



南京大學
NANJING UNIVERSITY

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UniAP: Unifying Inter- and Intra-Layer Automatic Parallelism by Mixed Integer Quadratic Programming



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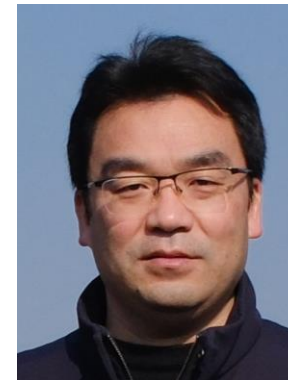
Ke Wu*



Jie Li*



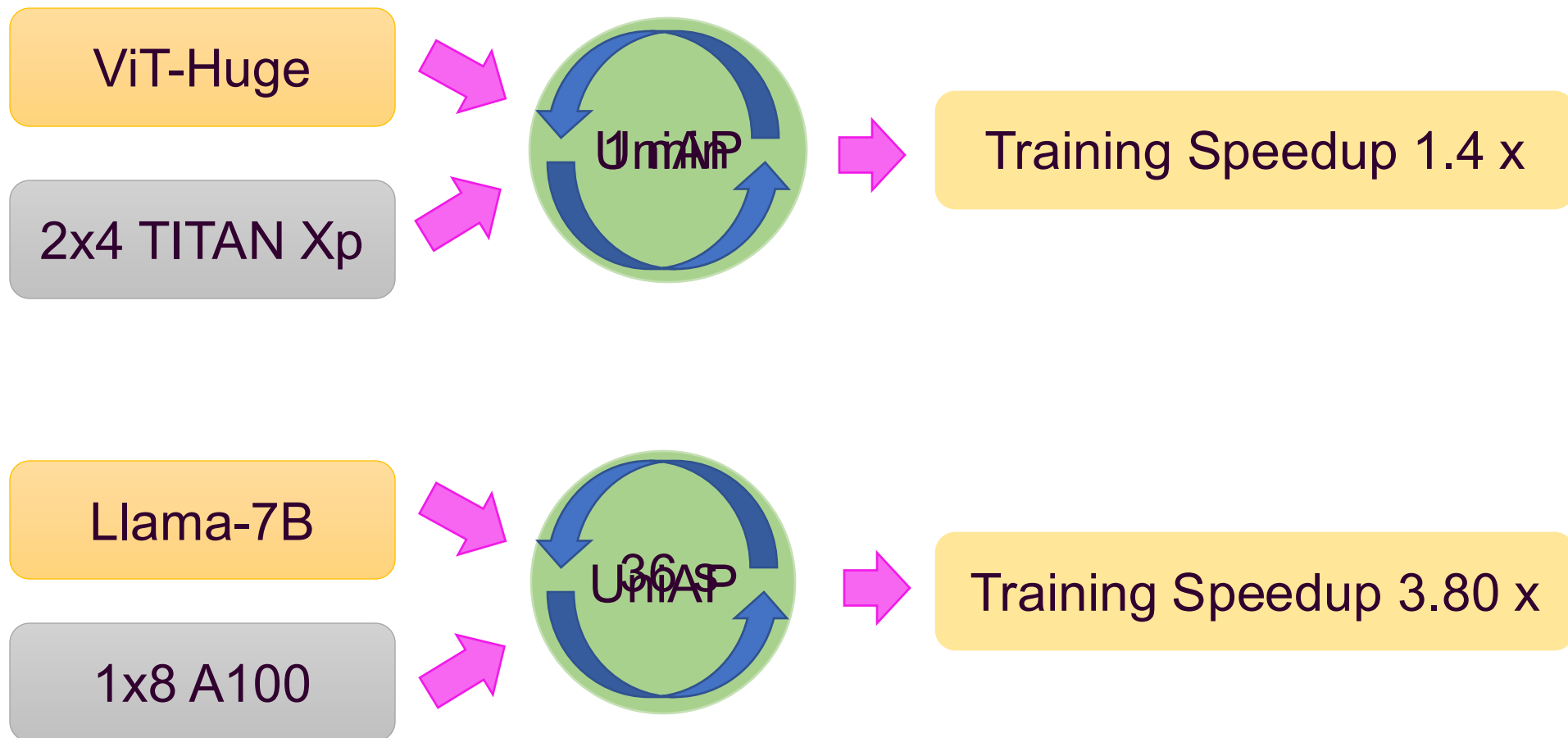
Jun Li



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CVPR 2025 Award Candidate

What is UniAP?





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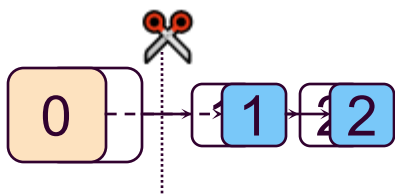
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1.1 Parallel Strategies

□ *Parallel strategies* have been proposed to accelerate distributed learning.

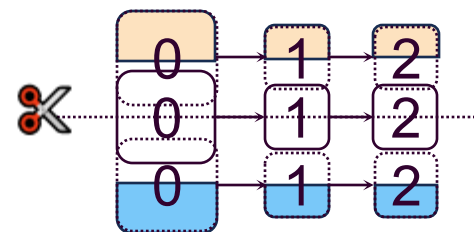


Inter-layer parallelism strategies



Pipeline Parallelism (PP)

...



Intra-layer parallelism strategies



Data Parallelism (DP)

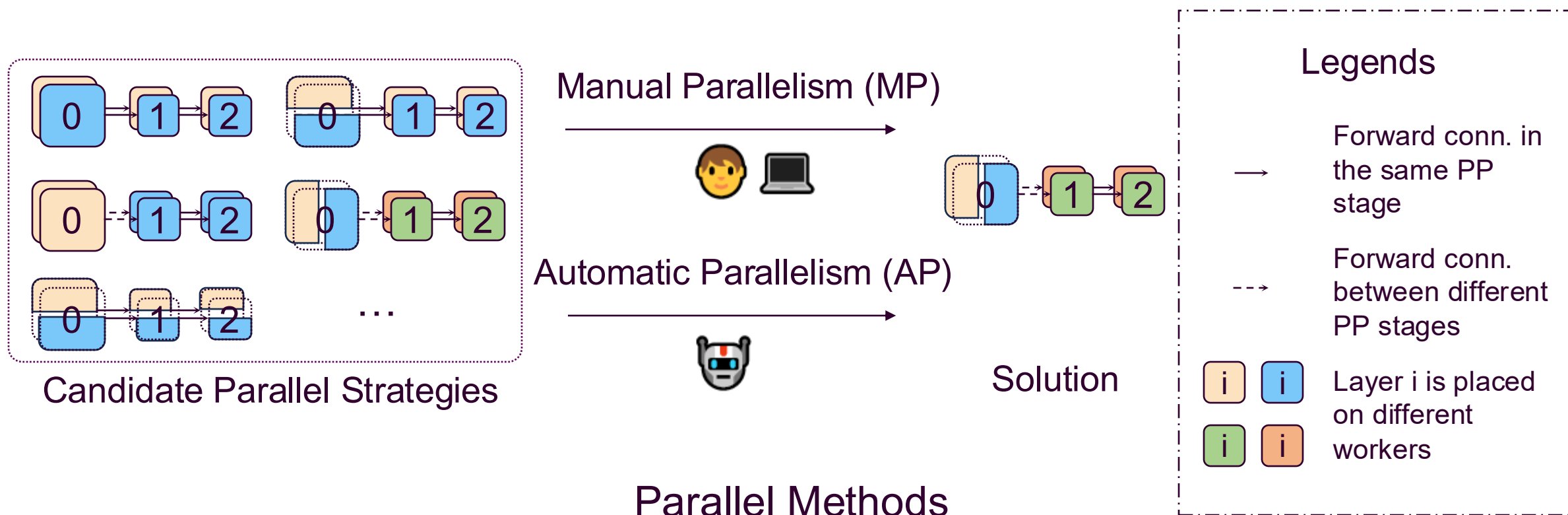
Tensor Parallelism (TP)

Fully Sharded Data Parallelism (FSDP)

...

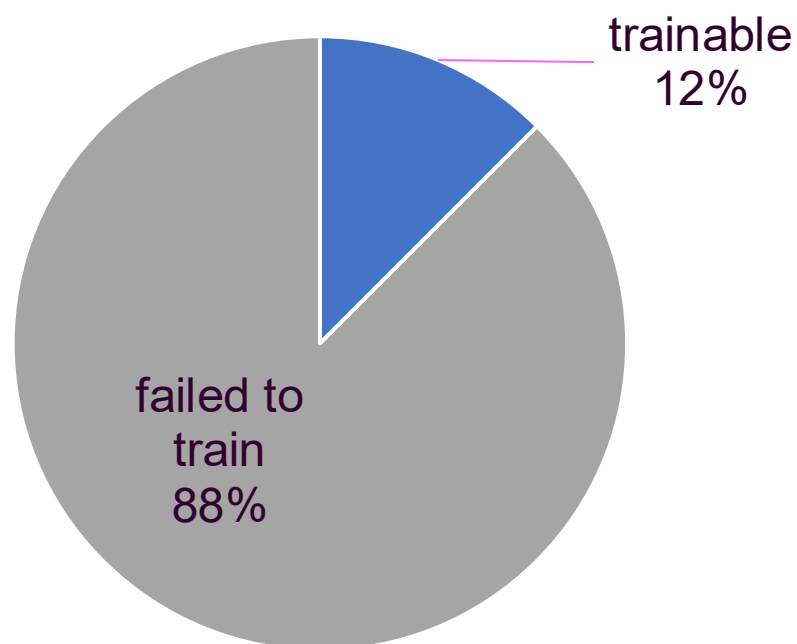
1.2 Parallel Methods

- The *parallel method* in distributed learning typically adopts one *parallel strategy* or a combination of several *parallel strategies*.

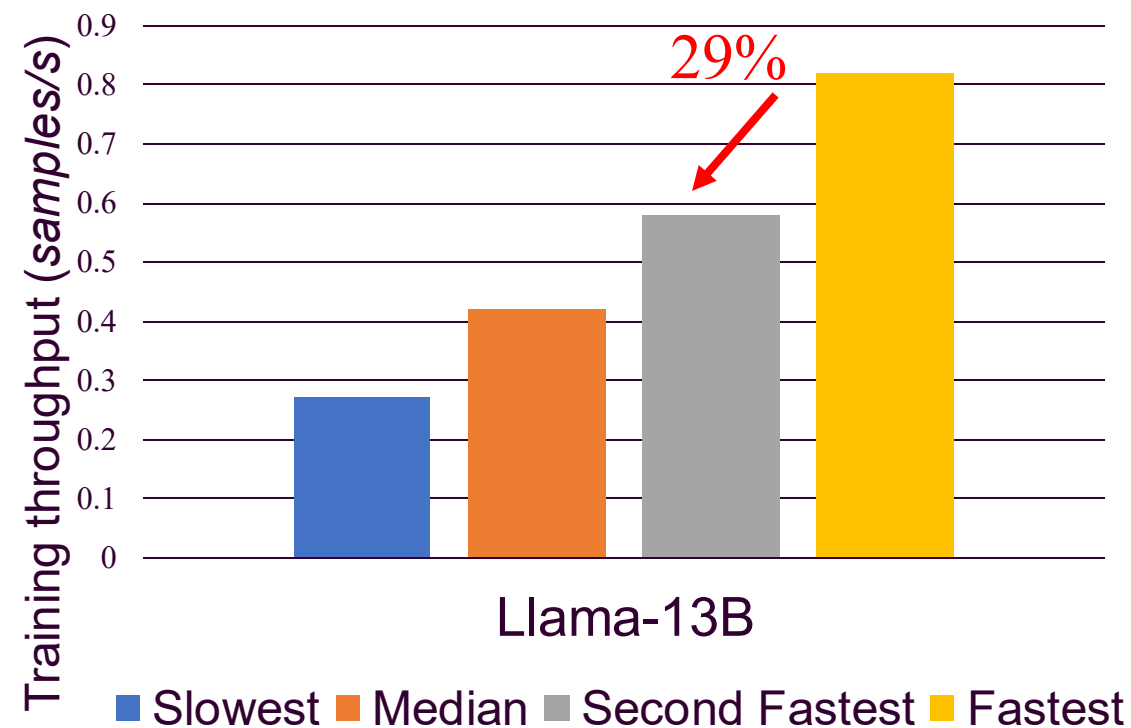


1.3 Why AP, rather than MP?

Percentage of trainable parallel strategies

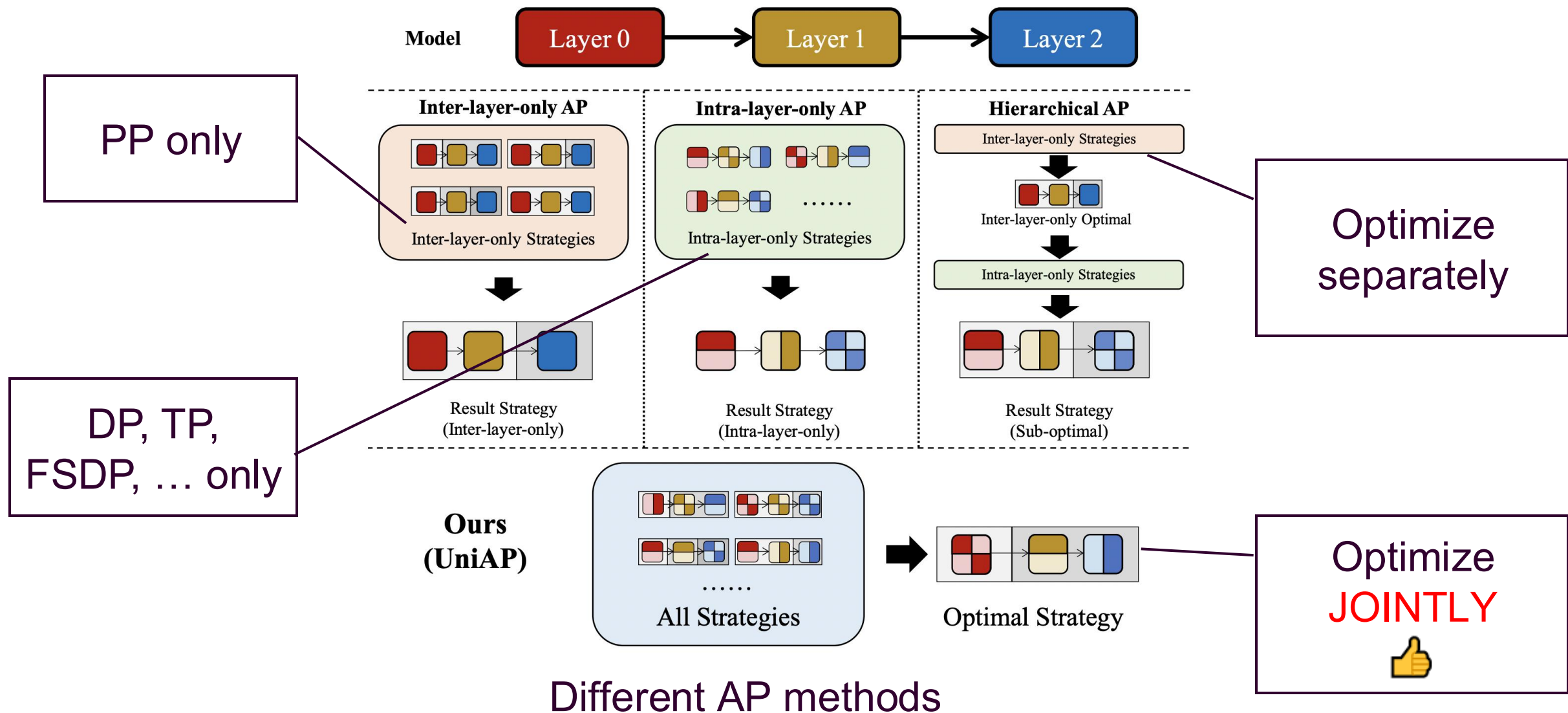


Training throughput on all trainable parallel strategies



Statistics on the Candidate Parallel Strategies for Llama-13B on Megatron

1.4 Why UniAP, rather than other AP methods?





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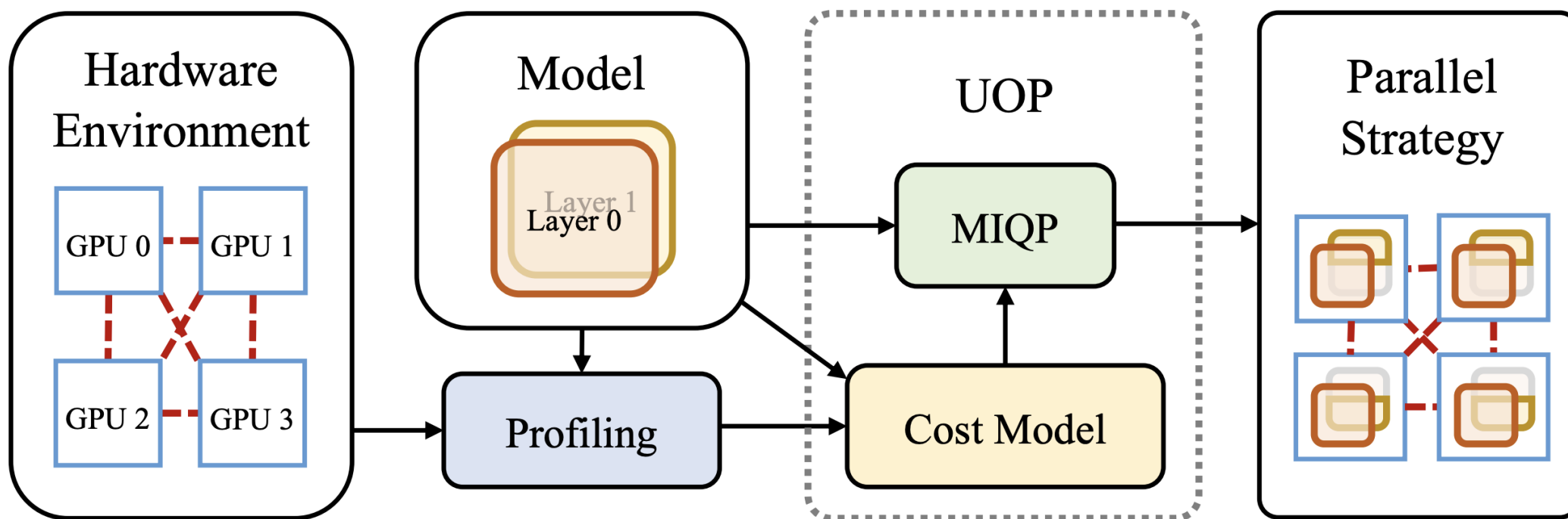
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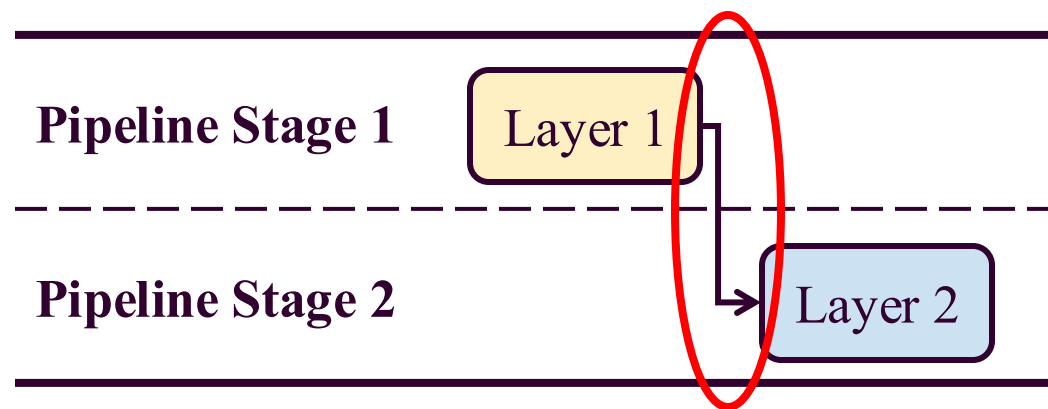
Conclusion



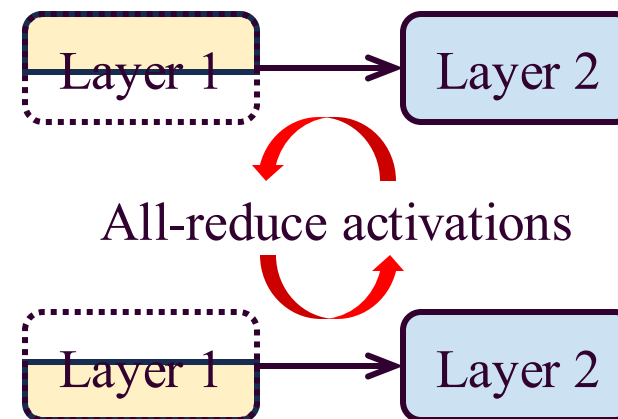
Flowchart of UniAP

□ Environment performance information

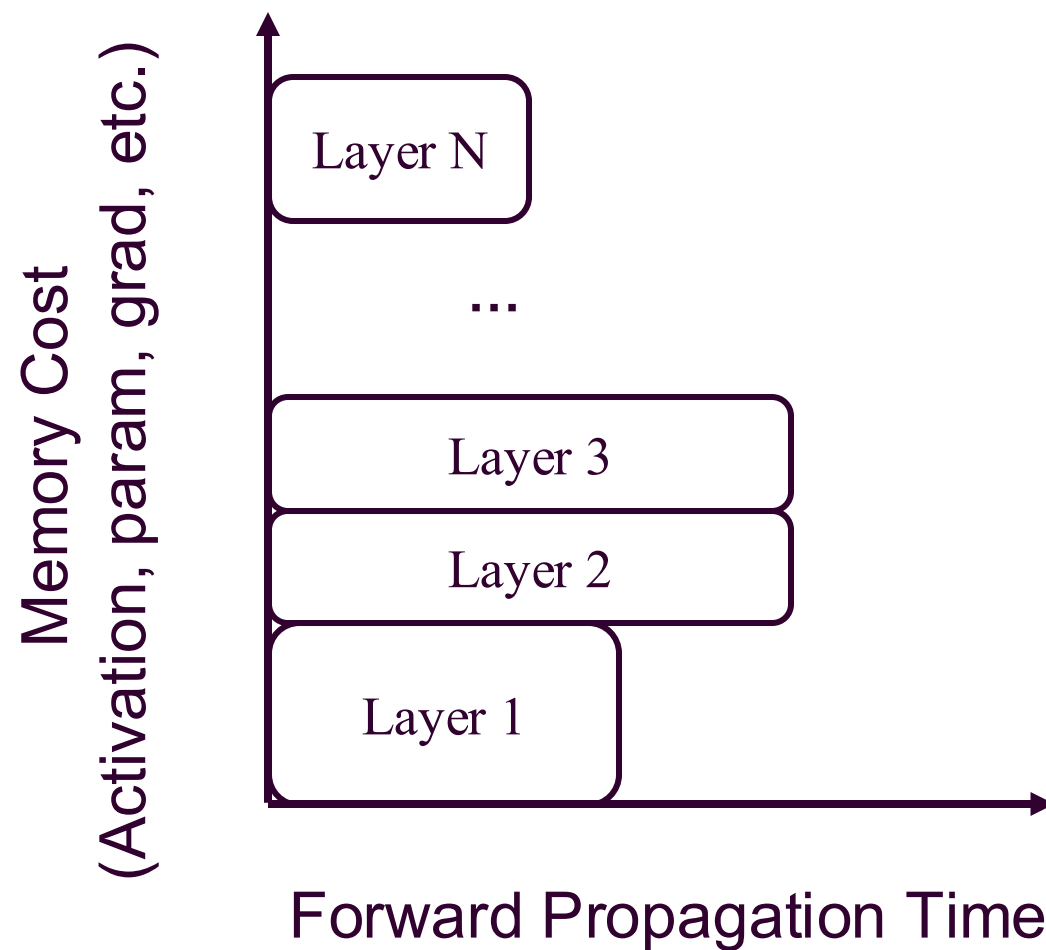
1. P2P efficiency



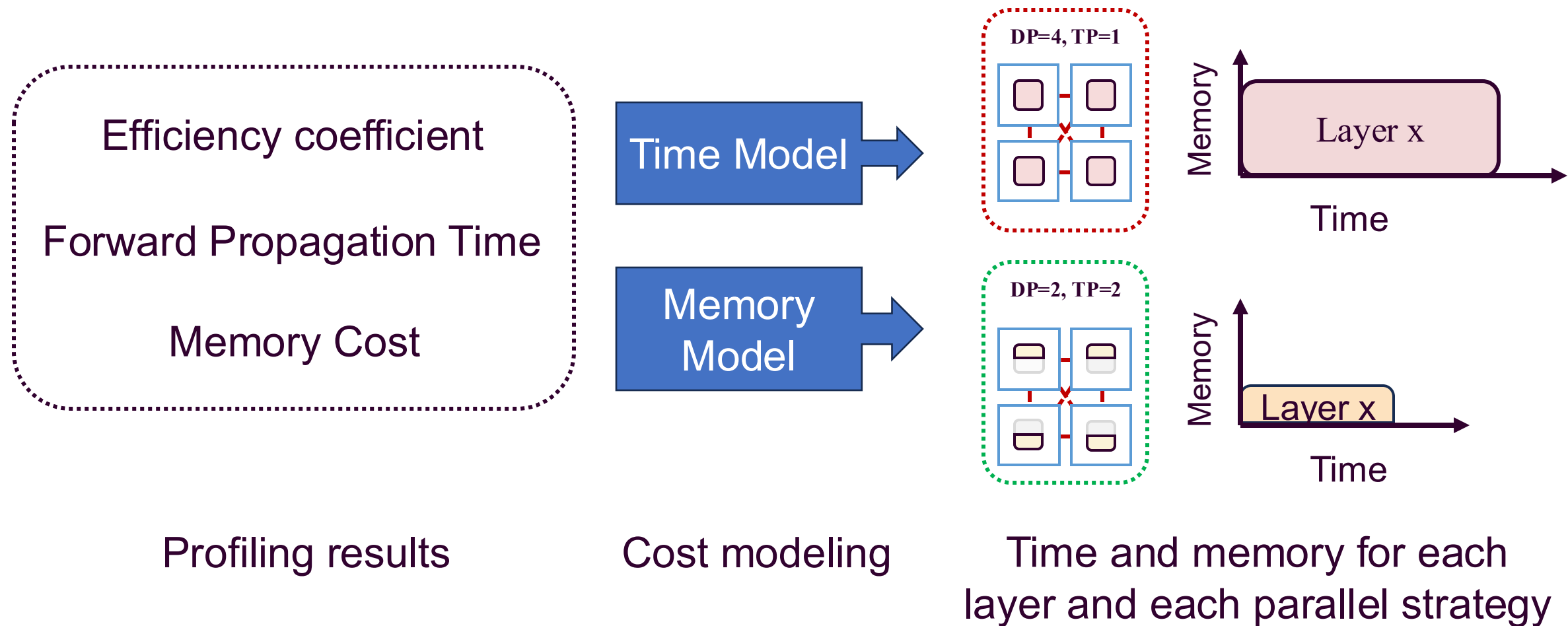
2. All-reduce efficiency



□ Model performance information

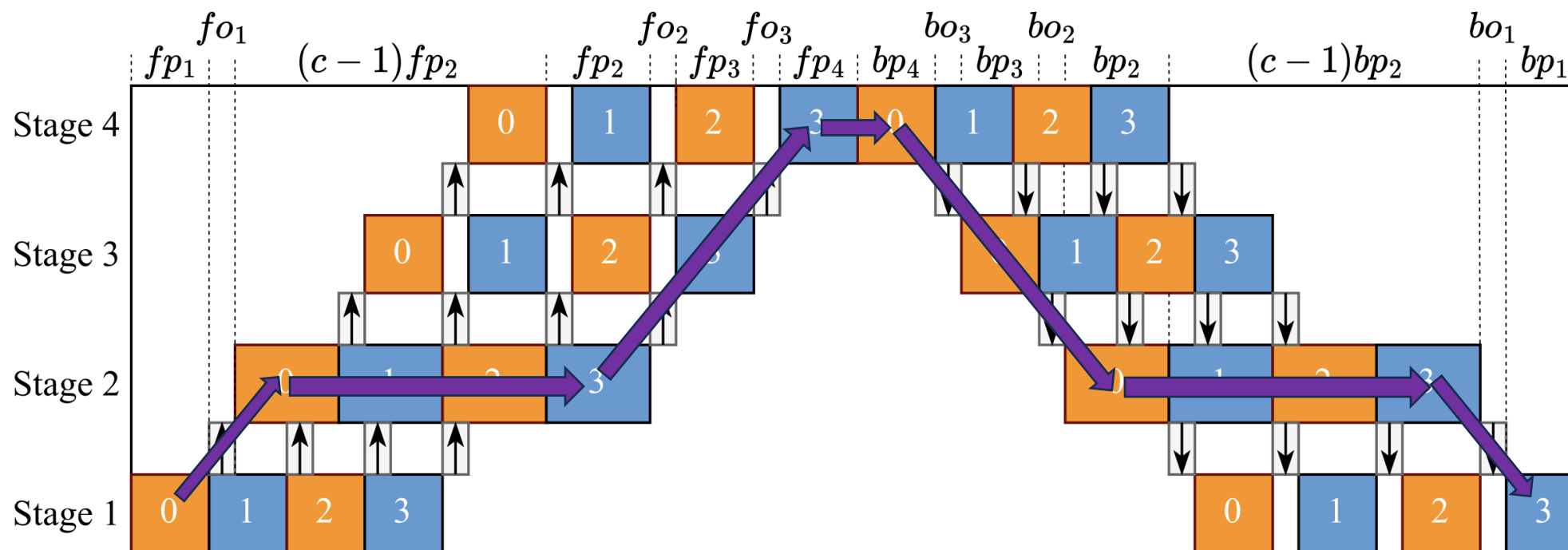


2.3 Cost Model



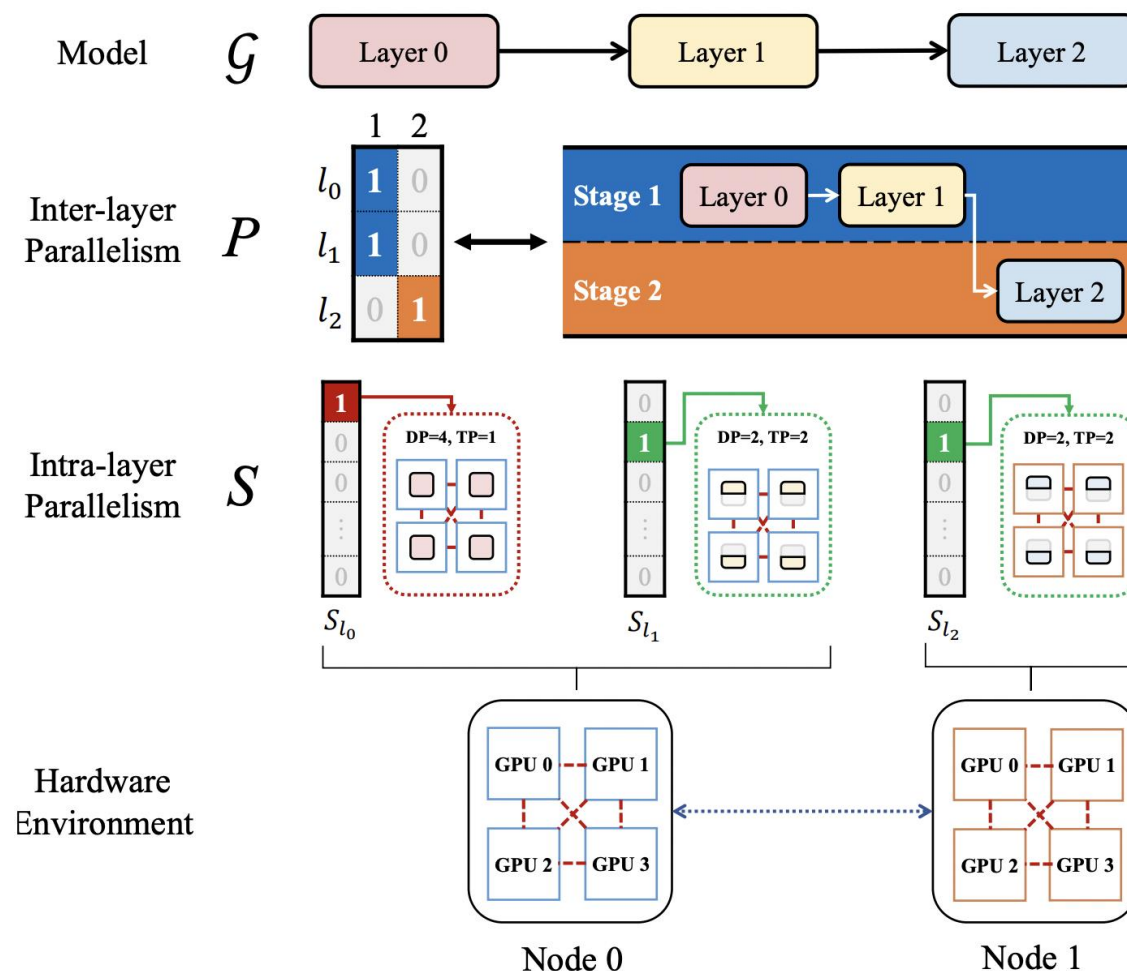
2.4 Mixed Integer Quadratic Programming

□ Objective function: to minimize the *Time-Per-Iteration* (TPI)



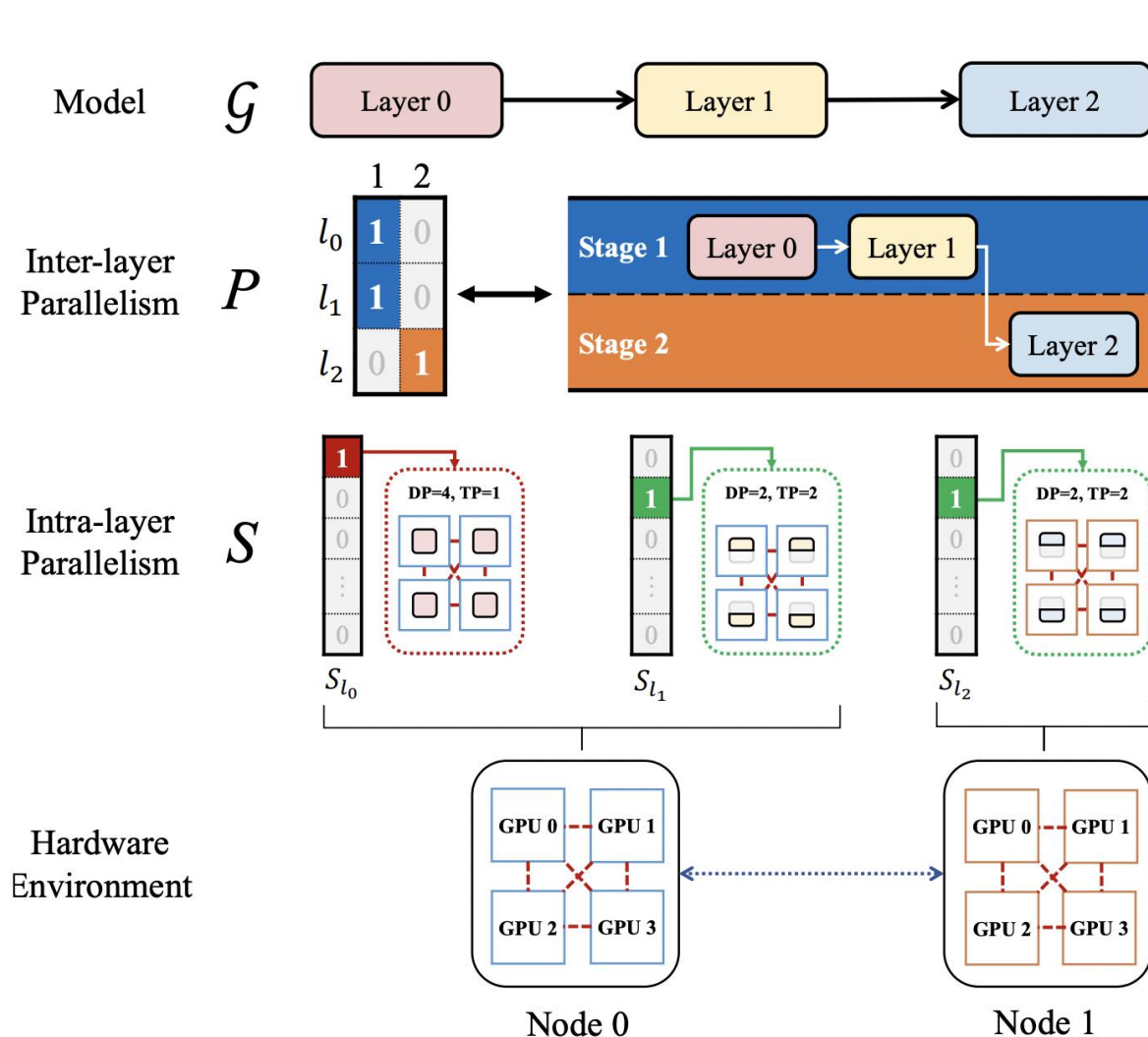
A GPipe-style pipeline

2.4 Mixed Integer Quadratic Programming



A candidate solution

2.4 Mixed Integer Quadratic Programming

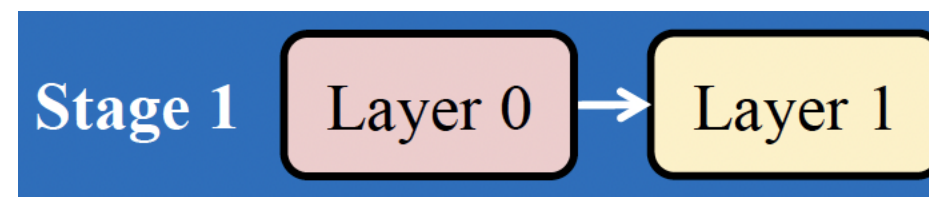


A candidate solution

- Computation-stage constraint

- Time cost of Stage 1 equals to:

- Latency of Layer 0; plus
- Latency of Layer 1; plus
- Latency between Layer 0 and 1.

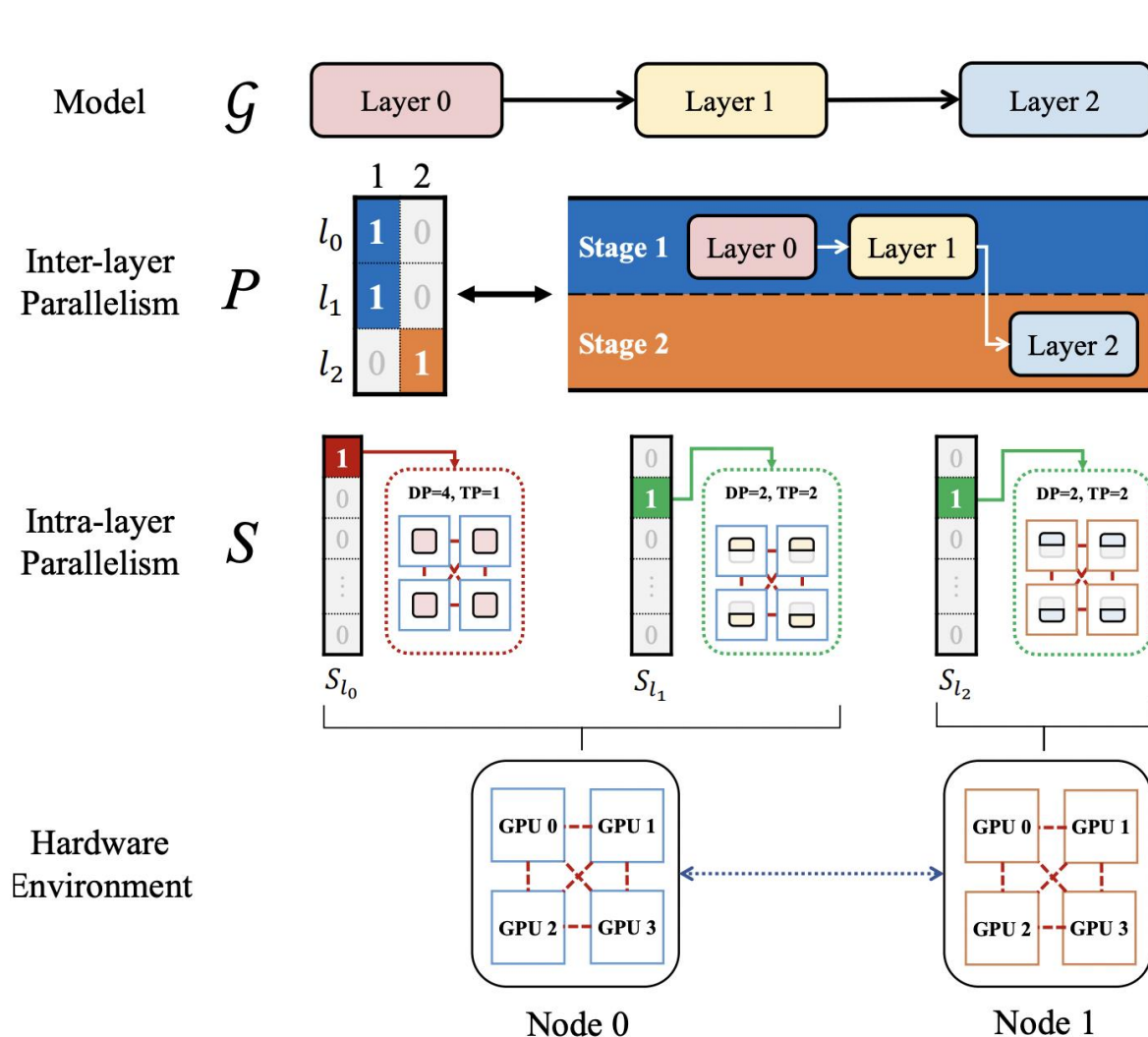


- Time cost of Stage 2 equals to:

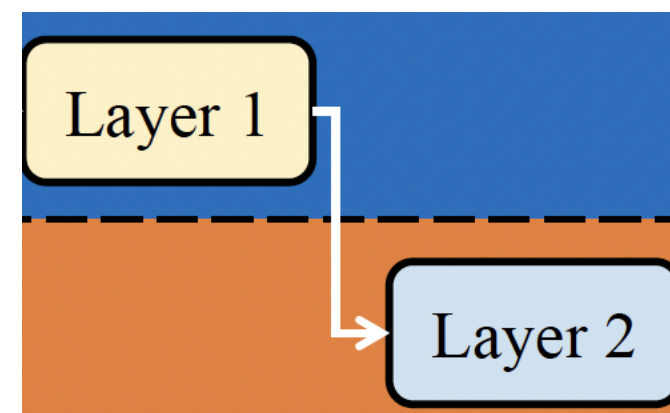
- Latency of Layer 2.



2.4 Mixed Integer Quadratic Programming

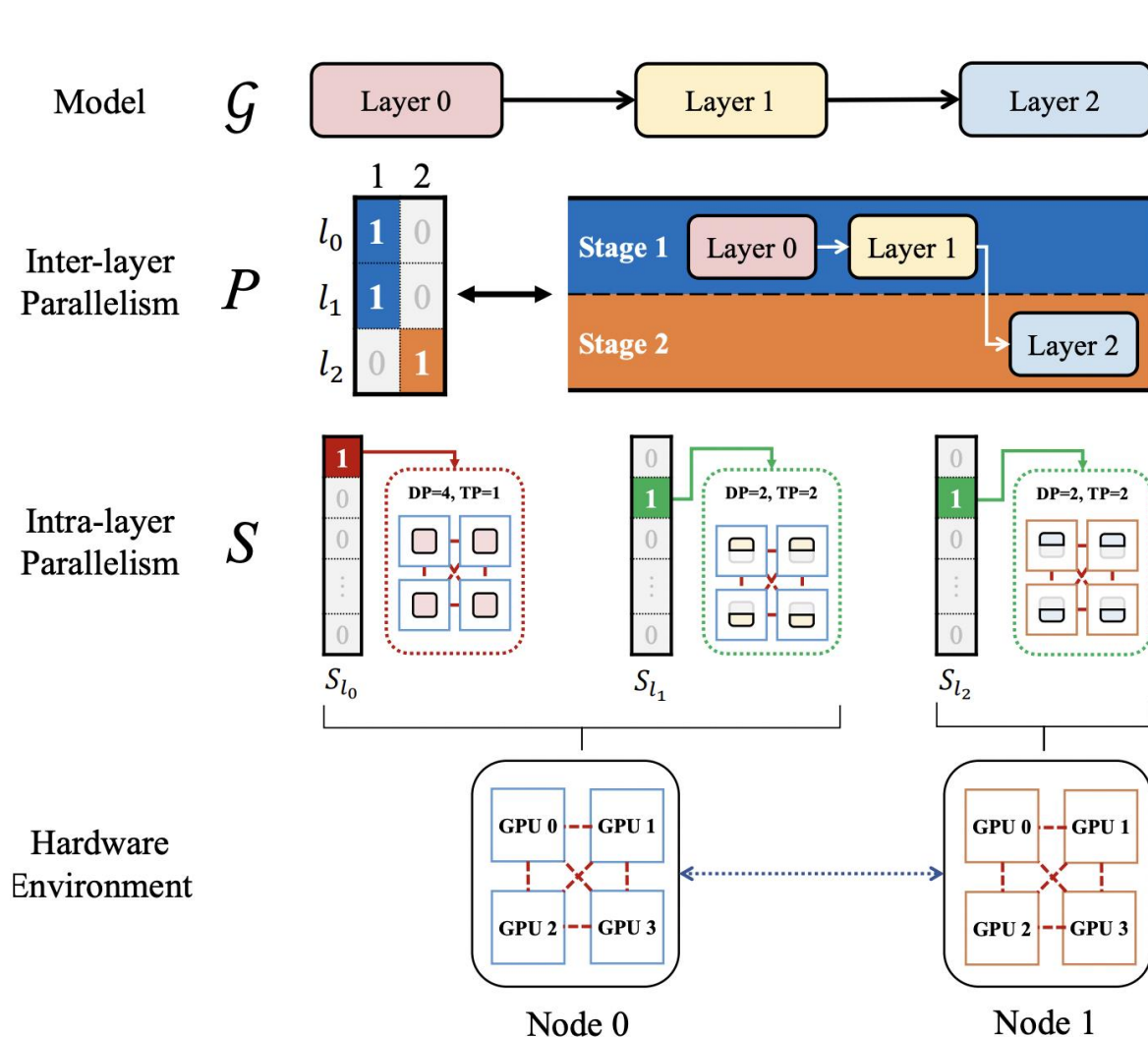


- Communication-stage constraint
- Time cost between Stage 1 and 2 equals to:
 - Latency between Layer 1 and 2.

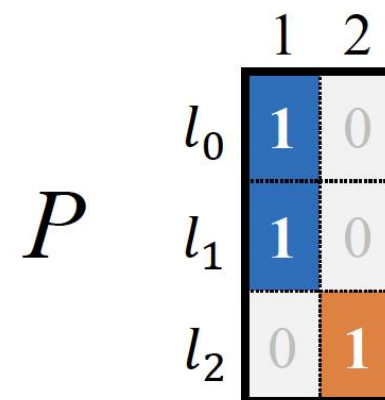


A candidate solution

2.4 Mixed Integer Quadratic Programming

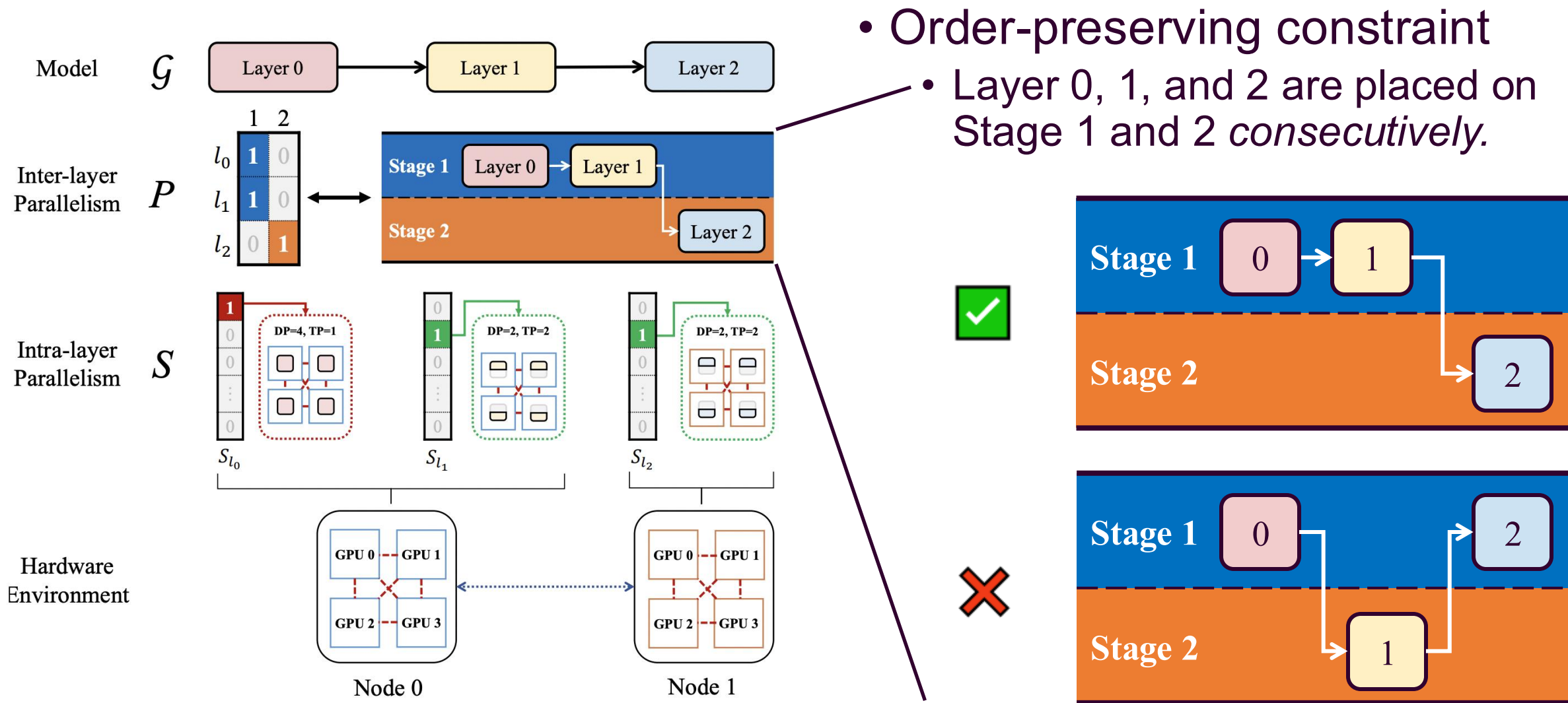


- Layer-placement constraint
- All layers should be placed on exactly one pipeline stage.
- At least one layer should be placed on each pipeline stage.



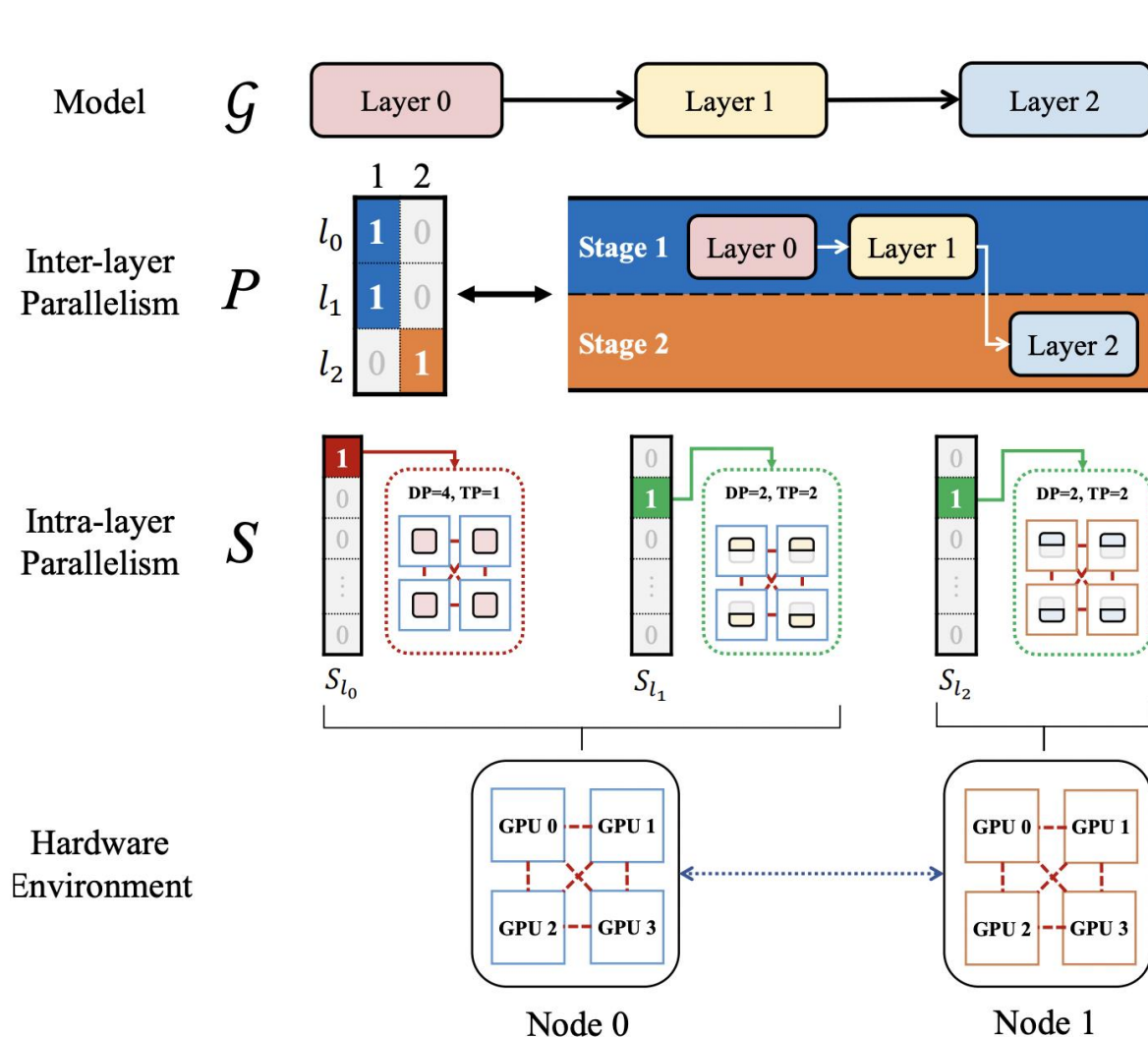
A candidate solution

2.4 Mixed Integer Quadratic Programming

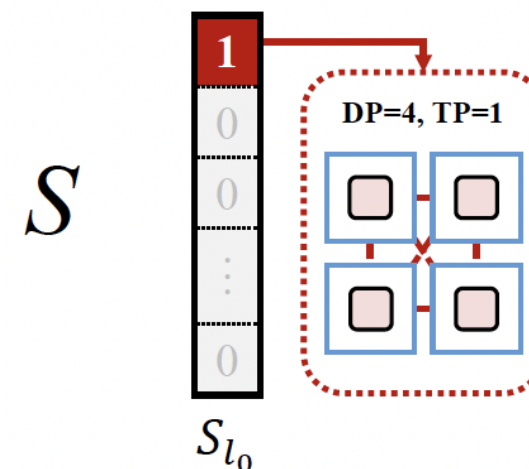


A candidate solution

2.4 Mixed Integer Quadratic Programming

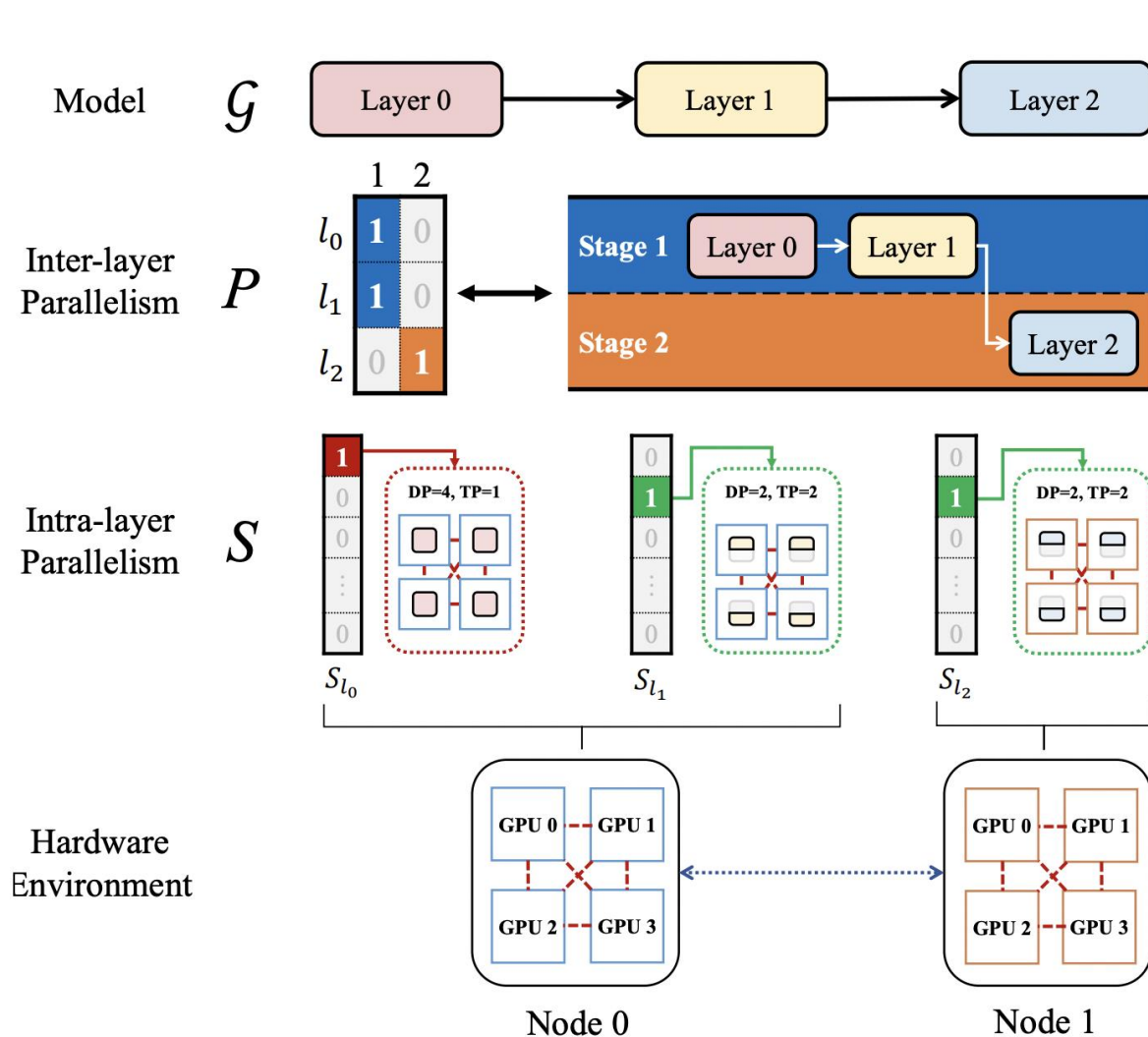


- Strategy-selection constraint
 - Each layer must choose a strategy.
 - Each layer can only choose one strategy.



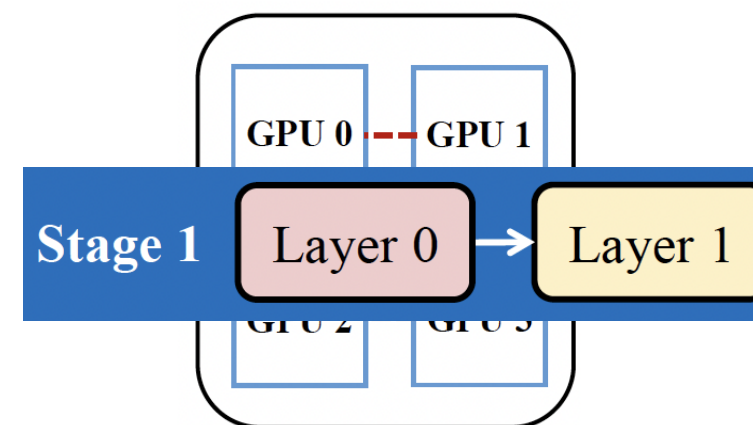
A candidate solution

2.4 Mixed Integer Quadratic Programming

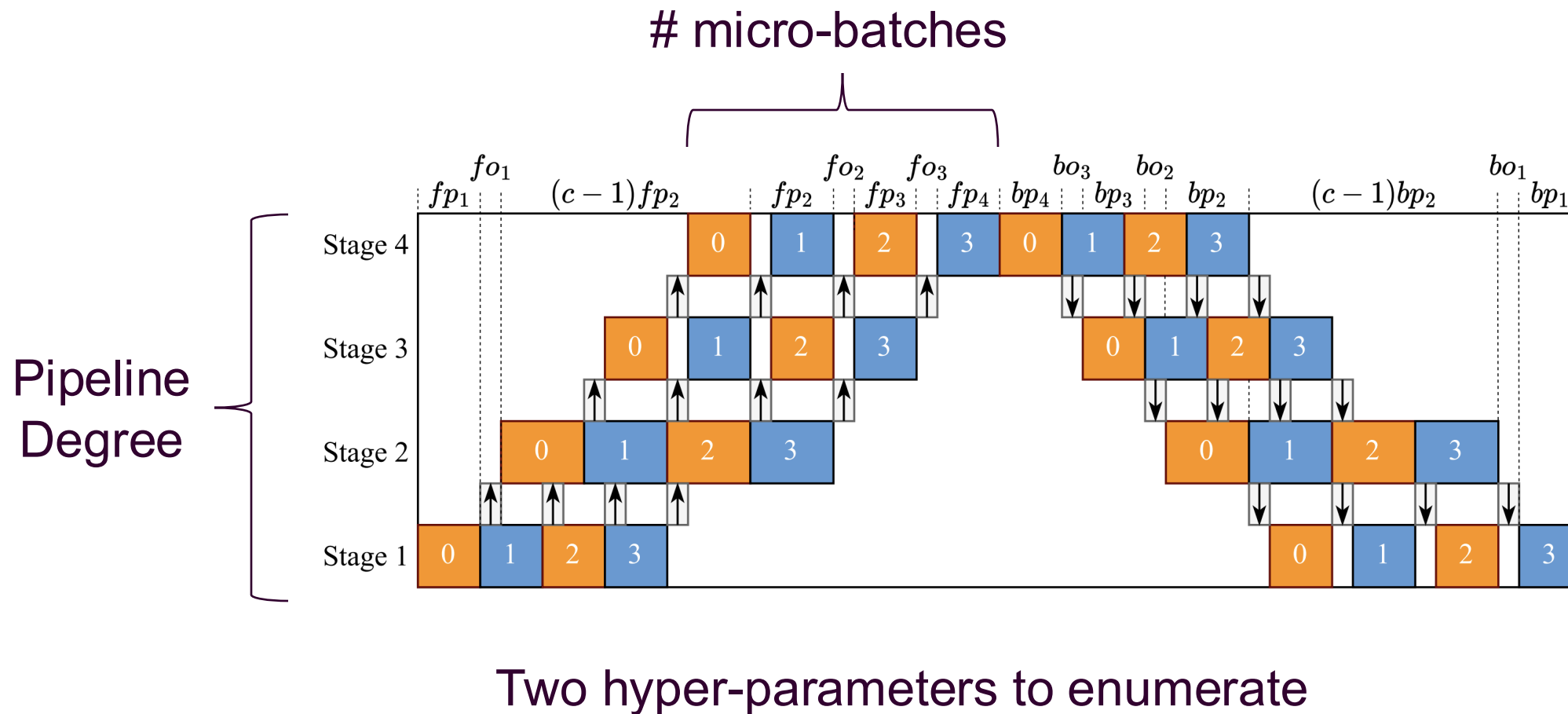


A candidate solution

- Memory constraint
- Stage 1 with Layer 0 and Layer 1 can be placed on Node 0.
- Layers on Stage 2 can be placed on Node 1.



2.5 Unified Optimization Process





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3.1 Results on NVIDIA GPU

Env.	Model	Training throughput (samples/s)			Minimum speedup	Maximum speedup
		Galvatron	Alpa	UniAP		
ENV A	BERT-Huge	33.46 ± 0.28	31.56 ± 0.04	33.46 ± 0.28	1.00	1.06
	T5-Large	23.29 ± 0.04	MEM× ²⁾	23.29 ± 0.04	1.00	1.00
	ViT-Huge	109.51 ± 0.07	97.66 ± 1.42	109.51 ± 0.07	1.00	1.12
	Swin-Huge	CUDA× ³⁾	N/A ⁴⁾	67.96 ± 0.12	N/A ⁴⁾	N/A ⁴⁾
ENV B-8	BERT-Huge	6.27 ± 0.17	8.95 ± 0.06	10.77 ± 0.13	1.20	1.71
	T5-Large ¹⁾	8.06 ± 0.06	MEM× ²⁾	7.98 ± 0.05	0.99	0.99
	ViT-Huge	32.20 ± 0.17	38.74 ± 0.20	45.58 ± 0.54	1.18	1.41
	Swin-Huge	13.90 ± 0.17	N/A ⁴⁾	19.08 ± 0.10	1.37	1.37
ENV C	Llama-7B	1.22 ± 0.01	N/A ⁴⁾	4.63 ± 0.007	3.80	3.80

Env.	Model	Strategy optimization time (min.)			Minimum speedup	Maximum speedup
		Galvatron	Alpa	UniAP		
ENV A	BERT-Huge	6.44 ± 0.588	> 40	0.37 ± 0.002	17.29	> 107.41
	T5-Large	12.41 ± 0.122	MEM× ²⁾	0.89 ± 0.007	13.98	13.98
	ViT-Huge	6.29 ± 0.464	> 40	0.57 ± 0.009	10.95	> 69.60
	Swin-Huge	11.88 ± 0.666	N/A ⁴⁾	2.16 ± 0.004	5.49	5.49
ENV B-8	BERT-Huge	2.04 ± 0.010	> 40	1.51 ± 0.005	1.34	> 26.32
	T5-Large ¹⁾	2.64 ± 0.110	MEM× ²⁾	0.91 ± 0.005	2.90	2.90
	ViT-Huge	2.37 ± 0.180	> 40	1.11 ± 0.011	2.14	> 36.01
	Swin-Huge	4.29 ± 0.320	N/A ⁴⁾	2.29 ± 0.010	1.87	1.87
ENV C	Llama-7B	6.84 ± 0.055	N/A ⁴⁾	0.58 ± 0.006	11.83	11.83

Throughput
max 3.8x ↑

Strategy opt. time
max 107x ↓

Training throughput and strategy optimization time on NVIDIA GPUs.

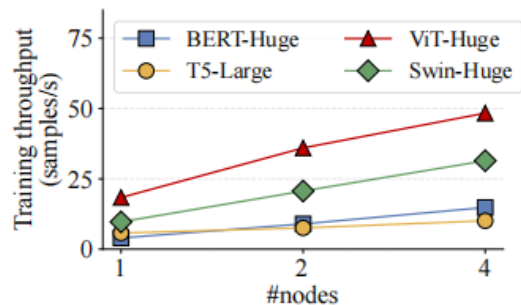
3.2 Results on Hygon DCU

UniAP can find fastest parallel strategy while spending less time

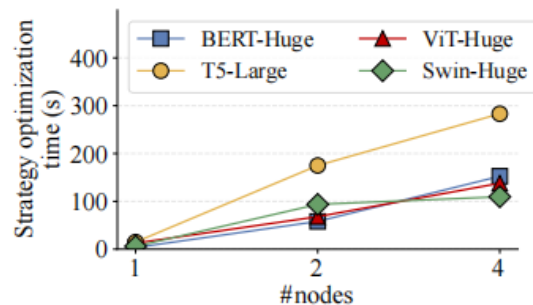
Model	Training throughput (samples/s)			Strategy optimization time (min.)		
	Megatron	DeepSpeed	UniAP	Megatron	DeepSpeed	UniAP
Llama-7B	2.01 ± 0.005	SOL $\times^1$	2.01 ± 0.005	> 8.0 hours	SOL $\times^1$	3.07 ± 0.121
Llama-13B	0.82 ± 0.001	SOL $\times^1$	0.82 ± 0.001	> 2.5 hours	SOL $\times^1$	1.95 ± 0.076

Training throughput and strategy optimization time on 32 DCUs

3.3 Other experiments



(a) Training throughput.

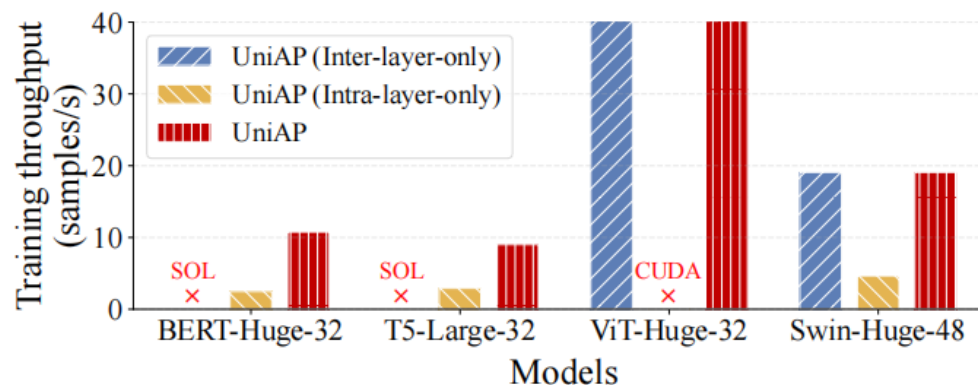


(b) Strategy optimization time.

Number of DCUs	Training throughput (samples/s)	Strategy optimization time(min.)
16	0.1726 ± 0.0005	0.75 ± 0.0100
32	0.3393 ± 0.0004	1.64 ± 0.0321
64	0.6656 ± 0.0023	1.55 ± 0.0058

Scalability on 16 NVIDIA GPUs

Scalability on 64 Hygon DCUs



Ablation study



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- We propose a novel AP method called UniAP to unify inter- and intra-layer AP by MIQP.
- To the best of our knowledge, UniAP is the **FIRST** parallel method that can optimize the two categories of parallel strategies jointly rather than separately to find an optimal solution.
- UniAP outperforms state-of-the-art methods to achieve the best training throughput.

□ Please find our personal website at

- Hao Lin: <https://haolin-nju.github.io/>
- Ke Wu: <https://bigai-nju.github.io/members/Ke Wu>
- Jie Li: <https://dibaotian-xing.github.io/lijie/>

THANKS



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