



# Recovering Dynamic 3D Sketches from Videos

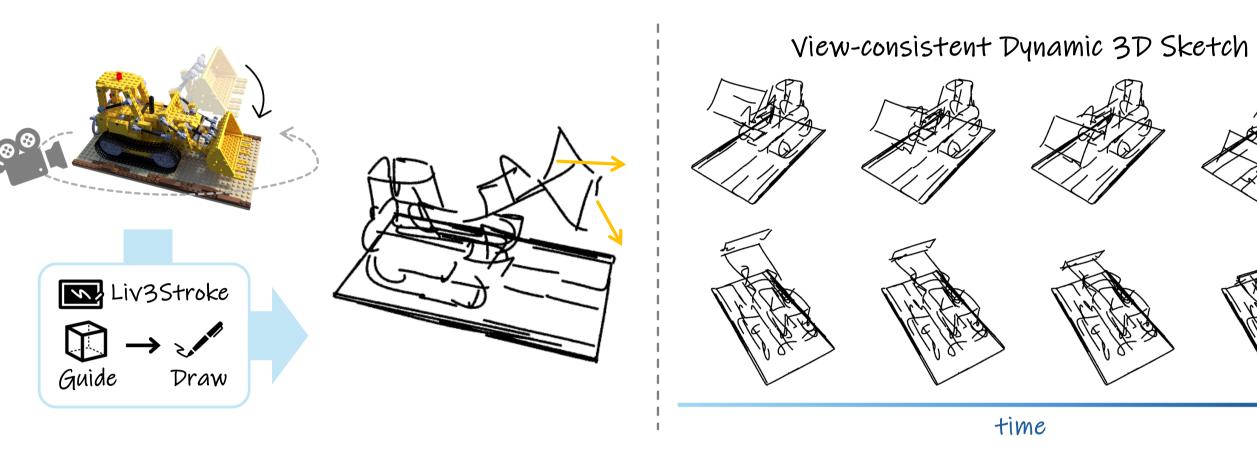
Jaeah Lee<sup>1</sup> Changwoon Choi<sup>2</sup> Young Min Kim<sup>2</sup> Jaesik Park<sup>1</sup> Seoul National University





# TL;DR

✓ Liv3Stroke is a novel approach for reconstructing dynamic sketches with deformable 3D strokes directly from video frames.

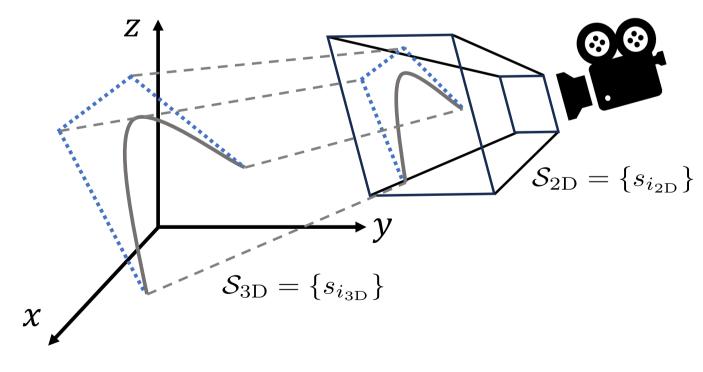


## **Problem Definition**

- ✓ Tracking 3D motion in videos is fundamentally ambiguous due to complex object types and projection into 2D frames.
- / Recent methods often aim for dense reconstruction, making them sensitive to appearance changes or imprecise alignments.
- ✓ We explore sketch-based abstraction to express 3D movements in a compact and robust way.

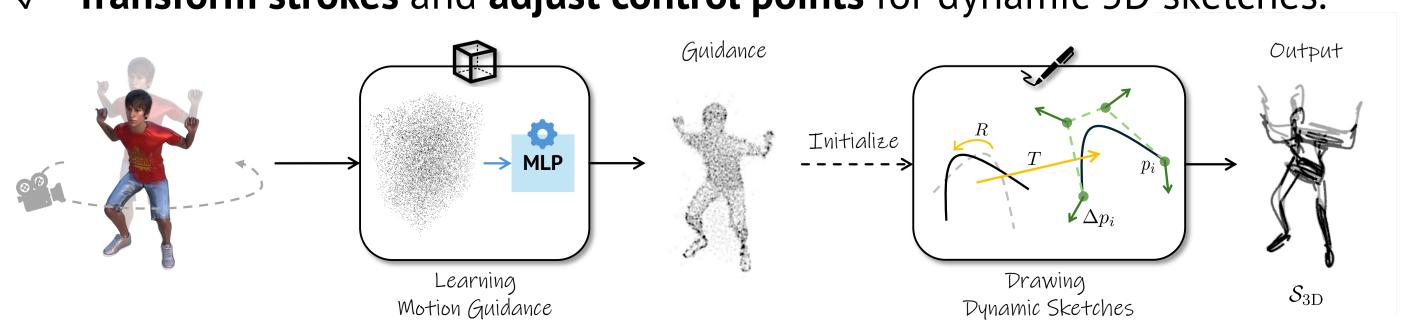
## Sketch representation

- Define a sketch as n black strokes on the white background.
- Each stroke is presented as a **3D cubic** Bézier curve, with four control points:  $s_i = \{p_i^j\}_{j=0}^3$

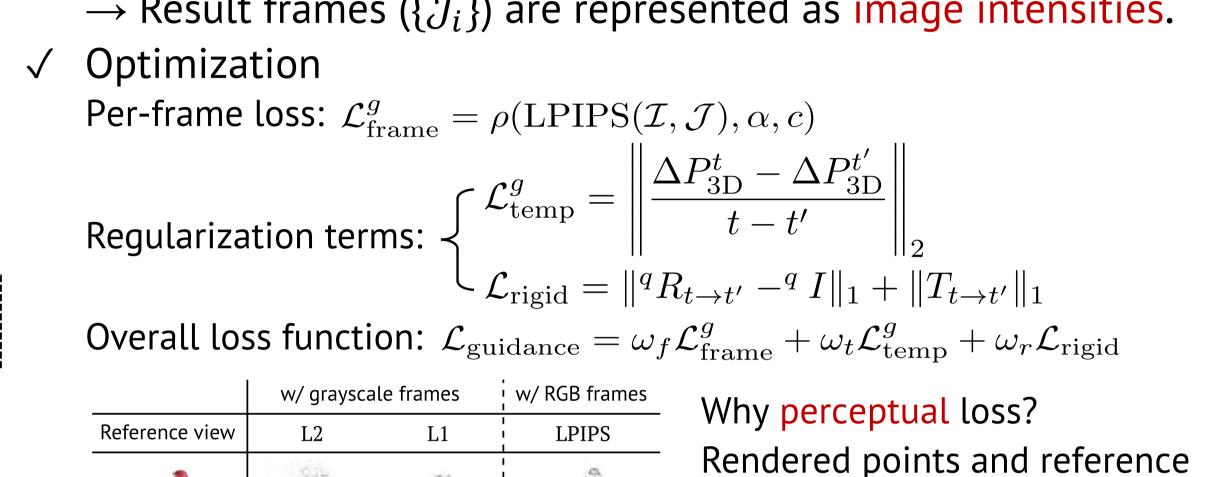


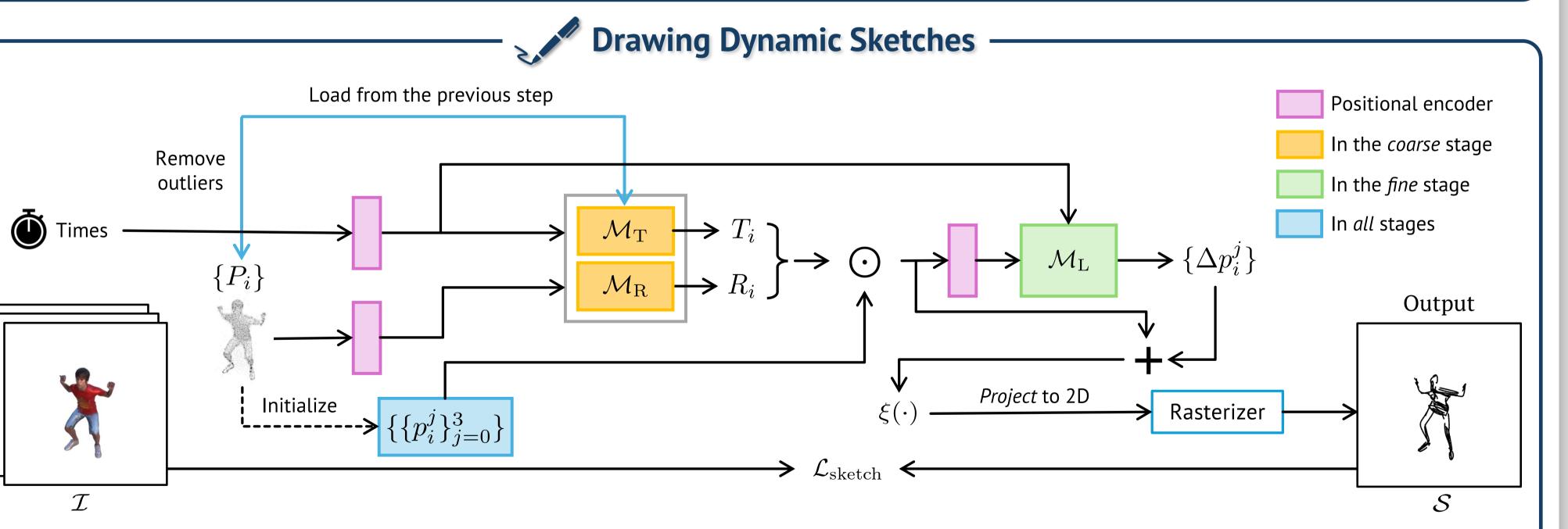
## **Method Overview**

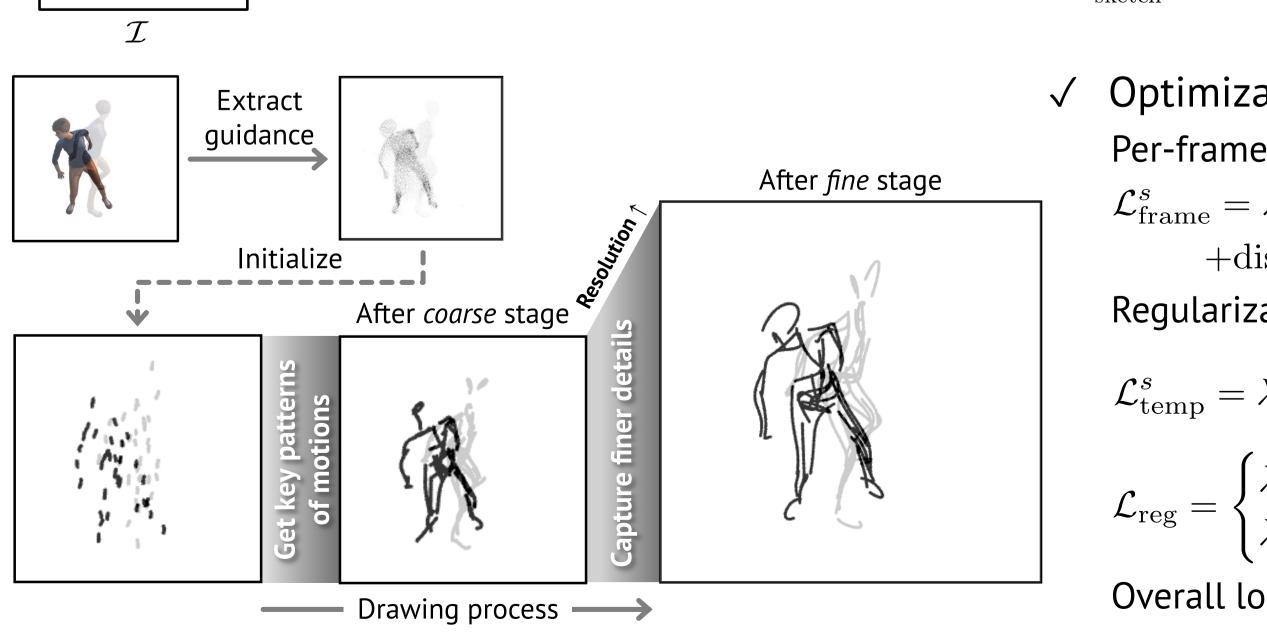
- Extract 3D motion guidance from frames for rough stroke movements.
- Transform strokes and adjust control points for dynamic 3D sketches.



## Method **Learning Motion Guidance** Each project point is represented as a Gaussian unit. Positional encoder $\rightarrow$ Result frames ( $\{\mathcal{J}_i\}$ ) are represented as image intensities.







*Project* to 2D

& Rasterize

# ✓ Optimization

Per-frame loss (with features from perceptual space):

 $\mathcal{L}_{\text{frame}}^s = \lambda_s \rho(\text{LPIPS}(\mathcal{I}, S), \alpha, c)$  $+ \operatorname{dist}(\operatorname{CLIP}(\mathcal{I}), \operatorname{CLIP}(S))$ 

Regularization terms:

 $\int \lambda_r (\|{}^q R_i - {}^q I\|_2 + \|T_i\|_2), \text{ if } coarse \text{ stage}$ 

views are of different types,

→ making direct comparison

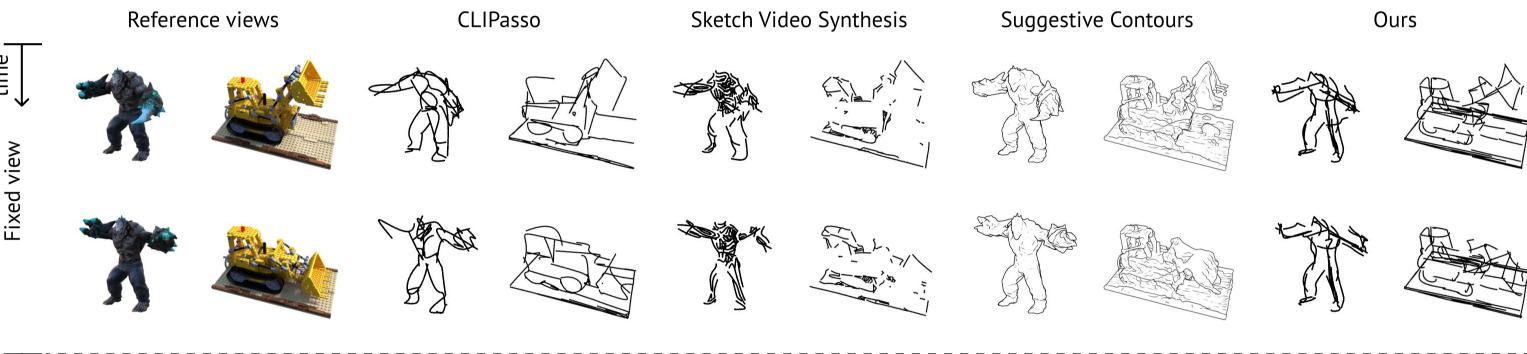
(e.g., pixel-wise) difficult.

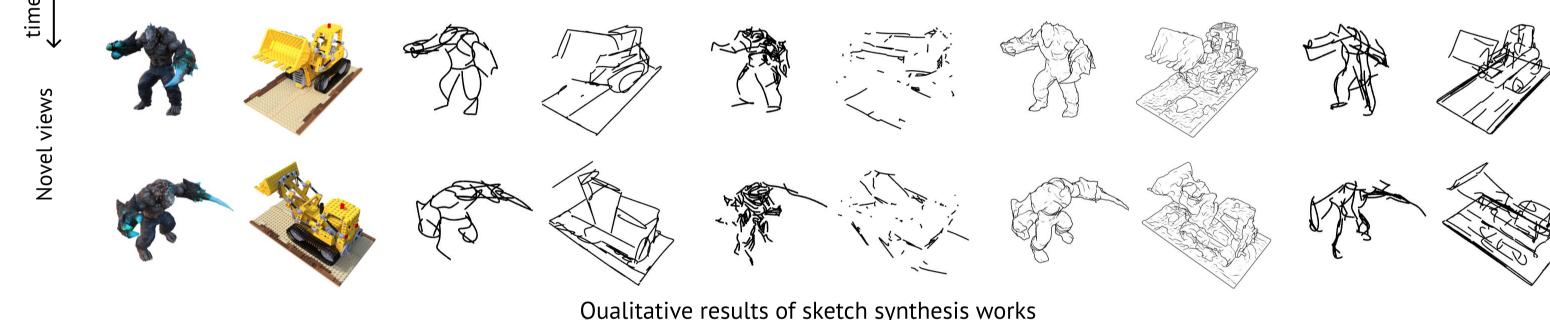
# **Experimental Results**

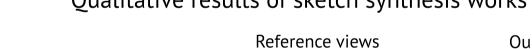
### **Quantitative Results**

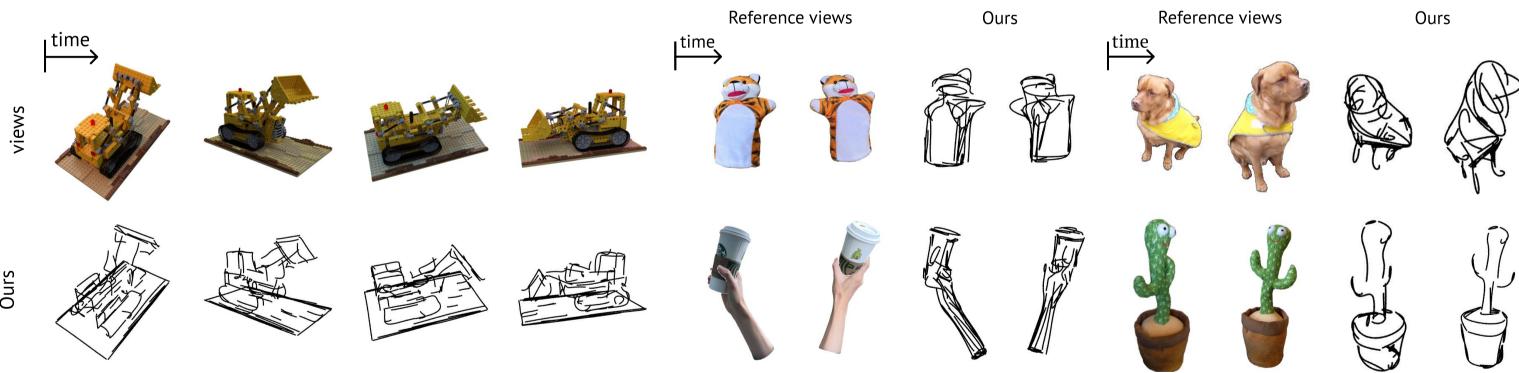
Quantitative results of dynamic 3D sketches.

### Qualitative Results









Results under changing light conditions

#### **Additional Results**

