

Masked Image Modeling with Local Multi-Scale Reconstruction

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LocalMIM: local multi-scale reconstruction

 \blacktriangleright For MIM models, thousands of GPU Hours for pre-training limit their industrial applications.

\succ Local reconstruction

- we are the first to conduct reconstruction tasks at both lower and upper layers, which explicitly guide multiple layers to accelerate the representation learning.
- Multi-scale supervision
 - for both columnar and pyramidal architectures, the lower layers reconstruct the fine-scale supervision signals, and the upper layers reconstruct the coarse-scale ones.



Performance

- LocalMIM is architecture-agnostic and can be used in both columnar and pyramidal architectures.
- On columnar ViT-B, LocalMIM achieves the best results of BEiT, MAE and MaskFeat with 27.4x, 3.1x and 5.6x acceleration respectively.
- On pyramidal Swin-B, LocalMIM achieves the best results of SimMIM₁₉₂ and GreenMIM with 3.6x and 6.4x acceleration respectively.



Background

Masked Image Modeling: randomly mask some input parts and inference them based on other parts.

Classic works



MaskFeat [Wei et al., 2022]







Background

Disadvantages: huge computational burden and slow pre-training process The pre-training efficiency is an inevitable bottleneck limiting the industrial applications of MIM.

Existing works: accelerate the encoding process

1. the encoder only processes visible patches, e.g., MAE, GreenMIM.

2. shrinking the input resolution to lessen the input patches, e.g., LoMaR, UM-MAE, FastMIM.

None of them focus on the representation learning process itself!

Analysis

The lower layers of the encoder play the key role in the representation learning of MIM: 1) For pre-training, the well-learned lower layers can propagate knowledge to the upper ones and facilitate their learning.

2) For fine-tuning, the upper layers are typically tuned quickly to adapt the downstream task while the lower ones change more slowly and need to be well-learned during pre-training.

All existing MIM models only explicitly guide the top layer!

Analysis

Without explicit guidance, the inter-patch semantical relations on the lower layers can not be sufficiently learned.

It has the computational complexity with a quadratic dependence on patch number N, i.e., $\Theta(N^2)$.

Existing MIM models with global loss have small Normalized Mutual Information (NMI) at lower layers, which means their patches have less query-adaptive attentions.



Figure: NMI between query and key patches at each layer

Model

Encoder (e.g., ViT, Swin) patches Stage 3 Stage 1 Stage 2 visible Patchify & mask Decoder Decoder Local Reconstruction: loss loss ... multi-scale supervisions (e.g., normalized pixels, HOG feature) visible patch features mask tokens predictions input Figure: Overview of LocalMIM.

1. we are the *first* to conduct reconstruction tasks at multiple layers. 2. we are the *first* to use multiple scale supervision signals, where the lower layers reconstruct the fine-scale supervisions and the upper layers reconstruct the coarse-scale ones.



Model

Input:

 $x \in \mathbb{R}^{H \times W \times C}$

Supervisions:

 $y_i = \pi(x_i)$ where $\{x_i \in \mathbb{R}^{p \times p \times C}\}_{i=1}^{HW/p^2}$ are non-overlapping patches with the scale of $\frac{H}{p} \times \frac{W}{p}$, π is the feature descriptor, e.g., codebook, HOG, pixel normalization.

Decoder: Transformer block + rescale + MLP

The tiny decoders have only one Transformer block with small embedding dim and few attention heads.



Figure: reconstruction process under a scale.

| 1. Classificat | ion on ImageNet-1K |
|----------------|--------------------|
| ViT-B: | |
| BEiT | 27.4x |
| MAE | 3.1x |
| MaskFeat | 5.6x |
| Swin-B: | |
| SimMIM | 3.6x |
| GreenMIM | 6.4x |
| | |

| Model | Backbone | # Params | PT Epoch | GPU Hours/Ep. | Total GPU Hours | Acc |
|----------------------------|----------|----------|----------|---------------|------------------------|------|
| Scratch, ViT | ViT-B | 86M | 0 | 1.5 | - | 82.3 |
| Scratch, Swin | Swin-B | 88M | 0 | 2.4 | - | 83.5 |
| MoCo v3 [12] | ViT-B | 86M | 600 | - | | 83.2 |
| DINO [7] | ViT-B | 86M | 300 | - | - | 82.8 |
| BEiT [2] | ViT-B | 86M | 800 | 2.4 | 1920 | 83.2 |
| iBOT [67] | ViT-B | 86M | 400 | 10.1 | 4040 | 83.8 |
| MAE [24] | ViT-B | 86M | 800 | 1.1 | 880 | 83.3 |
| MAE [24] | ViT-B | 86M | 1600 | 1.1 | 1760 | 83.6 |
| MAE [24] | ViT-L | 307M | 1600 | 1.7 | 2720 | 85.9 |
| MaskFeat [57] | ViT-B | 86M | 1600 | 3.9 | 6240 | 84.0 |
| CAE [11] | ViT-B | 86M | 800 | 2.8 | 2240 | 83.6 |
| LoMaR [†] [8] | ViT-B | 86M | 1600 | 1.4 | 2240 | 84.1 |
| data2Vec [†] [1] | ViT-B | 86M | 800 | 3.0 | 2400 | 84.2 |
| PeCo [17] | ViT-B | 86M | 800 | - | - | 84.5 |
| LocalMIM-HOG | ViT-B | 86M | 100 | 0.7 | 70 | 83.3 |
| LocalMIM-HOG | ViT-B | 86M | 1600 | 0.7 | 1120 | 84.0 |
| LocalMIM-HOG | ViT-L | 307M | 800 | 1.0 | 800 | 85.8 |
| SimMIM ₁₉₂ [60] | Swin-B | 88M | 800 | 1.8 | 1440 | 84.0 |
| SimMIM ₁₉₂ [60] | Swin-L | 197M | 800 | 3.0 | 2400 | 85.4 |
| GreenMIM [31] | Swin-B | 88M | 800 | 0.8 | 640 | 83.7 |
| GreenMIM [31] | Swin-L | 197M | 800 | 1.4 | 1120 | 85.1 |
| LocalMIM-Pixel | Swin-B | 88M | 100 | 1.0 | 100 | 83.7 |
| LocalMIM-HOG | Swin-B | 88M | 100 | 1.1 | 110 | 83.8 |
| LocalMIM-Pixel | Swin-B | 88M | 400 | 1.0 | 400 | 84.0 |
| LocalMIM-HOG | Swin-B | 88M | 400 | 1.1 | 440 | 84.1 |
| LocalMIM-HOG | Swin-L | 197M | 800 | 1.6 | 1280 | 85.6 |

Figure: Top-1 fine-tuning accuracy on ImageNet-1K.

2. Segmentation and Detection

| Model | PT Epoch | PT Hours | mIoU | | | | | |
|---------------|-----------------|-----------------|------|----------------------------|----------|----------|------|---|
| Supervised | - | - | 47.4 | | | | | |
| MoCo v3 [12] | 300 | - | 47.3 | | | | | |
| BEiT [2] | 800 | 1920 | 47.1 | Madal | DT Encoh | DT House | A Db | |
| MAE [24] | 1600 | 1760 | 48.1 | Model | PI Epoch | P1 Hours | AP | P |
| MaskFeat [57] | 1600 | 6240 | 48.8 | Supervised | 300 | 840 | 48.5 | 4 |
| PeCo [17] | 800 | - | 48.5 | SimMIM ₁₉₂ [60] | 800 | 1440 | 50.4 | 4 |
| CAE [11] | 800 | 2240 | 48.8 | GreenMIM [31] | 800 | 640 | 50.0 | 4 |
| LocalMIM-HOG | 1600 | 1120 | 49.5 | LocalMIM-HOG | 400 | 440 | 50.7 | 4 |

Figure: Semantic segmentation on ADE20K

Figure: Object detection and instance segmentation on COCO

1. LocalMIM significantly outperforms supervised pre-training. 2. LocalMIM achieves better performance than other MIM models with less pre-training burden.

3. Visualization of the attention maps

1) For object-centric images, LocalMIM can distinguish the foreground object from the background.

2) For multi-object images, LocalMIM can effectively separate different objects without any task-specific supervision, which means the attention maps are query-adaptive.

3) The patches at lower layers typically more focus on their neighboring regions, while those at upper layers attend to a wide range of semantically related regions.





Input

2-th 4-th 10-th 12-th Figure: Visualization of the attention maps for different query points, marked with red boxes.

4. Gradient-isolated pre-training

| model | backbone | GPU Hours/Ep. | acc |
|------------------|----------|---------------|------|
| LocalMIM | VIT D | 0.7 | 83.3 |
| w/ isolated grad | VII-D | 0.7 | 83.0 |
| LocalMIM | Swin D | 1.1 | 83.8 |
| w/ isolated grad | Swill-D | 1.1 | 83.7 |

Surprisingly, the gradient-isolated training achieves similar performance to global back-propagation.

Thank you!

Paper:<u>https://openaccess.thecvf.com/content/CVPR2023/papers/Wang_Masked_Image_Modeling_With_Local_Mu</u> <u>lti-Scale_Reconstruction_CVPR_2023_paper.pdf</u>

Code: https://github.com/huawei-noah/Efficient-Computing/tree/master/Self-supervised/LocalMIM