



Toward Accurate Post-Training Quantization for Image Super Resolution

No. 967

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Background & Motivation

- Model quantization is a crucial step for deploying super resolution (SR) networks on mobile devices.
- Existing works focus on quantization-aware training (QAT), which requires complete dataset and expensive computational overhead.
- On the contrast, post-training quantization (PTQ) only requires a few unlabeled calibration images without training, which enables fast deployment on various devices within minutes.

| Method | Туре | Data | Gt | Bs | Iters | Run time |
|------------|------|------|--------------|----|---------|---------------|
| EDSR [28] | FP | 800 | ✓ | 16 | 15,000 | $240 \times$ |
| PAMS [25] | QAT | 800 | \checkmark | 16 | 1,500 | $24 \times$ |
| FQSR [39] | QAT | 800 | \checkmark | 16 | 15,000 | $120 \times$ |
| CADyQ [14] | QAT | 800 | \checkmark | 8 | 30,000 | $240 \times$ |
| DAQ [15] | QAT | 800 | \checkmark | 4 | 300,000 | $1200 \times$ |
| DDTB [49] | QAT | 800 | \checkmark | 16 | 3,000 | $48 \times$ |
| Ours | PTQ | 100 | × | 2 | 500 | $1 \times$ |

Background & Motivation

- Different from the image classification, super resolution requires accurate prediction for each pixel of the output images, which is much sensitive to low-bit compression for feature maps.
- We observe three properties of their distributions that are much unfriendly to quantization:

Long-tailed

0.02

0.00

-100 -50

ò

(a) body.0.conv1

50 100

150

Asymmetric

Highly-dynamic

0.00 400

-200

Ó

(d) body.31.conv1

200

50

Ó

(c) body.21.conv1

100



0.02

0.00

200

-200

-100

Ó

(b) body.11.conv1

100

-150 -100 -50

Building Accurate Post-training quantization for SR

we propose a coarse-to-fine method to get the accurate quantized SR model with post-training quantization.

- We first introduce the density-based dual clipping (DBDC) to cut off most of the outliers for narrowing the distribution to a valid range
- Then utilize pixel-aware calibration (PaC) to help the quantized network fit the highly dynamic activations for different samples



What is the Model Quantization

There are three steps in tensor quantization:

(1) Truncate the tensor x into range [l, u],

(2) Map the floating-point tensor of the range [l, u] to the integer tensor of the range $[0, 2^n - 1]$,

(3) Reconstruct the floating point tensor from the integer tensor.

$$\begin{aligned} x_c &= \operatorname{Clamp}(x, l, u), \\ x_{int} &= \operatorname{Round}(\frac{x_c - l}{u - l} \times (2^N - 1)), \\ x_q &= x_{int} \times \frac{(u - l)}{2^N - 1} + l, \end{aligned}$$

Density-based Dual Clipping

■ DBDC Aims to cut off outliers of activations, help narrow the distribution to a valid range.

1. We first divide the original activation x into the N equal interval based on its min-max value

$$\Delta = (\max(x) - \min(x))/N,$$
$$H(p) = \sum_{i \in x} \mathbb{I}(i > p \& i$$

2. By comparing the density values between the position of l_a and u_a iteratively, we make the clipping position with smaller density closer to the middle

$$l_a^t, u_a^t = \begin{cases} l_a^{t-1} + \Delta, u_a^{t-1}, & H(l_a^{t-1}) < H(u_a^{t-1}) \\ l_a^{t-1}, u_a^{t-1} - \Delta, & H(l_a^{t-1}) \ge H(u_a^{t-1}) \end{cases}$$

3. The global bounds l_a and u_a are updated by the exponential moving average (EMA) method

$$l_a = \beta \cdot l_a + (1 - \beta) \cdot l_a^T,$$

$$u_a = \beta \cdot u_a + (1 - \beta) \cdot l_a^T,$$

Pixel-aware Calibration

■ PaC finetunes these clipping parameters for fitting the highly-dynamic feature maps.

1. With the unlabeled calibration images and full-precision pretrained model, we can get outputs and the middle feature maps for different layers to build a dataset for finetuning

 $(\text{input, label})^i = (x^i, (F_1^i, F_2^i, ..., F_N^i, O^i))$

2. Then we construct the PaC loss between the output and feature maps of middle layers for fullprecision model and quantized model

$$L_{PaC} = L_o + \lambda L_{pt}$$
$$L_o = \frac{1}{H_o \cdot W_o \cdot C_o} ||O - O_q||_1, \qquad L_{pt} = \frac{1}{B} \sum_{i}^{N} \frac{1}{H_i \cdot W_i \cdot C_i} ||\hat{F}_i - \hat{F}_{q_i}||_2,$$

3. To stabilize the finetune process, we further propose to iteratively optimize the clipping parameters of weights and activations instead of finetuning them together.

Experimental Results on EDSR

| Method | Bit | Set5 (×4) | Set14 (×4) | BSD100 (×4) | Urban100 (×4) | Set5 (×2) | Set14 (×2) | BSD100 (×2) | Urban100 (×2) |
|-----------------|-----|--------------|--------------|--------------|---------------|--------------|--------------|--------------|---------------|
| Baseline | 32 | 32.485/0.899 | 28.815/0.788 | 27.721/0.742 | 26.646/0.804 | 38.193/0.961 | 33.948/0.920 | 32.352/0.902 | 32.967/0.936 |
| Bicubic | 32 | 28.420/0.810 | 26.000/0.703 | 25.960/0.668 | 23.140/0.658 | 33.660/0.930 | 30.24/0.869 | 29.560/0.843 | 26.880/0.840 |
| OpenVINO [11] | 8 | 32.148/0.892 | 28.629/0.782 | 27.572/0.735 | 26.454/0.796 | 32.148/0.892 | 28.629/0.782 | 27.572/0.735 | 26.454/0.796 |
| TensorRT [38] | 8 | 32.329/0.895 | 28.711/0.784 | 27.639/0.738 | 26.548/0.799 | 37.880/0.958 | 33.774/0.917 | 32.217/0.899 | 32.764/0.933 |
| SNPE [18] | 8 | 32.329/0.896 | 28.707/0.786 | 27.646/0.740 | 26.551/0.800 | 37.786/0.957 | 33.751/0.917 | 32.189/0.898 | 32.733/0.932 |
| MSE [4] | 8 | 32.191/0.897 | 28.524/0.785 | 27.539/0.740 | 26.341/0.799 | 37.781/0.960 | 33.349/0.919 | 32.114/0.901 | 32.237/0.934 |
| Percentile [26] | 8 | 32.306/0.897 | 28.642/0.785 | 27.630/0.739 | 26.310/0.796 | 38.041/0.960 | 33.686/0.910 | 32.256/0.901 | 32.690/0.934 |
| MinMax [20] | 8 | 32.350/0.896 | 28.730/0.785 | 27.654/0.740 | 26.560/0.800 | 37.983/0.959 | 33.832/0.918 | 32.260/0.900 | 32.719/0.934 |
| Ours | 8 | 32.460/0.898 | 28.763/0.787 | 27.695/0.741 | 26.567/0.802 | 38.120/0.960 | 33.850/0.920 | 32.313/0.901 | 32.810/0.935 |
| OpenVINO [11] | 6 | 30.283/0.843 | 27.426/0.735 | 26.592/0.687 | 25.214/0.740 | 34.337/0.907 | 31.436/0.860 | 30.236/0.833 | 30.172/0.878 |
| TensorRT [38] | 6 | 30.696/0.851 | 27.719/0.744 | 26.765/0.694 | 25.459/0.749 | 34.735/0.913 | 31.778/0.867 | 30.472/0.841 | 30.582/0.887 |
| SNPE [18] | 6 | 30.493/0.839 | 27.599/0.735 | 26.664/0.685 | 25.386/0.742 | 34.305/0.903 | 31.499/0.858 | 30.249/0.831 | 30.336/0.877 |
| MSE [4] | 6 | 30.648/0.879 | 27.593/0.771 | 26.881/0.725 | 25.256/0.773 | 35.746/0.950 | 32.163/0.909 | 31.231/0.909 | 30.302/0.917 |
| Percentile [26] | 6 | 31.496/0.875 | 28.188/0.768 | 27.213/0.720 | 25.890/0.773 | 36.610/0.944 | 32.890/0.904 | 31.599/0.885 | 31.666/0.917 |
| MinMax [20] | 6 | 31.073/0.863 | 27.986/0.760 | 27.011/0.713 | 25.643/0.713 | 36.037/0.936 | 32.544/0.897 | 31.286/0.878 | 31.208/0.908 |
| Ours | 6 | 32.300/0.894 | 28.653/0.784 | 27.627/0.738 | 26.382/0.797 | 37.896/0.958 | 33.675/0.918 | 32.186/0.899 | 32.452/0.932 |
| OpenVINO [11] | 4 | 20.526/0.542 | 18.949/0.475 | 18.636/0.439 | 18.418/0.467 | 24.157/0.606 | 22.642/0.559 | 22.346/0.543 | 22.083/0.589 |
| TensorRT [38] | 4 | 21.343/0.512 | 19.809/0.461 | 19.495/0.423 | 19.100/0.450 | 23.897/0.608 | 22.325/0.571 | 22.208/0.553 | 22.068/0.600 |
| SNPE [18] | 4 | 21.417/0.472 | 20.035/0.413 | 19.925/0.392 | 19.320/0.406 | 23.284/0.548 | 22.086/0.522 | 22.215/0.517 | 21.873/0.555 |
| MSE [4] | 4 | 24.600/0.737 | 24.365/0.668 | 24.343/0.635 | 22.183/0.649 | 28.813/0.855 | 27.898/0.827 | 27.706/0.813 | 25.714/0.826 |
| Percentile [26] | 4 | 26.570/0.696 | 24.834/0.620 | 24.173/0.576 | 22.871/0.608 | 29.803/0.788 | 27.992/0.758 | 27.187/0.736 | 26.514/0.766 |
| MinMax [20] | 4 | 23.132/0.635 | 21.208/0.569 | 23.266/0.508 | 20.220/0.554 | 28.005/0.744 | 25.960/0.703 | 24.684/0.682 | 24.717/0.725 |
| Ours | 4 | 31.203/0.867 | 27.977/0.760 | 27.085/0.714 | 25.556/0.764 | 36.327/0.942 | 32.753/0.904 | 31.477/0.884 | 30.900/0.913 |

Experimental Results on SRResNet

| Method | Bit | Set5 (×4) | Set14 (×4) | BSD100 (×4) | Urban100 (×4) | Set5 (×2) | Set14 (×2) | BSD100 (×2) | Urban100 (×2) |
|-----------------|-----|--------------|--------------|--------------|---------------|--------------|--------------|--------------|---------------|
| Baseline | 32 | 32.234/0.896 | 28.656/0.784 | 27.630/0.738 | 26.229/0.791 | 38.091/0.961 | 33.752/0.919 | 32.241/0.900 | 32.367/0.931 |
| Bicubic | 32 | 28.420/0.810 | 26.000/0.703 | 25.960/0.668 | 23.140/0.658 | 33.660/0.930 | 30.240/0.869 | 29.560/0.843 | 26.880/0.840 |
| OpenVINO [11] | 8 | 32.003/0.890 | 28.505/0.778 | 27.509/0.732 | 26.039/0.783 | 37.451/0.955 | 33.350/0.912 | 31.978/0.895 | 31.978/0.924 |
| TensorRT [38] | 8 | 32.013/0.891 | 28.507/0.779 | 27.508/0.733 | 26.069/0.785 | 37.506/0.956 | 33.428/0.913 | 31.984/0.895 | 32.026/0.925 |
| SNPE [18] | 8 | 32.120/0.893 | 28.556/0.781 | 27.562/0.736 | 26.111/0.788 | 37.734/0.957 | 33.529/0.915 | 32.085/0.896 | 32.100/0.927 |
| MSE [4] | 8 | 32.006/0.892 | 28.387/0.779 | 27.469/0.734 | 25.910/0.784 | 37.737/0.958 | 33.247/0.915 | 31.972/0.897 | 31.665/0.926 |
| Percentile [26] | 8 | 32.092/0.893 | 28.492/0.780 | 27.525/0.735 | 26.046/0.786 | 37.739/0.958 | 33.414/0.916 | 32.058/0.897 | 31.965/0.927 |
| MinMax [20] | 8 | 31.984/0.891 | 28.495/0.779 | 27.503/0.733 | 26.057/0.785 | 37.539/0.956 | 33.413/0.913 | 31.992/0.895 | 32.020/0.925 |
| Ours | 8 | 32.207/0.895 | 28.619/0.783 | 27.618/0.738 | 26.191/0.790 | 38.032/0.960 | 33.648/0.919 | 32.212/0.900 | 32.210/0.930 |
| OpenVINO [11] | 6 | 30.080/0.835 | 27.348/0.727 | 26.665/0.683 | 24.861/0.721 | 33.539/0.884 | 31.007/0.849 | 30.050/0.827 | 29.505/0.857 |
| TensorRT [38] | 6 | 29.990/0.828 | 27.277/0.724 | 26.553/0.681 | 24.782/0.719 | 33.634/0.885 | 30.923/0.846 | 30.011/0.827 | 29.270/0.854 |
| SNPE [18] | 6 | 29.650/0.814 | 27.112/0.714 | 26.449/0.671 | 24.690/0.710 | 33.120/0.874 | 30.501/0.834 | 29.654/0.813 | 28.895/0.842 |
| MSE [4] | 6 | 30.822/0.872 | 27.642/0.760 | 27.002/0.718 | 25.003/0.752 | 36.010/0.944 | 32.099/0.898 | 31.174/0.881 | 29.935/0.904 |
| Percentile [26] | 6 | 30.970/0.869 | 27.874/0.760 | 27.085/0.715 | 25.340/0.756 | 35.826/0.936 | 32.314/0.893 | 31.192/0.874 | 30.707/0.902 |
| MinMax [20] | 6 | 30.725/0.859 | 27.784/0.750 | 26.987/0.704 | 25.233/0.744 | 34.964/0.919 | 31.895/0.877 | 30.755/0.856 | 30.286/0.886 |
| Ours | 6 | 32.089/0.892 | 28.504/0.779 | 27.561/0.733 | 26.011/0.783 | 37.811/0.959 | 33.295/0.916 | 32.068/0.898 | 31.719/0.926 |
| OpenVINO [11] | 4 | 24.316/0.573 | 23.201/0.519 | 23.276/0.500 | 21.614/0.528 | 24.415/0.535 | 23.570/0.508 | 23.551/0.502 | 22.942/0.556 |
| TensorRT [38] | 4 | 23.729/0.461 | 22.648/0.402 | 22.808/0.389 | 21.089/0.399 | 24.769/0.535 | 23.753/0.502 | 23.733/0.491 | 22.753/0.526 |
| SNPE [18] | 4 | 23.130/0.413 | 22.317/0.376 | 22.404/0.358 | 20.793/0.371 | 24.111/0.505 | 23.297/0.477 | 23.195/0.464 | 22.452/0.511 |
| MSE [4] | 4 | 27.979/0.784 | 25.828/0.680 | 25.704/0.641 | 23.042/0.639 | 31.239/0.870 | 29.106/0.828 | 28.470/0.801 | 26.376/0.804 |
| Percentile [26] | 4 | 27.283/0.699 | 25.411/0.625 | 25.329/0.603 | 22.990/0.605 | 27.369/0.703 | 26.477/0.689 | 26.180/0.668 | 24.866/0.686 |
| MinMax [20] | 4 | 26.639/0.654 | 25.122/0.599 | 25.107/0.577 | 22.746/0.573 | 25.824/0.603 | 25.302/0.602 | 25.191/0.584 | 23.914/0.606 |
| Ours | 4 | 31.146/0.878 | 27.889/0.763 | 27.152/0.718 | 25.133/0.753 | 36.487/0.951 | 32.404/0.904 | 31.357/0.885 | 29.896/0.904 |

Combined with QAT

| Method | Scale | Bit | FQ | QAT | Set5 | Set14 | BSD100 | Urban100 |
|------------|------------|-----|----|-----|--------------|--------------|--------------|--------------|
| | | 32 | | | 32.095/0.894 | 28.576/0.781 | 27.562/0.736 | 26.035/0.785 |
| DAMS [25] | ×4 | 4 | × | 1 | 31.591/0.885 | 28.199/0.773 | 27.322/0.728 | 25.321/0.762 |
| PANIS [23] | ~ 2 | 32 | | | 37.985/0.960 | 33.568/0.918 | 32.155/0.899 | 31.977/0.927 |
| | ×Z | 4 | × | 1 | 37.665/0.959 | 33.196/0.915 | 31.936/0.897 | 31.100/0.919 |
| | ~ 1 | 32 | | | 32.007/0.892 | 28.486/0.778 | 27.528/0.731 | 25.934/0.781 |
| EOSP [30] | ×4 | 4 | ✓ | 1 | 30.928/0.870 | 27.816/0.761 | 27.073/0.715 | 24.927/0.744 |
| FQ3K [39] | ~ 2 | 32 | | | 37.885/0.958 | 33.425/0.915 | 32.106/0.897 | 31.777/0.924 |
| | ~4 | 4 | 1 | ✓ | 37.038/0.951 | 32.835/0.908 | 31.668/0.889 | 30.646/0.911 |
| | | 32 | | | 32.485/0.899 | 28.815/0.788 | 27.721/0.742 | 26.646/0.804 |
| | | 4 | × | × | 32.105/0.891 | 28.563/0.781 | 27.553/0.714 | 26.051/0.787 |
| | $\times 4$ | 4 | × | ✓ | 32.295/0.895 | 28.576/0.784 | 27.558/0.738 | 26.232/0.794 |
| | | 4 | 1 | × | 31.203/0.867 | 27.977/0.760 | 27.085/0.714 | 25.556/0.764 |
| Ours | | 4 | ✓ | 1 | 31.641/0.881 | 28.217/0.772 | 27.332/0.727 | 25.748/0.777 |
| Ours | | 32 | | | 38.193/0.961 | 33.948/0.920 | 32.352/0.902 | 32.967/0.936 |
| | | 4 | × | × | 37.837/0.958 | 33.662/0.917 | 32.146/0.898 | 32.335/0.930 |
| | $\times 2$ | 4 | × | ✓ | 37.992/0.960 | 33.838/0.919 | 32.205/0.900 | 32.545/0.933 |
| | | 4 | ✓ | × | 36.327/0.942 | 32.753/0.904 | 31.477/0.884 | 30.900/0.913 |
| | | 4 | 1 | 1 | 37.561/0.955 | 33.442/0.915 | 31.992/0.896 | 31.725/0.924 |

Ablation study & Visualization

| DBDC PaC | | PaC | Set5 | Set14 | BSD100 | Urban100 |
|----------|---|-----|--------------|--------------|--------------|--------------|
| - | | | 26.570/0.696 | 24.834/0.620 | 24.173/0.576 | 22.871/0.608 |
| | 1 | | 30.406/0.838 | 27.510/0.735 | 26.633/0.687 | 25.312/0.736 |
| | | ✓ | 28.000/0.775 | 26.002/0.681 | 25.406/0.630 | 24.116/0.669 |
| | ✓ | 1 | 31.203/0.867 | 27.977/0.760 | 27.085/0.714 | 25.556/0.764 |



Thank you!





MindSpore