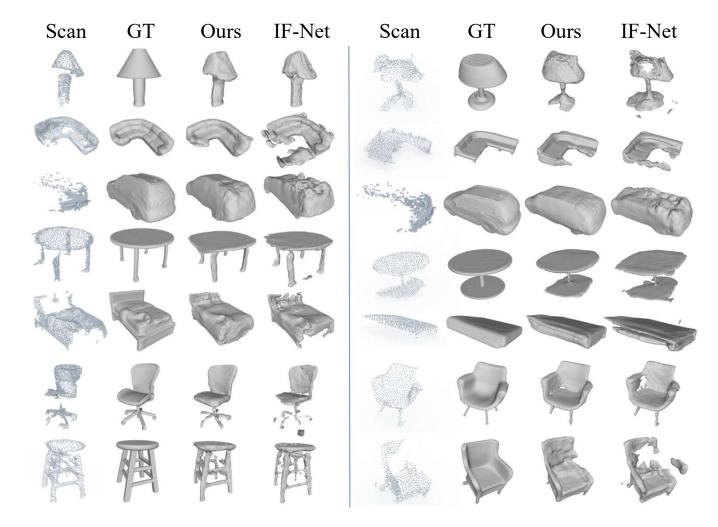
### Methods: VCST







### Results







### Results

#### (a) Results on the 3% labels setting.

	Chair		Desk		Sofa		Bed		Lamp		Car		Average	
Method	CD↓	mIoU↑	CD↓	mIoU↑	CD↓	mIoU↑	CD↓	mIoU↑	CD↓	mIoU↑	CD↓	mIoU↑	CD↓	mIoU↑
IF-Net	1.57	56.10	2.44	43.04	0.65	79.03	1.64	67.30	1.67	39.89	0.74	74.77	1.45	60.02
SelfSup	1.49	58.55	3.49	42.97	0.55	81.16	1.59	68.58	2.41	51.42	0.62	78.75	1.69	63.57
PtComp	1.61	57.33	2.16	44.26	0.51	79.90	1.52	68.23	1.95	46.97	0.59	80.35	1.39	62.84
Adversarial	1.74	58.54	2.99	46.02	0.46	81.42	1.37	71.32	2.43	56.39	0.67	78.91	1.61	65.43
Ours	1.58	60.77	2.36	48.62	0.42	82.00	1.57	73.05	1.62	58.57	0.41	80.96	1.32	67.32

#### (b) Results on the 5% labels setting.

	Chair		Desk		Sofa		Bed		Lamp		Car		Average	
Method	CD↓	mIoU↑	CD↓	mIoU↑	CD↓	mIoU↑	CD↓	mIoU↑	CD↓	mIoU↑	CD↓	mIoU↑	CD↓	mIoU↑
IF-Net	1.88	56.98	2.14	44.87	0.50	82.04	0.66	76.05	1.72	51.33	0.52	80.13	1.24	65.23
SelfSup	2.08	59.42	2.73	46.39	0.51	82.25	0.61	77.22	1.46	62.02	0.43	81.89	1.09	68.06
PtComp	1.34	57.98	1.83	46.20	0.32	82.66	0.61	79.07	1.44	61.61	0.43	81.89	1.00	68.24
Adversarial	1.71	60.58	2.13	48.46	0.41	83.54	0.51	80.81	1.33	64.22	0.41	81.86	1.08	69.91
Ours	1.37	61.48	2.09	50.93	0.31	82.71	0.41	82.27	1.57	67.80	0.46	83.12	1.04	71.39

#### (c) Ablation results.

CDFF only														
VCST only	2.08	59.42	2.89	46.86	0.43	81.60	1.63	72.62	1.85	50.18	0.62	78.62	1.58	64.88





#### Conclusion

#### • Contributions:

- 1. A new task, SCoDA, is proposed, with a small dataset, ScanSalon, contributed.
- 2. A novel cross-domain feature fusion module is designed to combine the knowledge of global shapes and local patterns learned in the synthetic and real domain.
- 3. A volume-consistent self-training framework is proposed to improve the robustness of shape completion to the complex incompleteness of real scans.
- 4. Extensive experiments also demonstrate the superiority of the proposed method.





#### The End.

- Yushuang Wu:
- https://scholar.google.com/citations?user=x5gpN0sAAAAJ
- GAP Lab: (Generation and Analysis of Pixels, Points and Polygons)
- <a href="https://gaplab.cuhk.edu.cn">https://gaplab.cuhk.edu.cn</a>

