

HexPlane: A Fast Representation for Dynamic Scenes

Ang Cao, Justin Johnson University of Michigan TUE-AM-013



HexPlane gives promising synthesis results with over 100x acceleration













- Fast speed (more than 100x) during training and inference.
- **Powerful** representation ability for dynamic scenes.
- Disentangling speeds and performance.
- Compact model size to represent dense 4D grids.
- Inherent feature sharing is **robust** to sparse observations.
- General representation for 4D field with minimal assumptions.

Thank you





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HexPlane: Motivation





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HexPlane: Method



HexPlane: Regularization





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HexPlane: Results





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DyNeRF 650K iterations 1344 hours (1x)

HexPlane 650K iterations 12 hours (112x)





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HexPlane

650K iterations 12 hours (112x) HexPlane 100K iterations 2 hours (672x)











HexPlane with different coordinate systems

Euclidean Coordinate (x, y, z, t)

Spherical Coordinate (θ, φ, r, t)





HexPlane with different **fusion designs**



HexPlane with different **decoding designs**





Spherical Harmonics





HexPlane: Summary

- We propose HexPlane, a simple and elegant solution for dynamic field representation
- We decompose a 4D grid into six 2D feature planes, and query point features via interpolation and fusion operations.
- It shows impressive results with significant acceleration for dynamic novel view synthesis task.



As a general 4D representation, HexPlane could empower generation and other 4D tasks.



Text-To-4D Dynamic Scene Generation, Uriel Singer et al. 2023

Thank you

